

# A generalist model for intracortical motor brain-computer interfaces

Preprint



## The Team

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Leila Wehbe  
Robert A. Gaunt

DNNs excel at  
**single tasks.**

DNNs features  
**transfer across settings.**

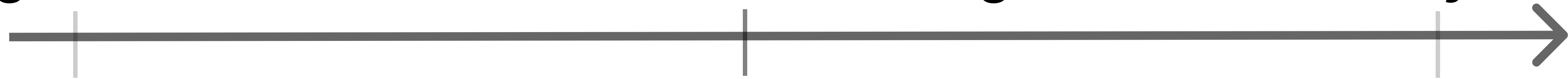
DNNs can be scaled  
to **use everywhere.**



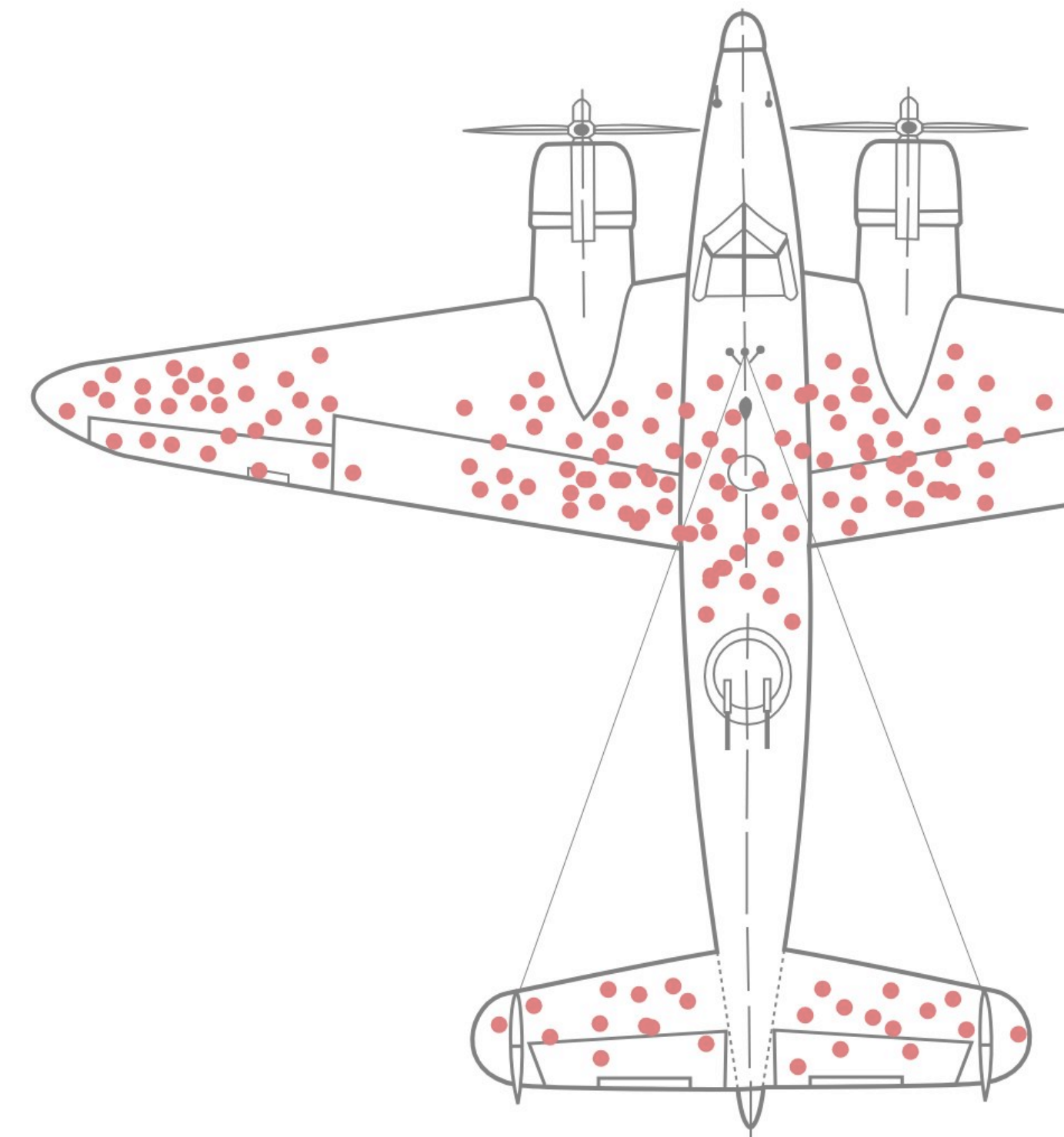
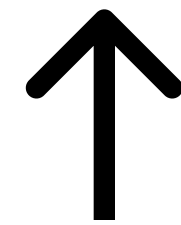
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**We're here (?) Now what?**



DNNs excel at  
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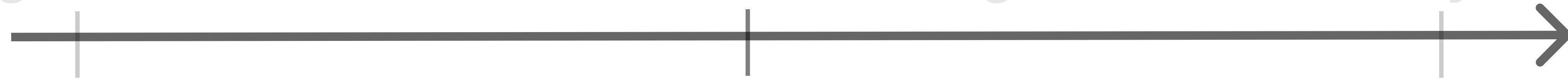


**We're here (?) Now what?**

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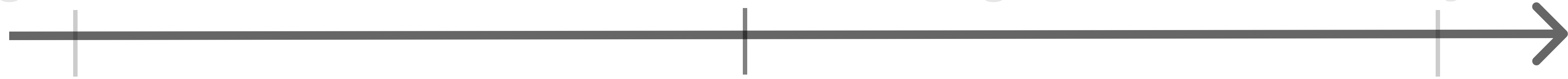
**In machine learning,  
evaluations drive our understanding of progress.**

**(Guess and check will never end)**

DNNs excel at  
**single tasks.**

DNNs features  
**transfer across settings.**

DNNs can be scaled  
to **use everywhere.**



**We're here (?) Now what?**

**In machine learning,  
evaluations drive our understanding of progress.**

**How should we prioritize evaluations?**

**1. Evaluating for pragmatics**

**2. Evaluating for generalization**

**In machine learning,  
evaluations drive our understanding of progress.**

**How should we prioritize evaluations?**

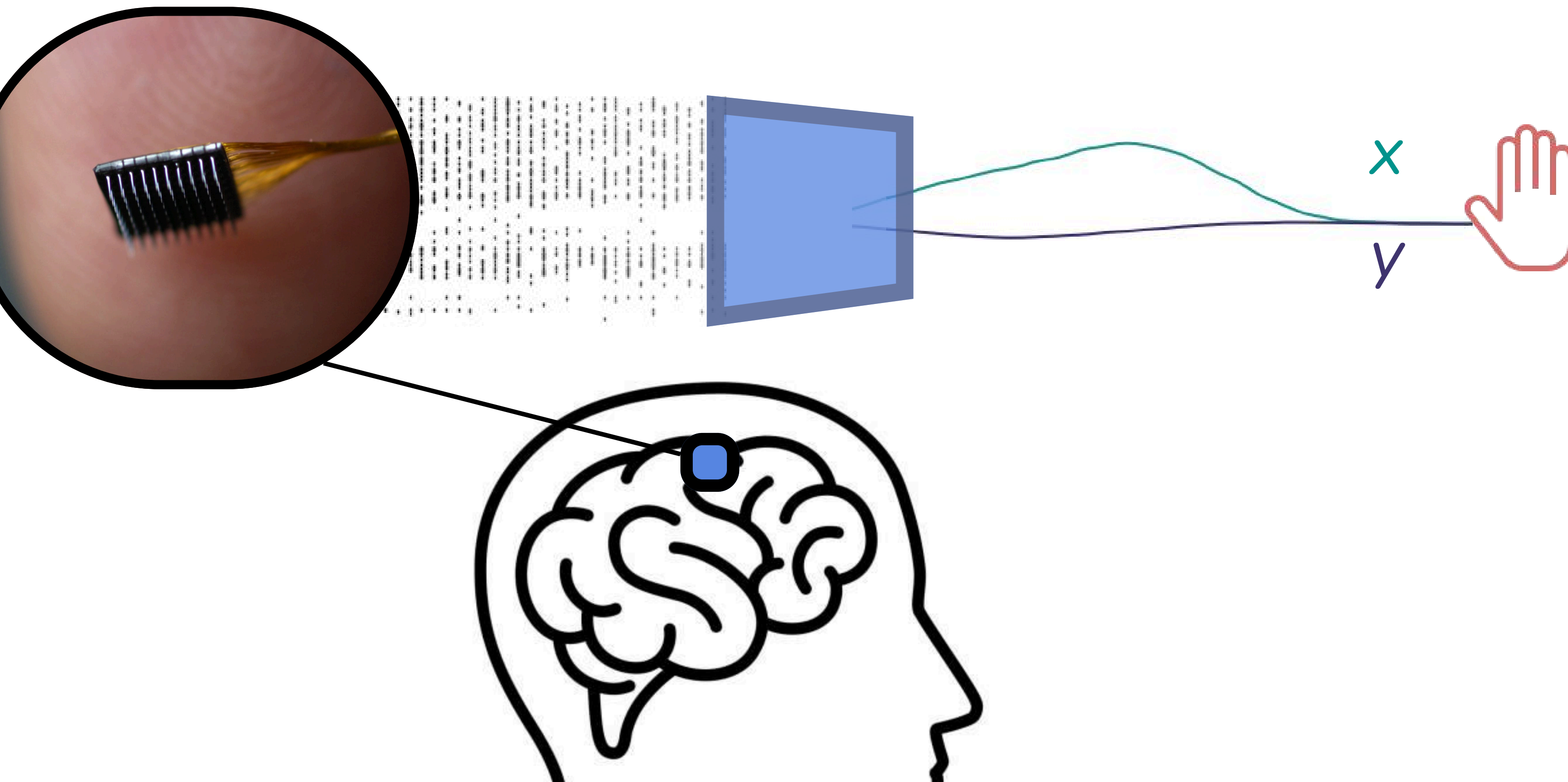
What is the **practical** benefit of **unified** pretraining?

# 1. Evaluating for pragmatics

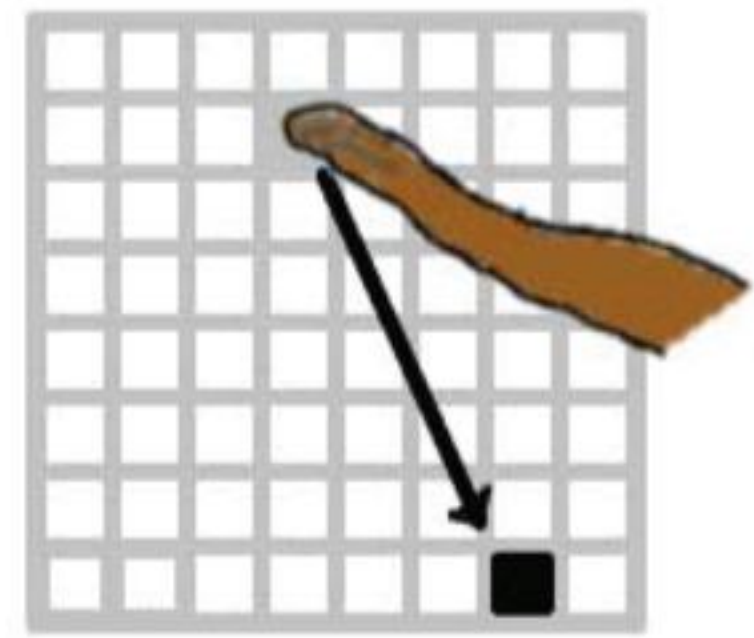


What is the **practical** benefit of **unified** pretraining?

# 1. Evaluating for pragmatics

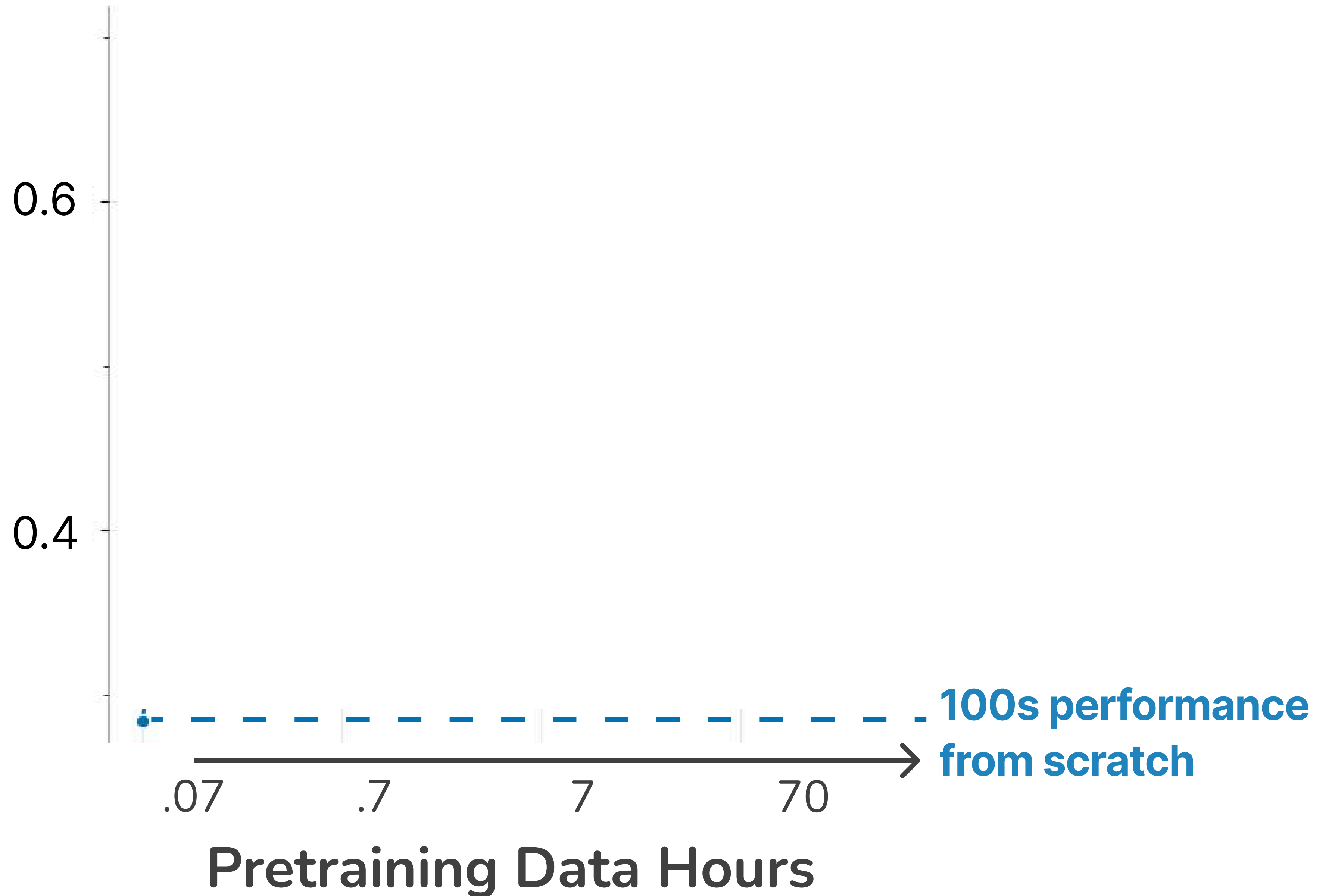


What is the **practical** benefit of **unified** pretraining?

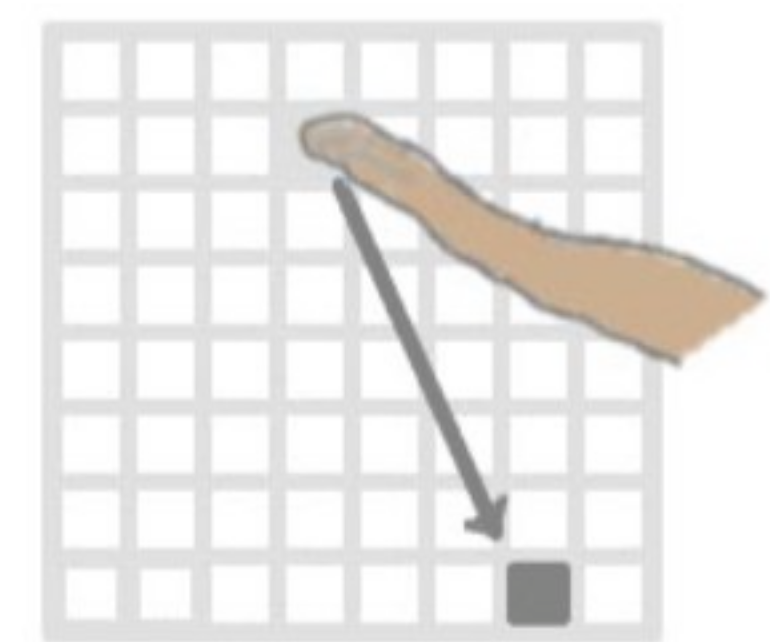


**100 seconds for  
fine-tuning**

Velocity  $R^2$

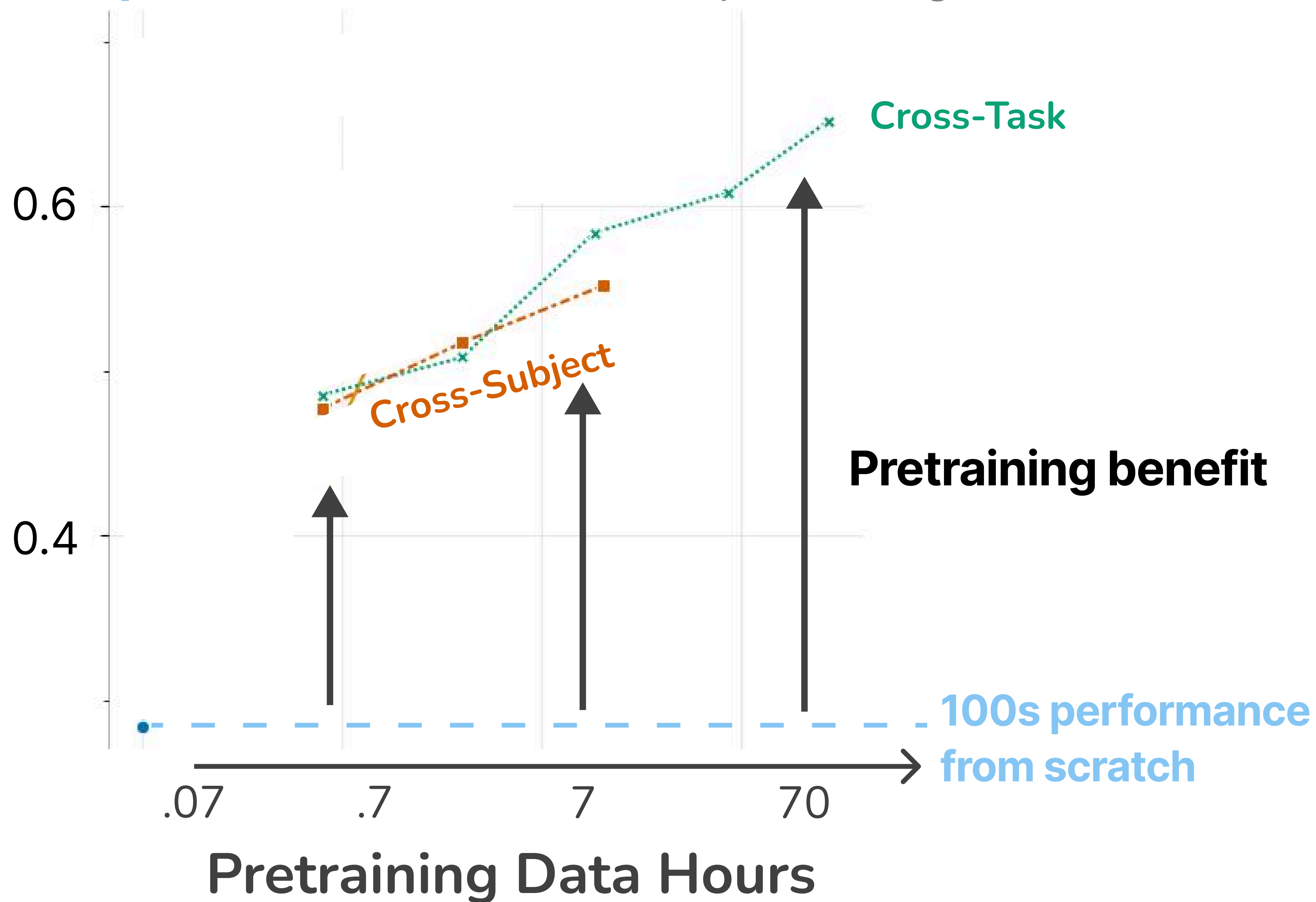


What is the **practical** benefit of **unified** pretraining?



100 seconds for  
fine-tuning

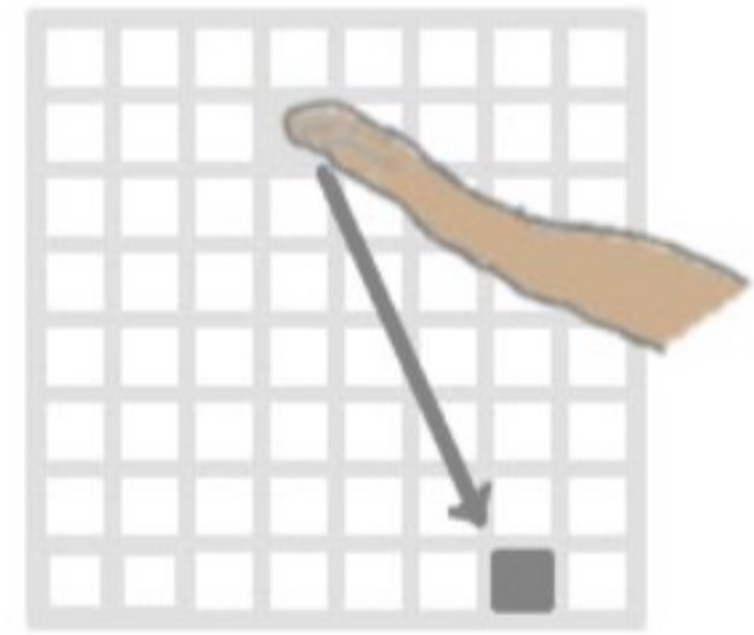
Velocity  $R^2$



100s performance  
from scratch

What is the **practical** benefit of **unified** pretraining?

**Cross session (same subject)  
is best**



100 seconds for  
fine-tuning

Velocity  $R^2$

0.6

0.4

.07

.7

7

70

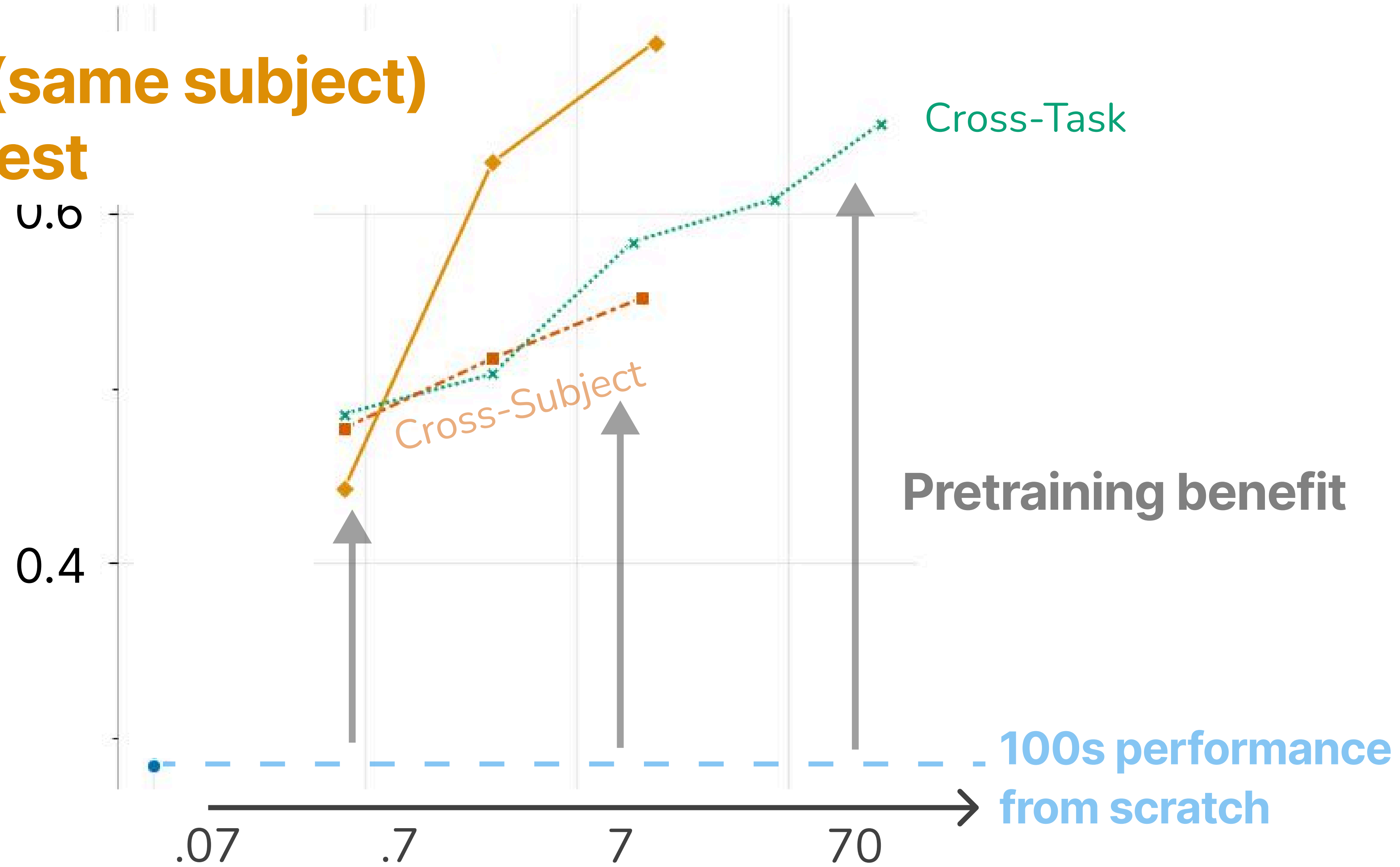
Pretraining Data Hours

Cross-Subject

Cross-Task

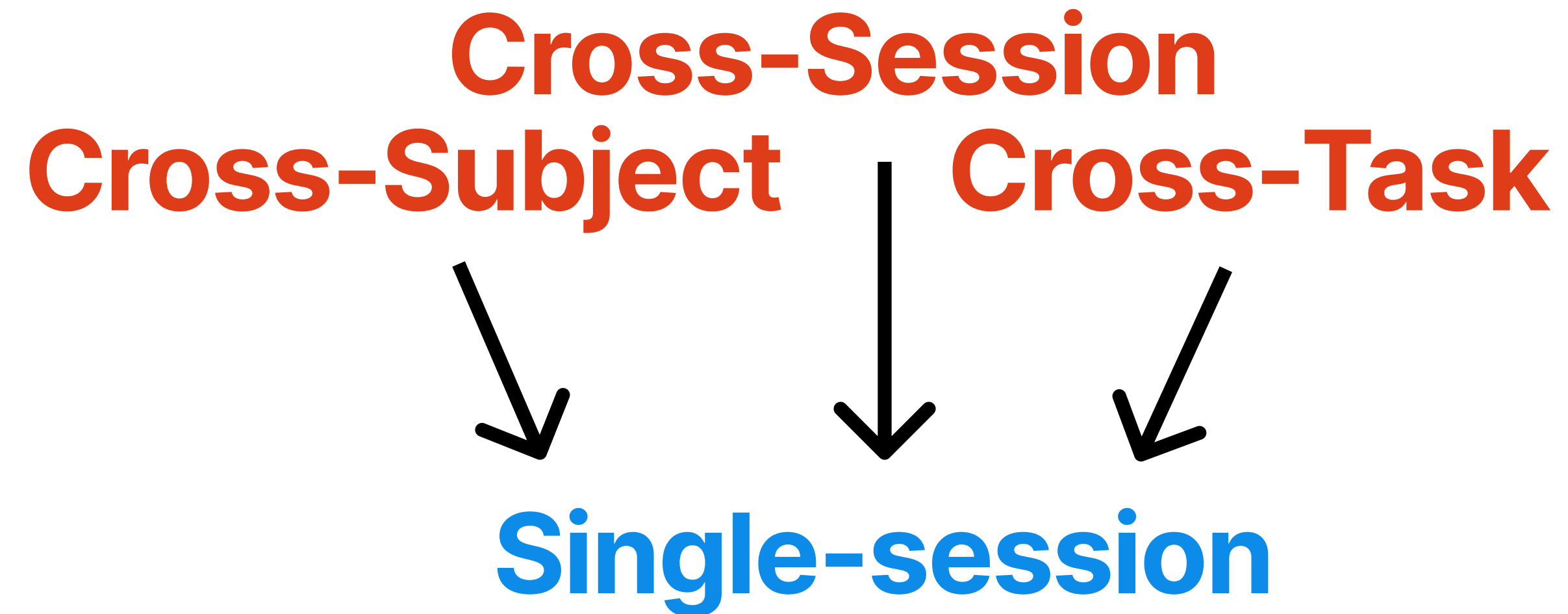
Pretraining benefit

100s performance  
from scratch



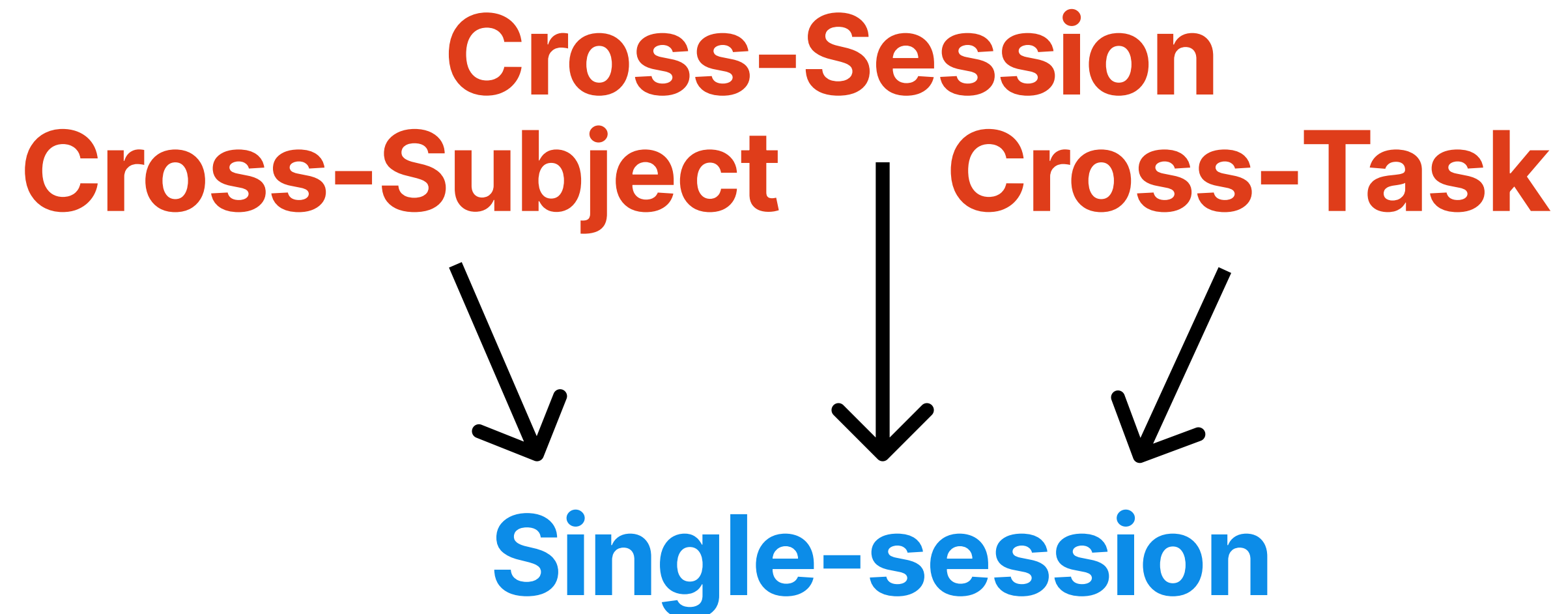
What is the **practical** benefit of **unified** pretraining?

## THE NORM



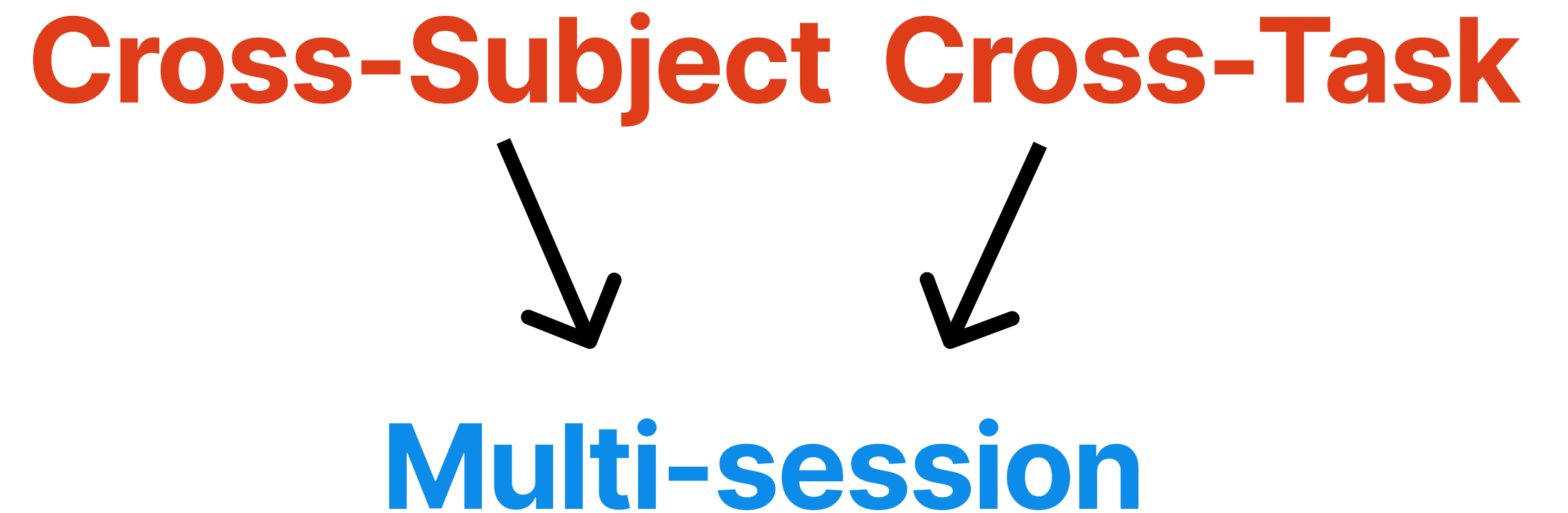
What is the **practical** benefit of **unified** pretraining?

## THE NORM



## PRAGMATIC EVAL

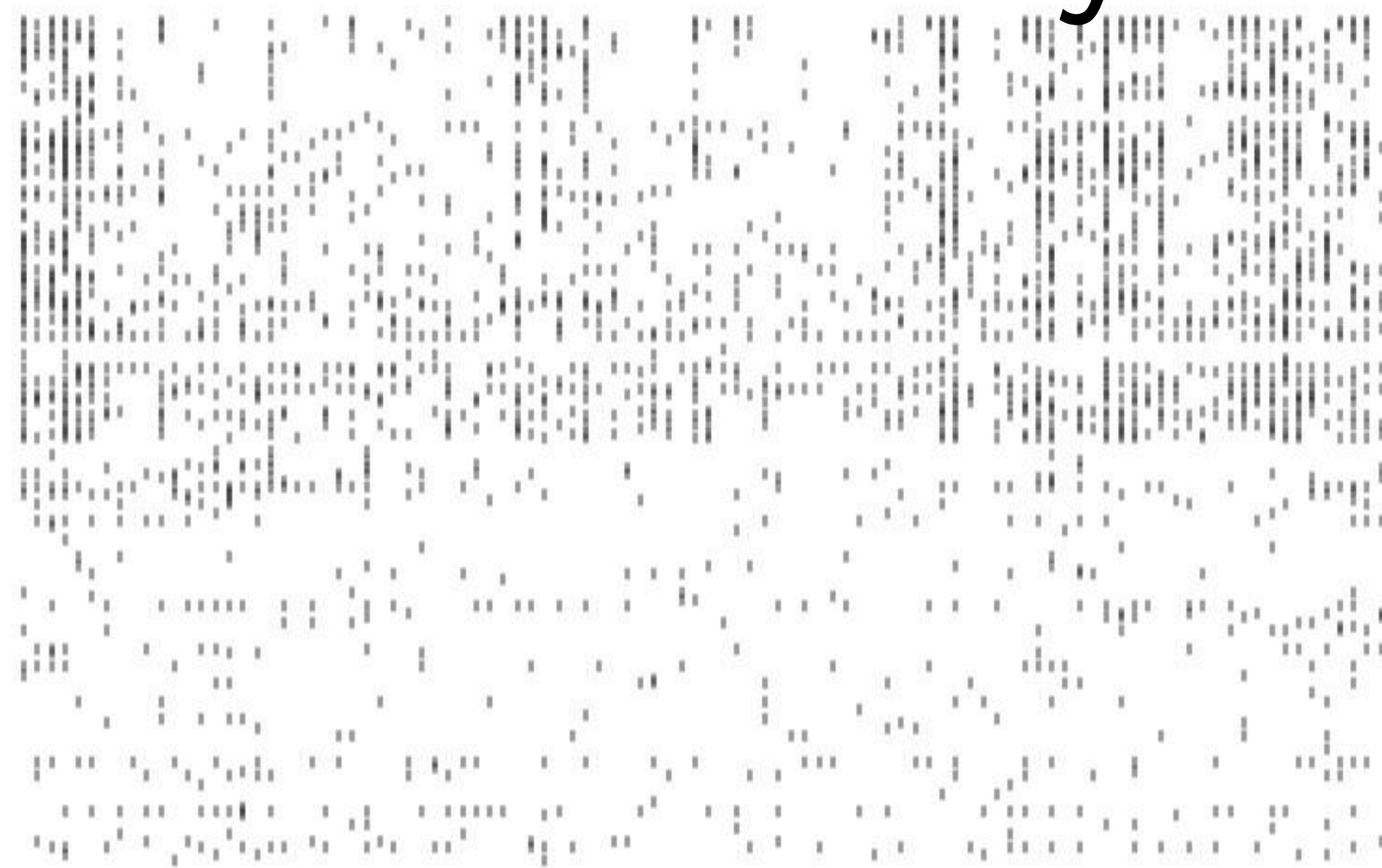
(For chronic BCI)



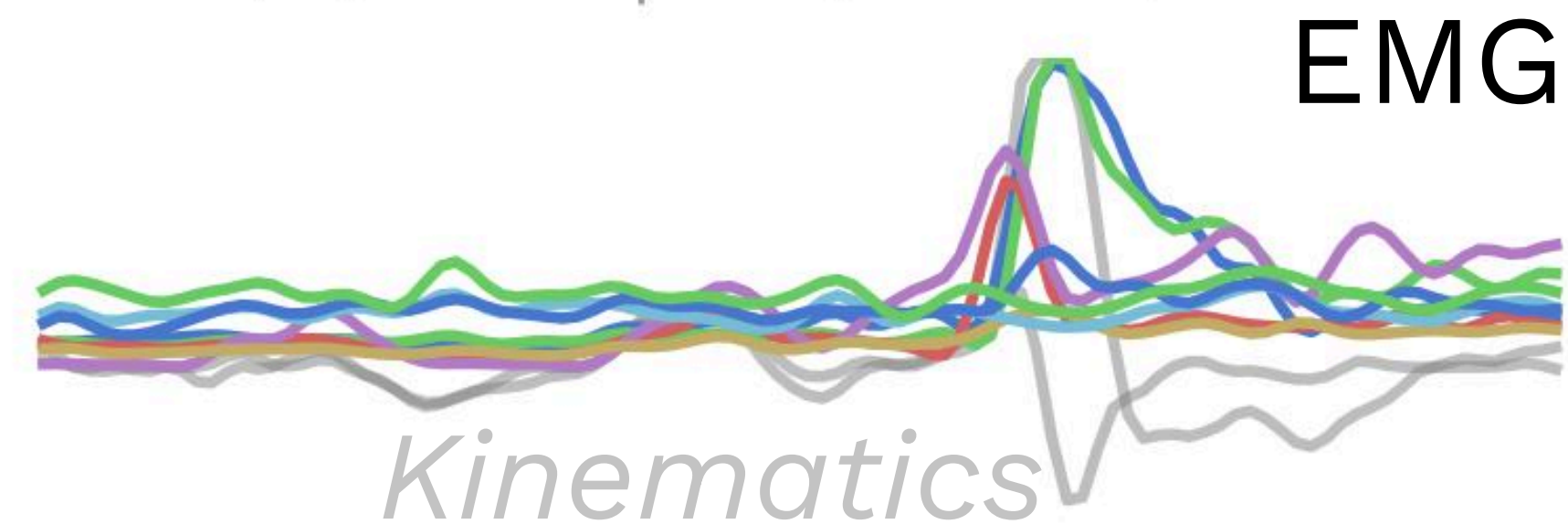
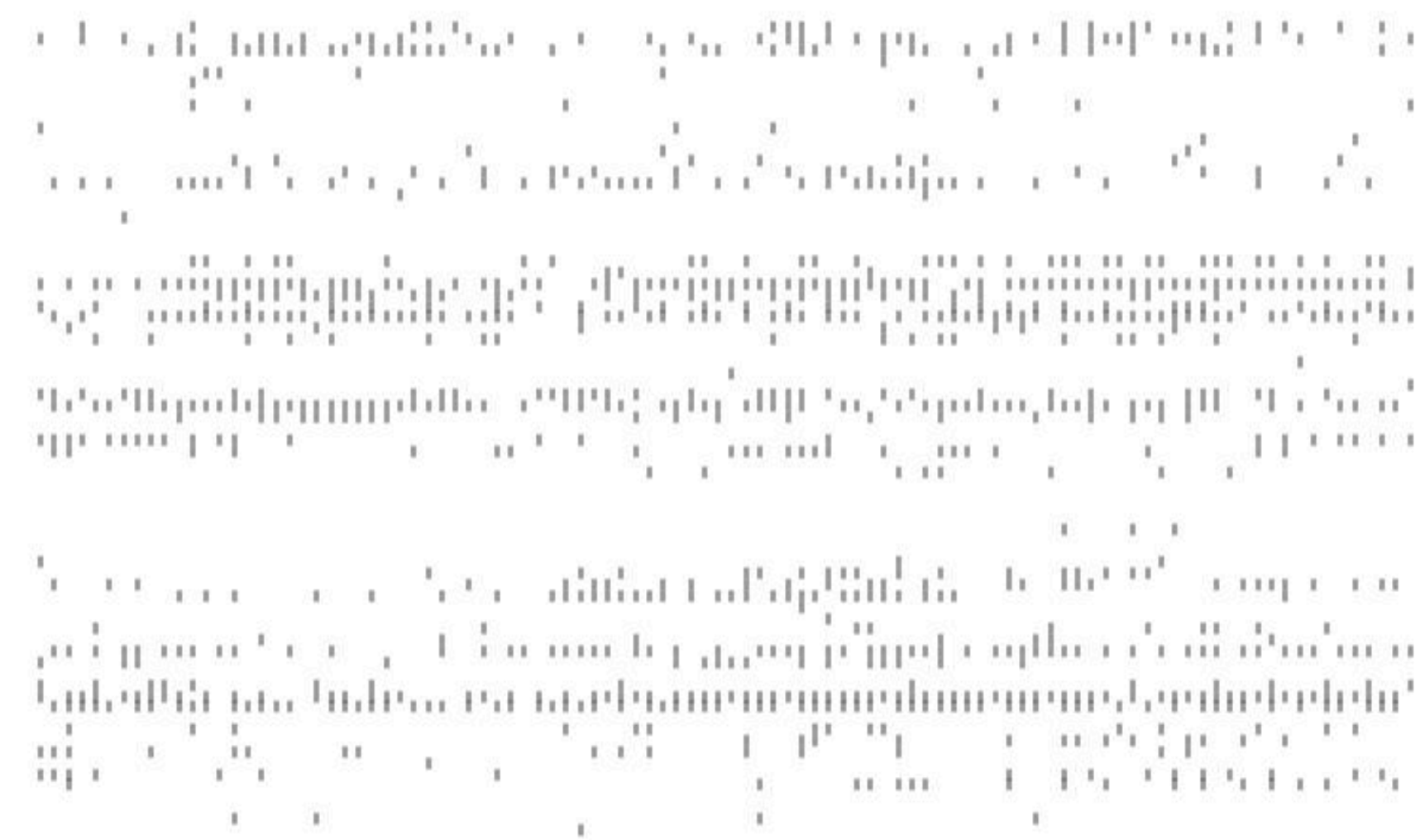
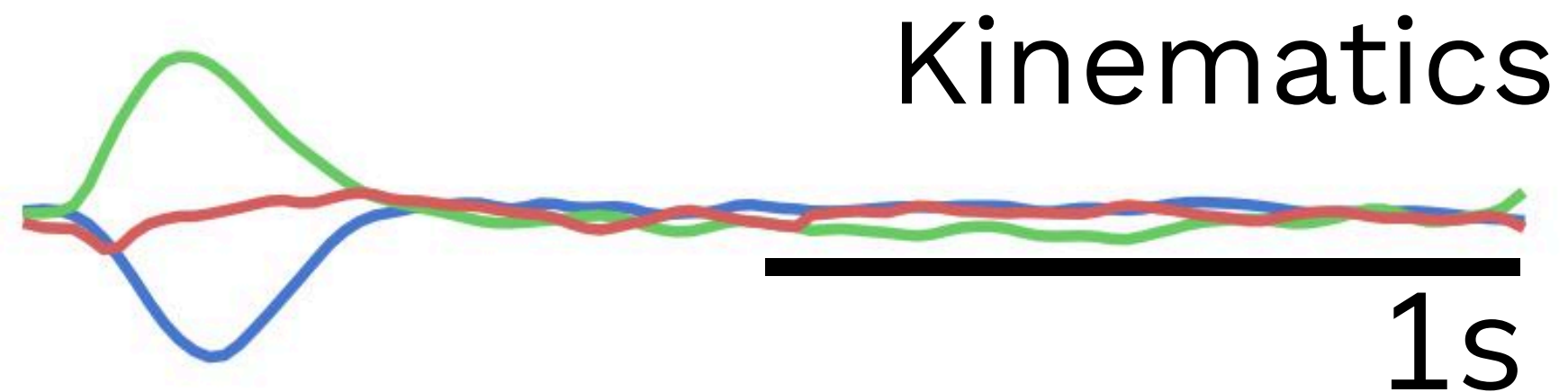


# Neural Data Transformer 3 (NDT3): Scaling motor BCI pretraining to 2000 hours

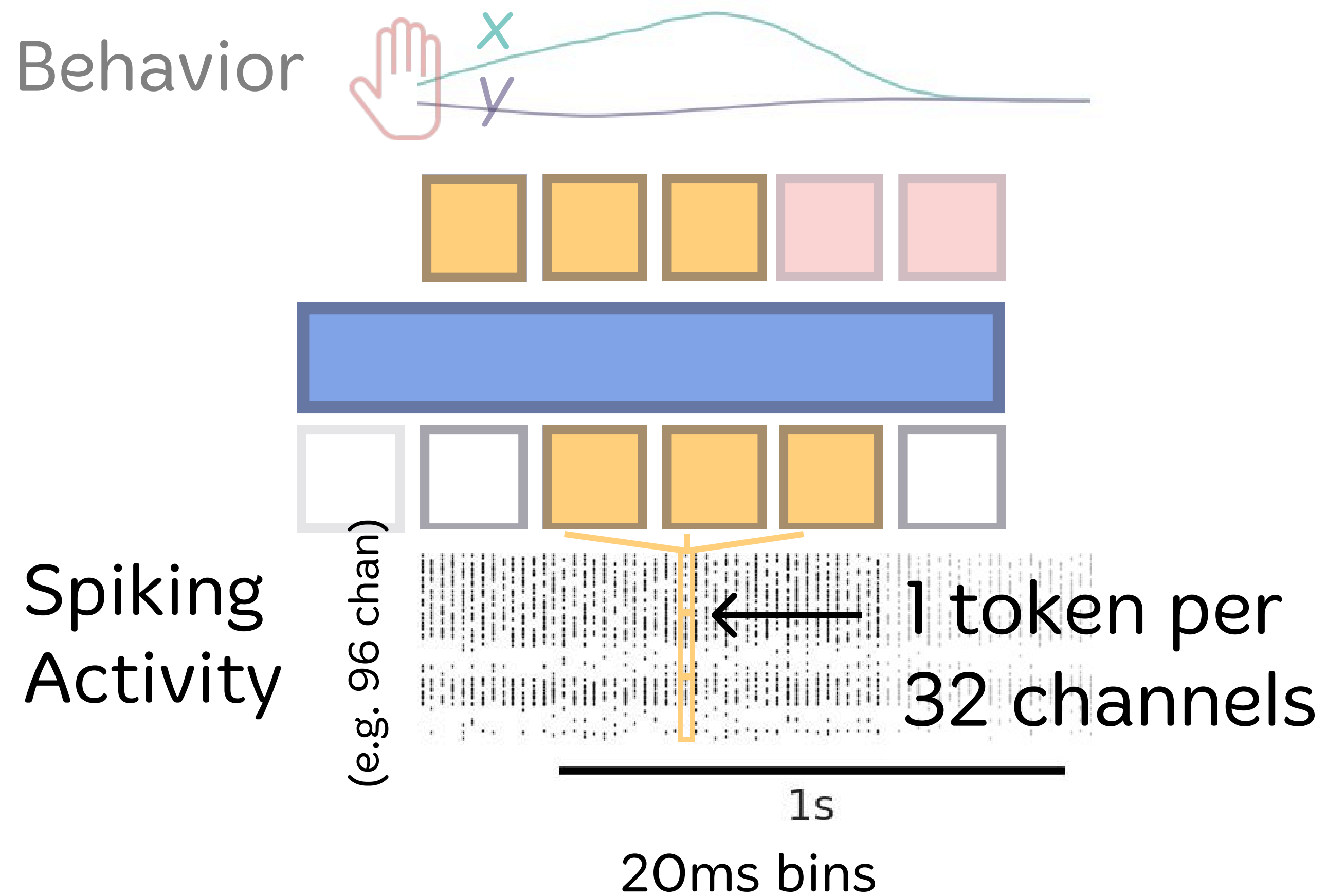
## Neural Activity



## Covariates

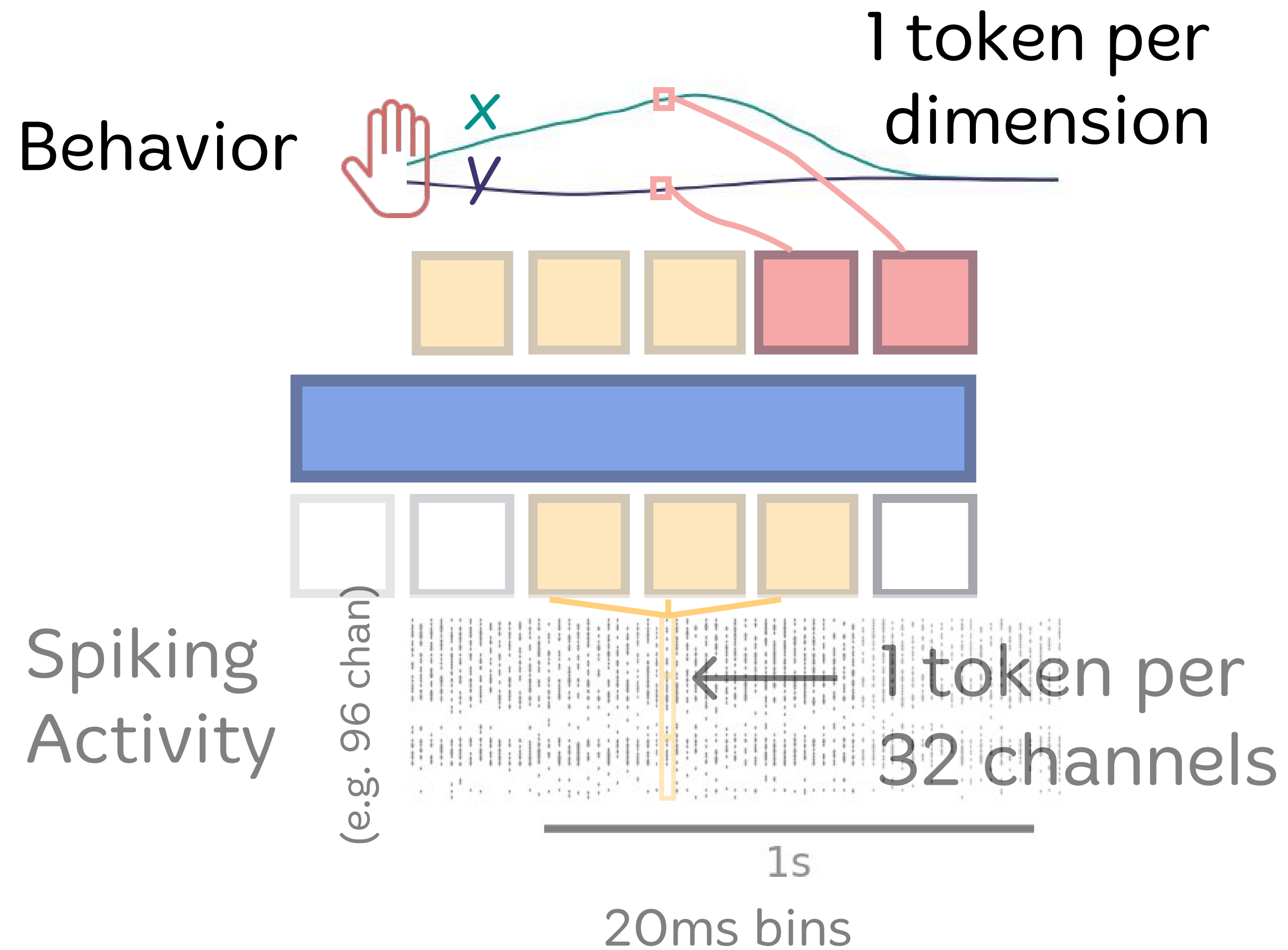


# Neural Data Transformer 3 (NDT3): Scaling motor BCI pretraining to 2000 hours

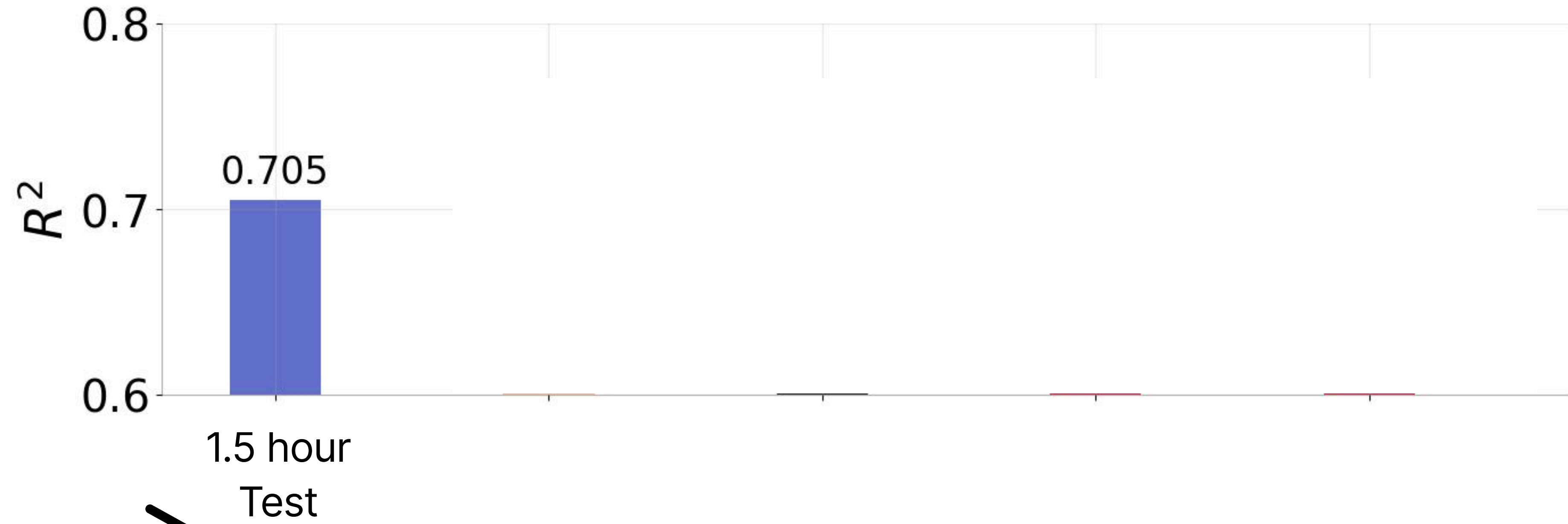




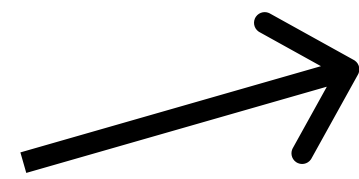
# Neural Data Transformer 3 (NDT3): Scaling motor BCI pretraining to 2000 hours



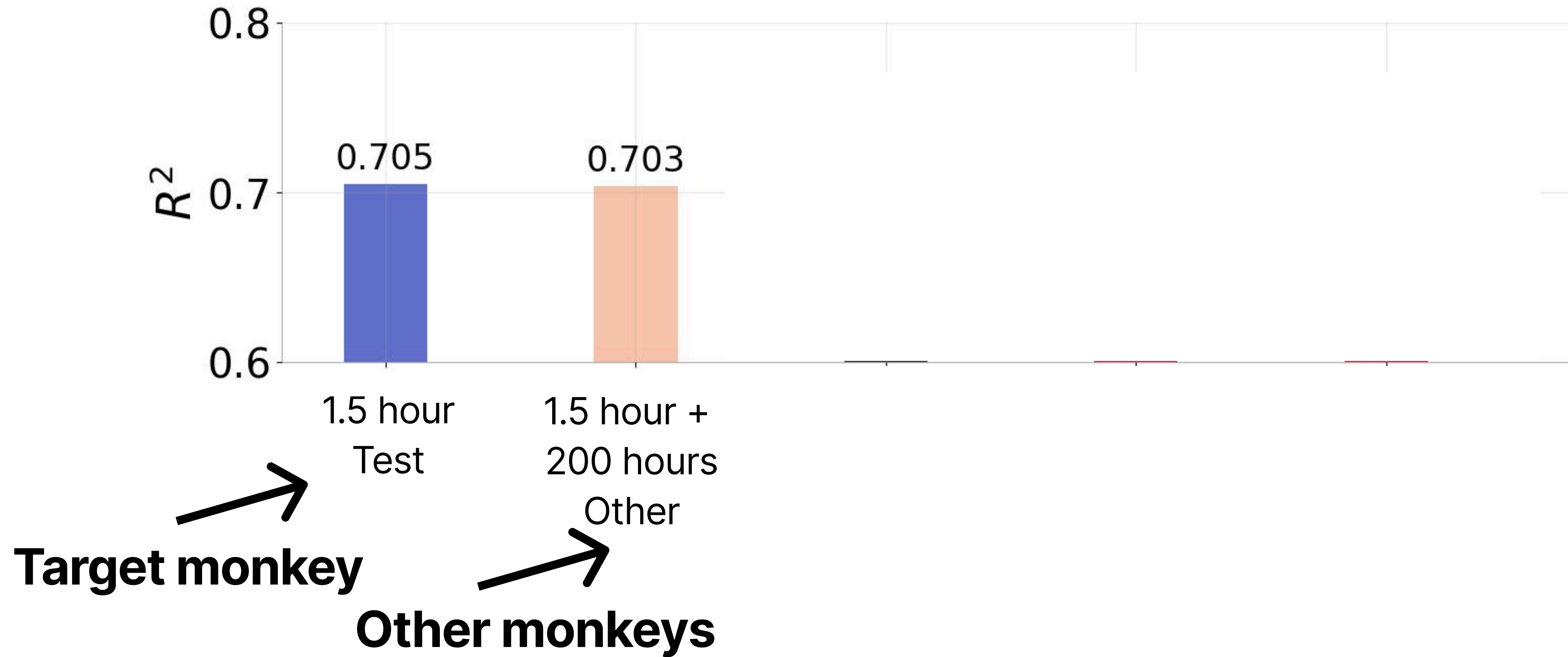
# Scaled pretraining shows weak pragmatic (cross-subject) transfer



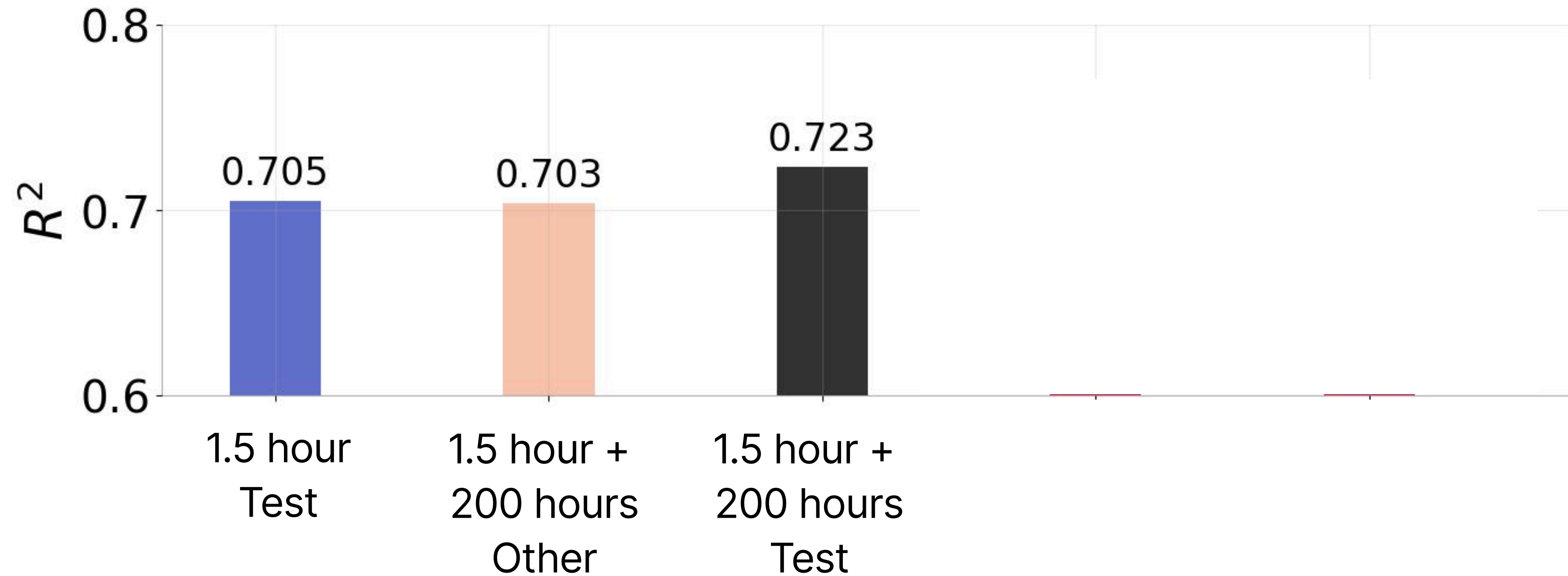
**Target monkey**



# Scaled pretraining shows weak pragmatic (cross-subject) transfer

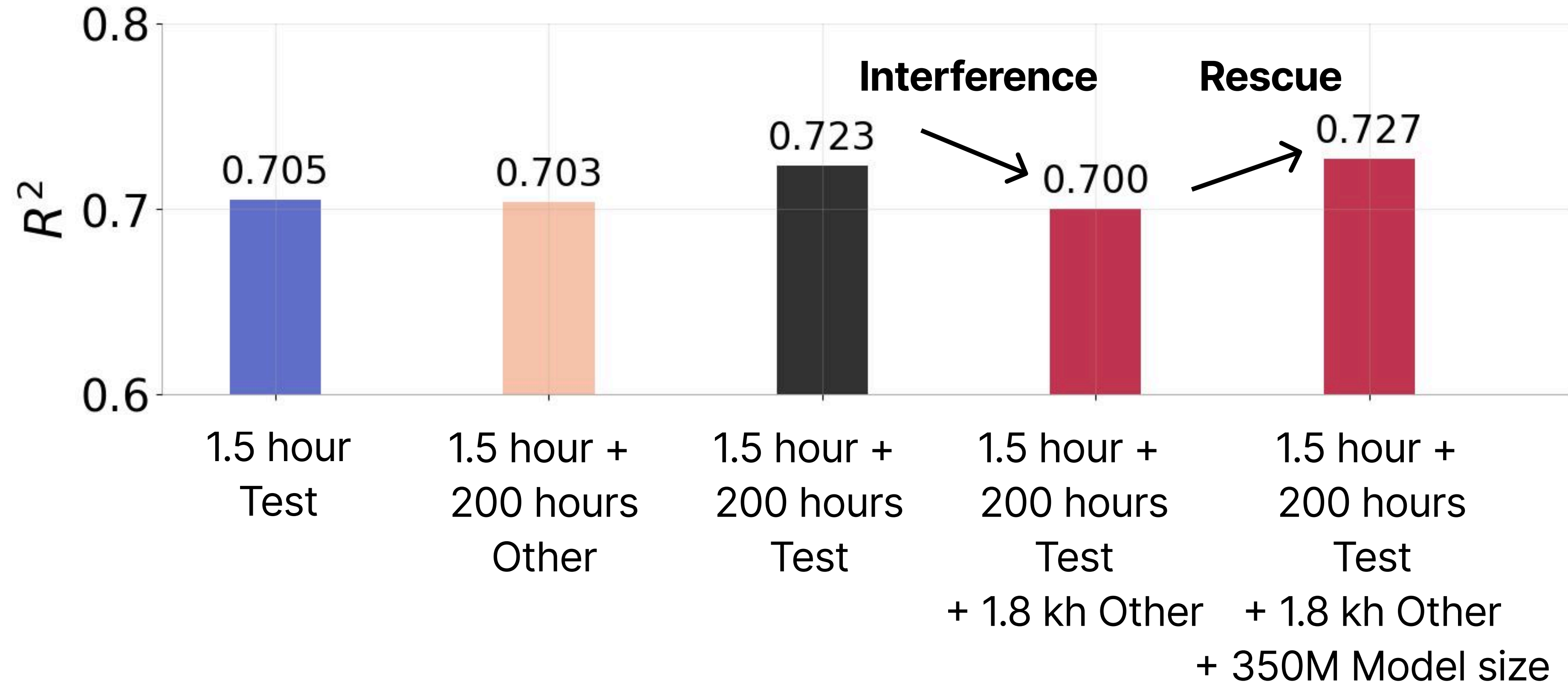


## Scaled pretraining shows weak pragmatic (cross-subject) transfer

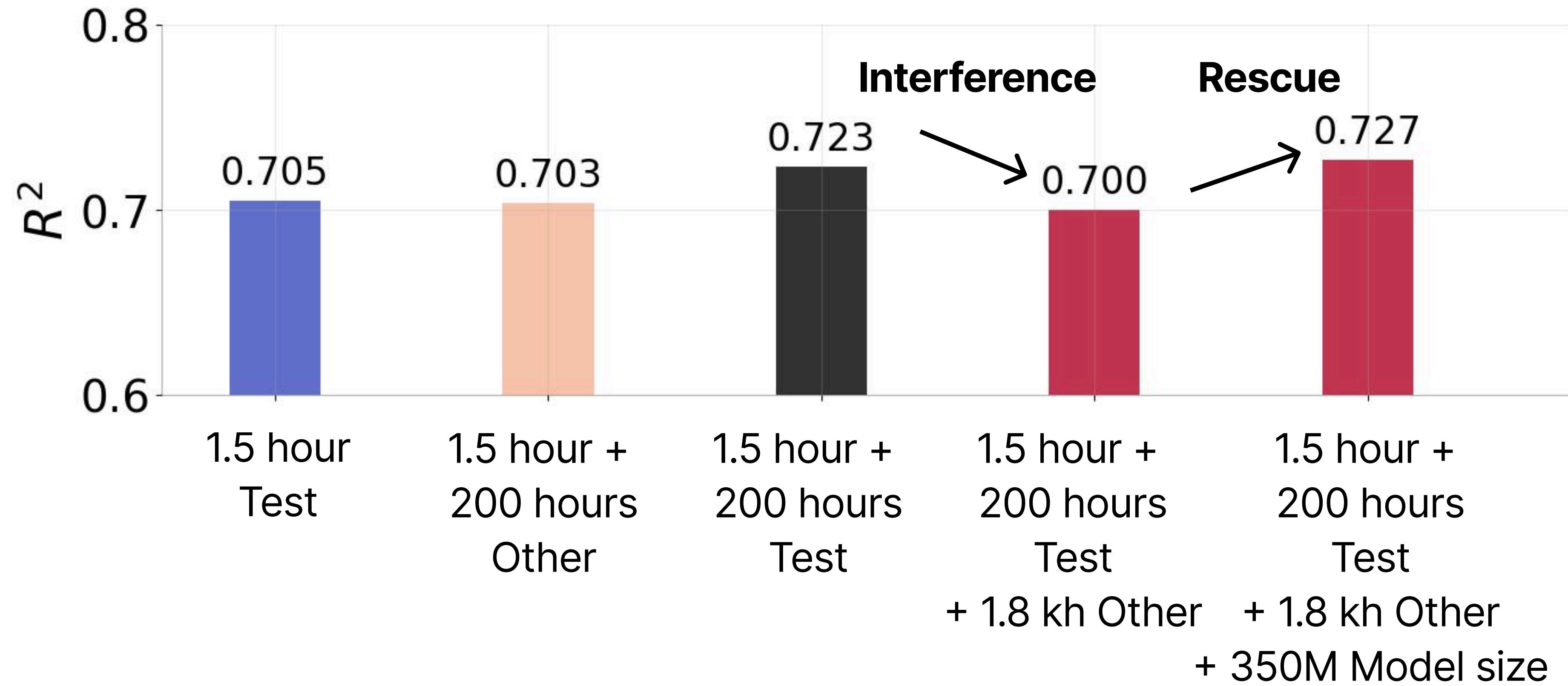


**Cross-subject transfer fails for the long tail?**

# Scaled pretraining shows weak pragmatic (cross-subject) transfer

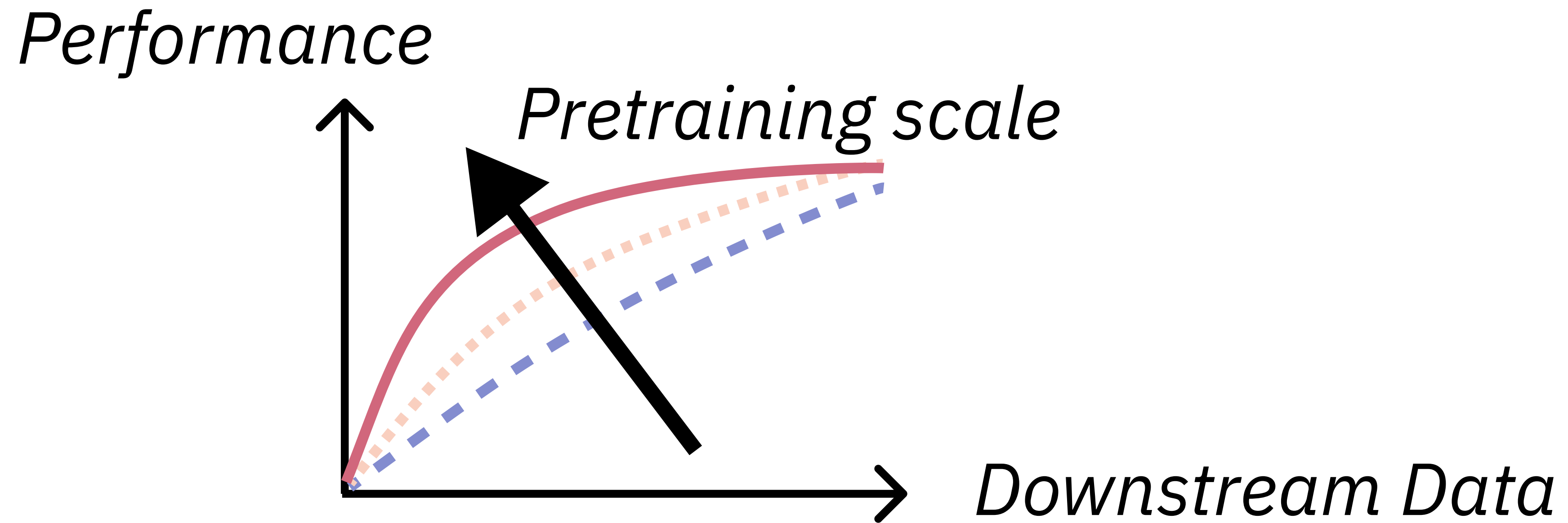


# Scaled pretraining shows weak pragmatic (cross-subject) transfer



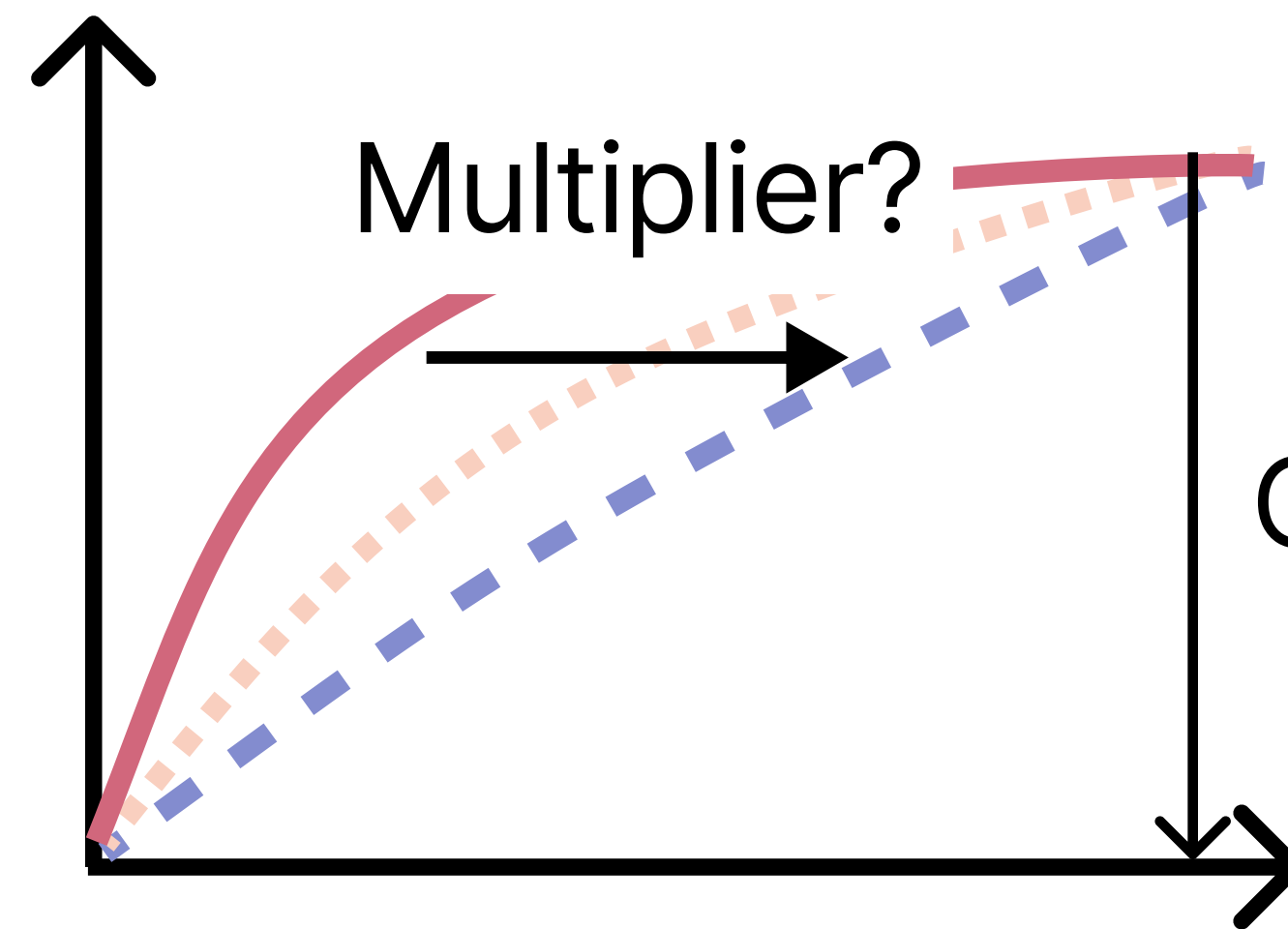
**A cost to our ambition, for no gain?**

# Quantifying downstream scaling gains



# Quantifying downstream scaling gains

*Performance*



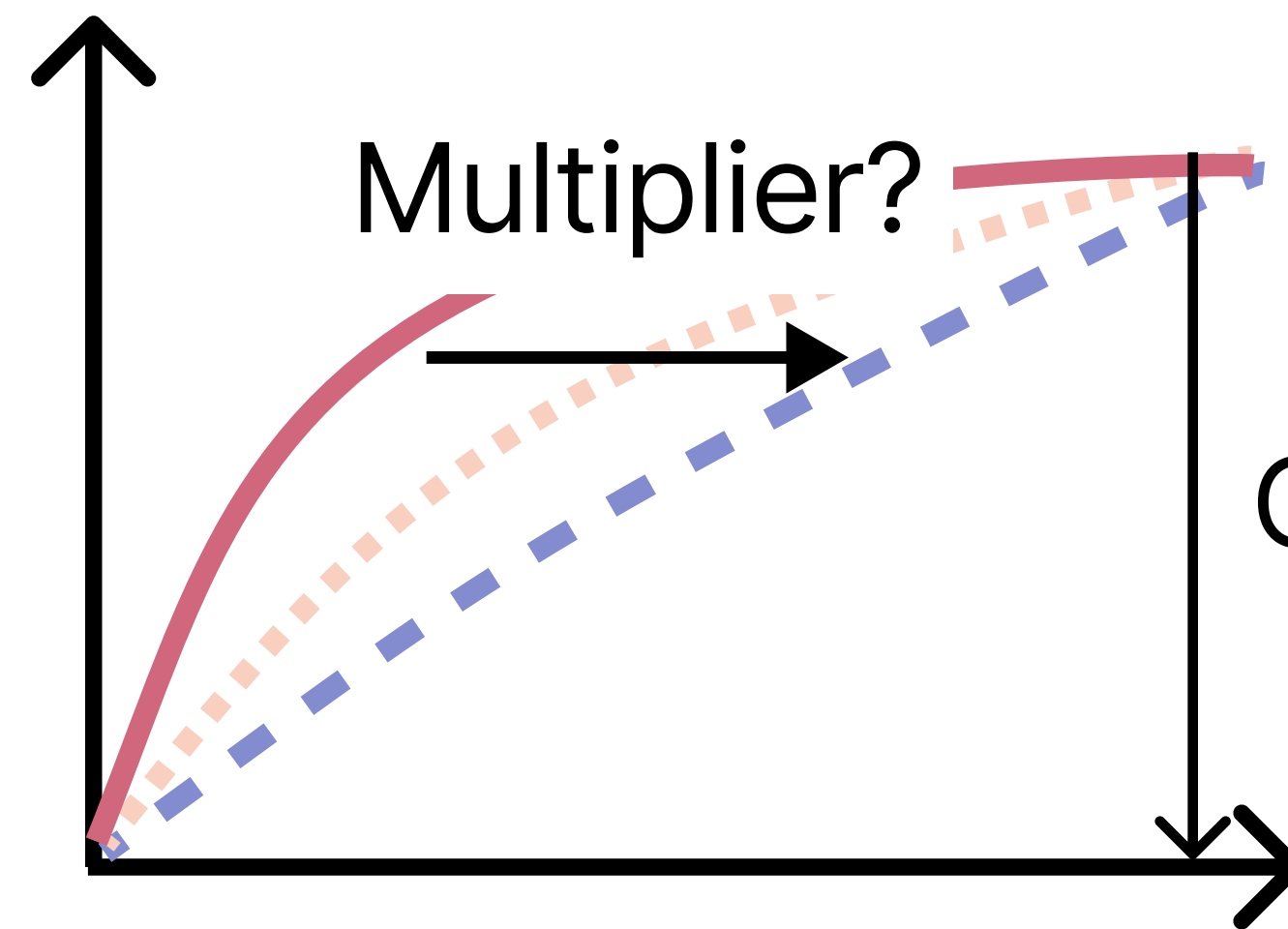
Convergence?

*Downstream Data*



# Quantifying downstream scaling gains

*Performance*

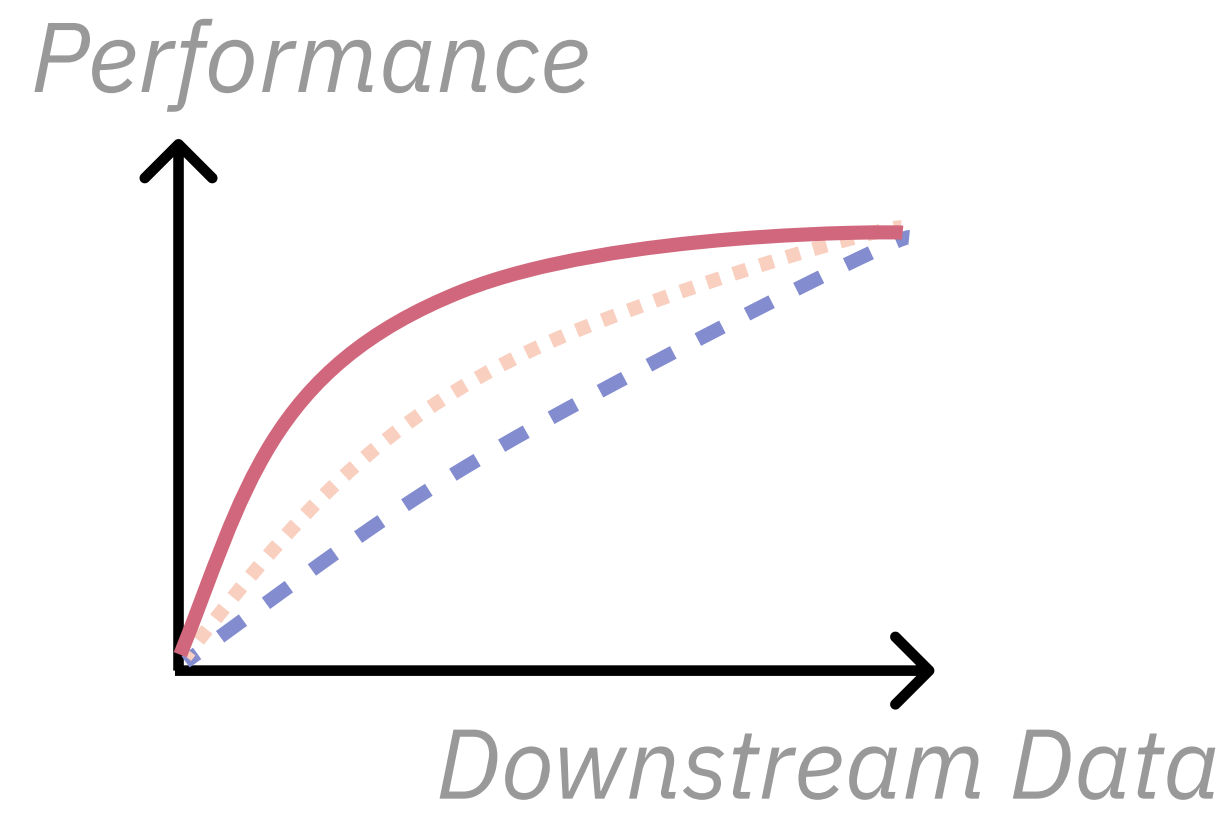


**Pretraining results suggest  
convergence  $\leq 1.5$  hours**

Convergence?

*Downstream Data*

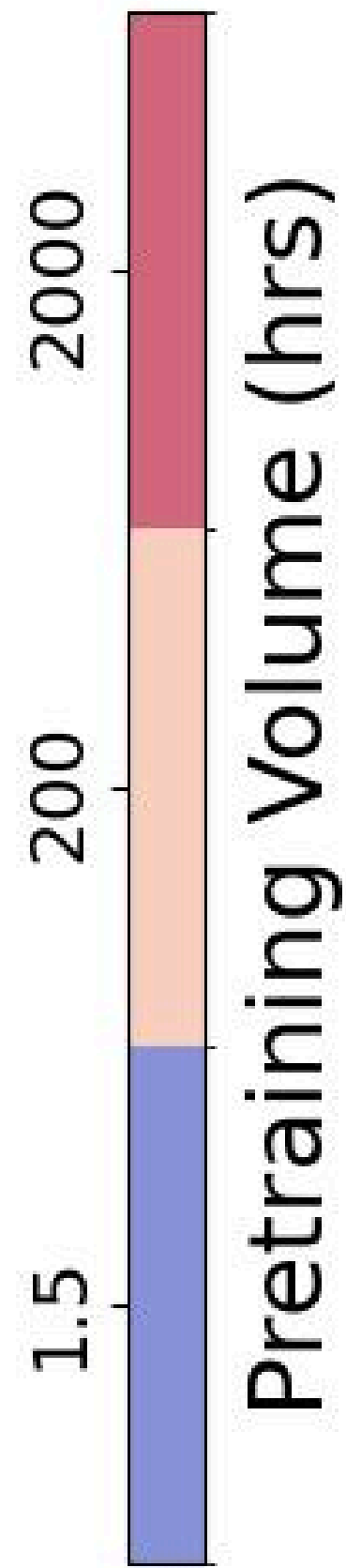
# Quantifying downstream scaling gains



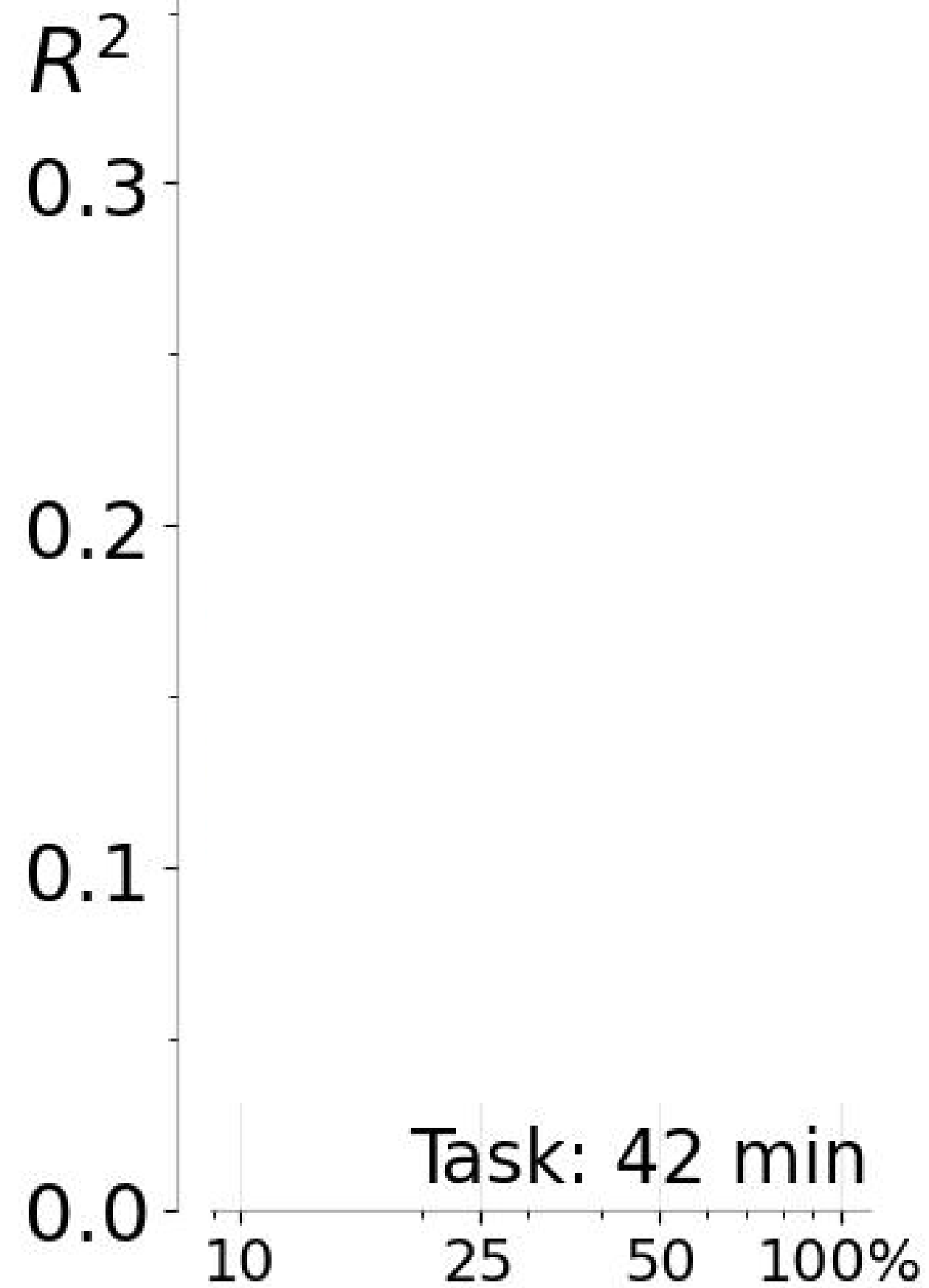
Scratch ·····x

Pretrained 45M —●—●

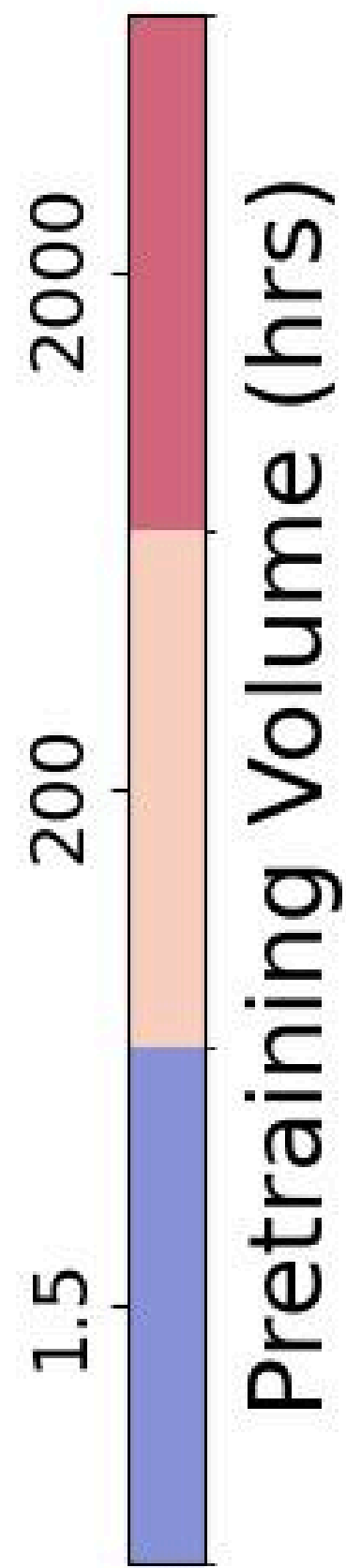
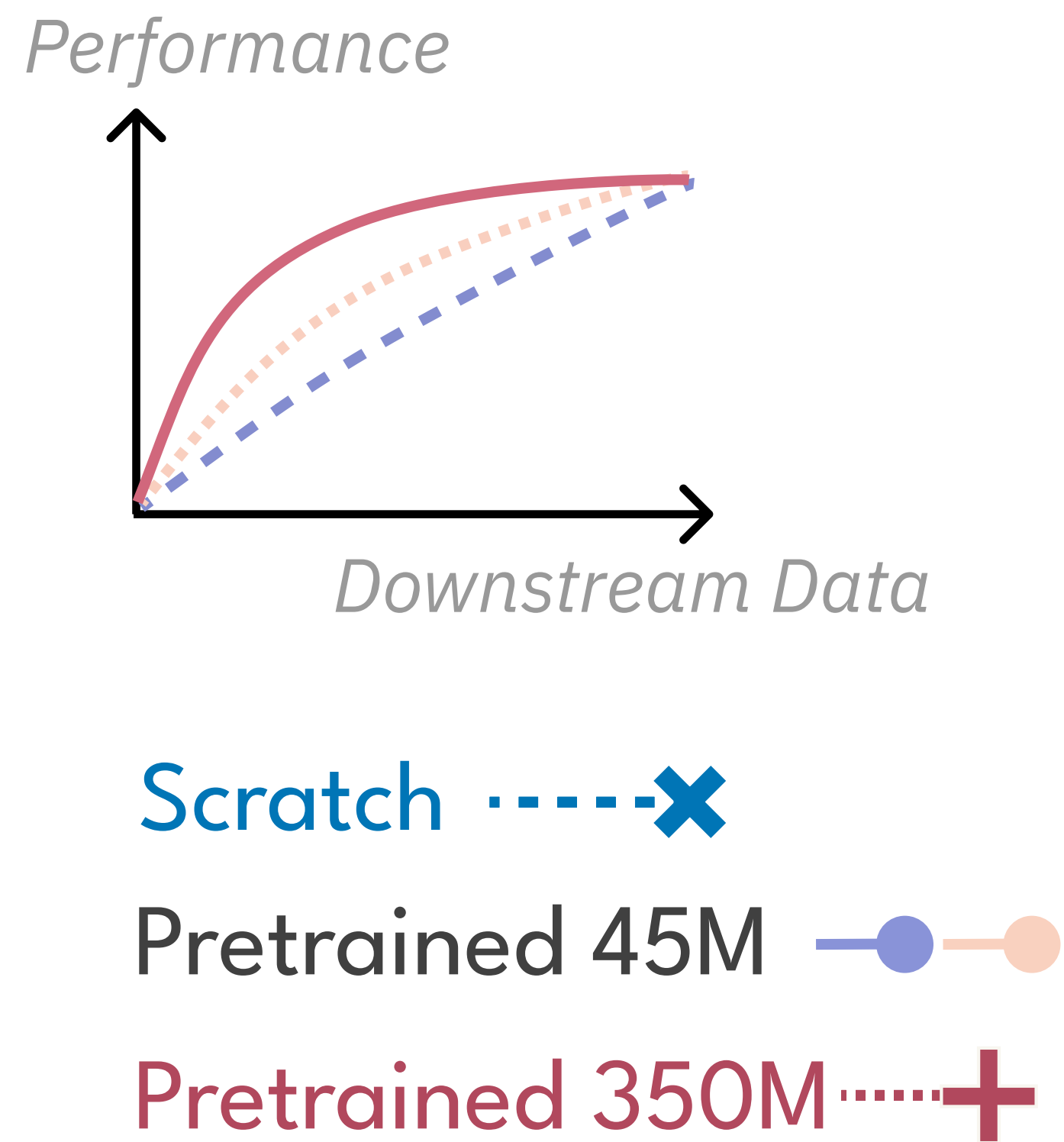
Pretrained 350M ·····+



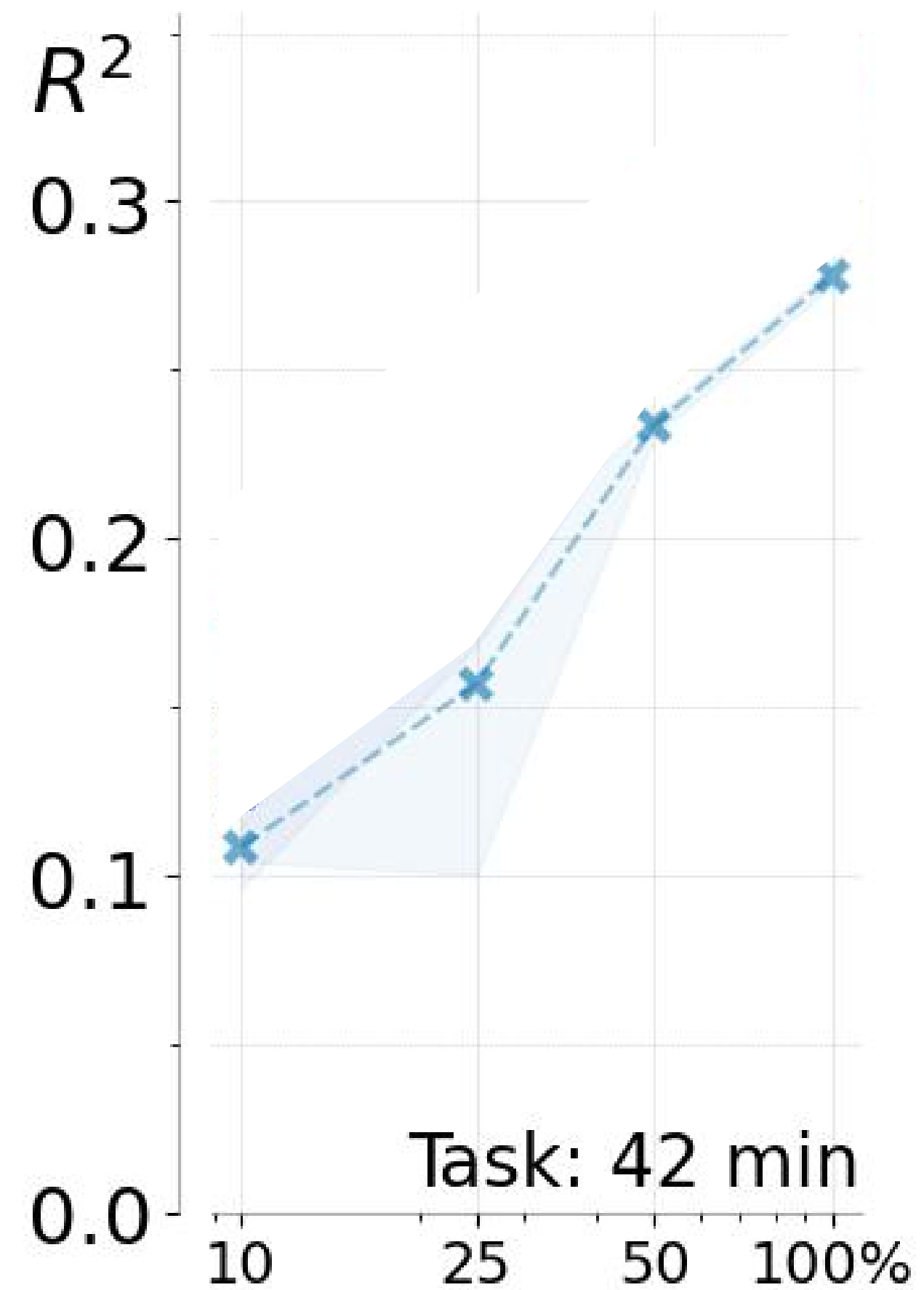
## Bimanual Cursor



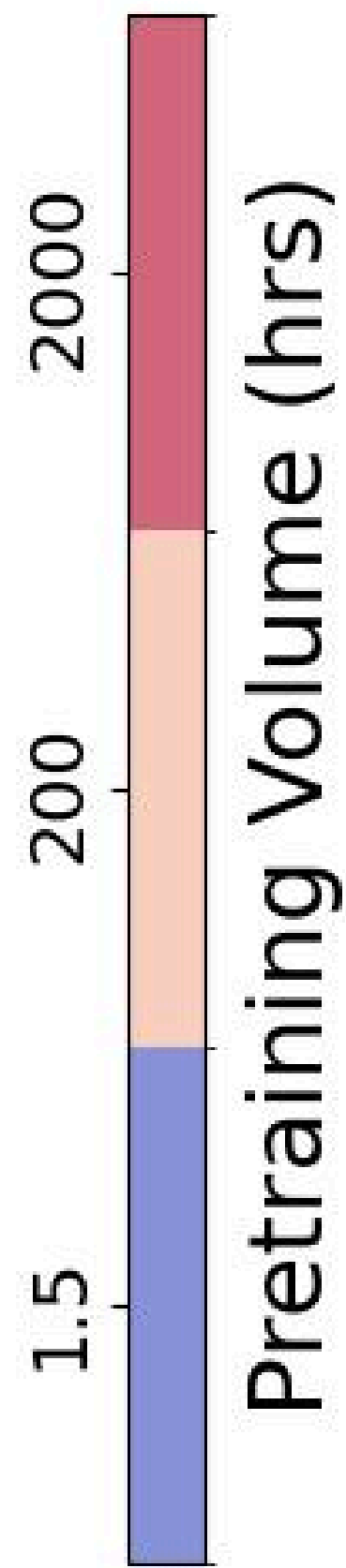
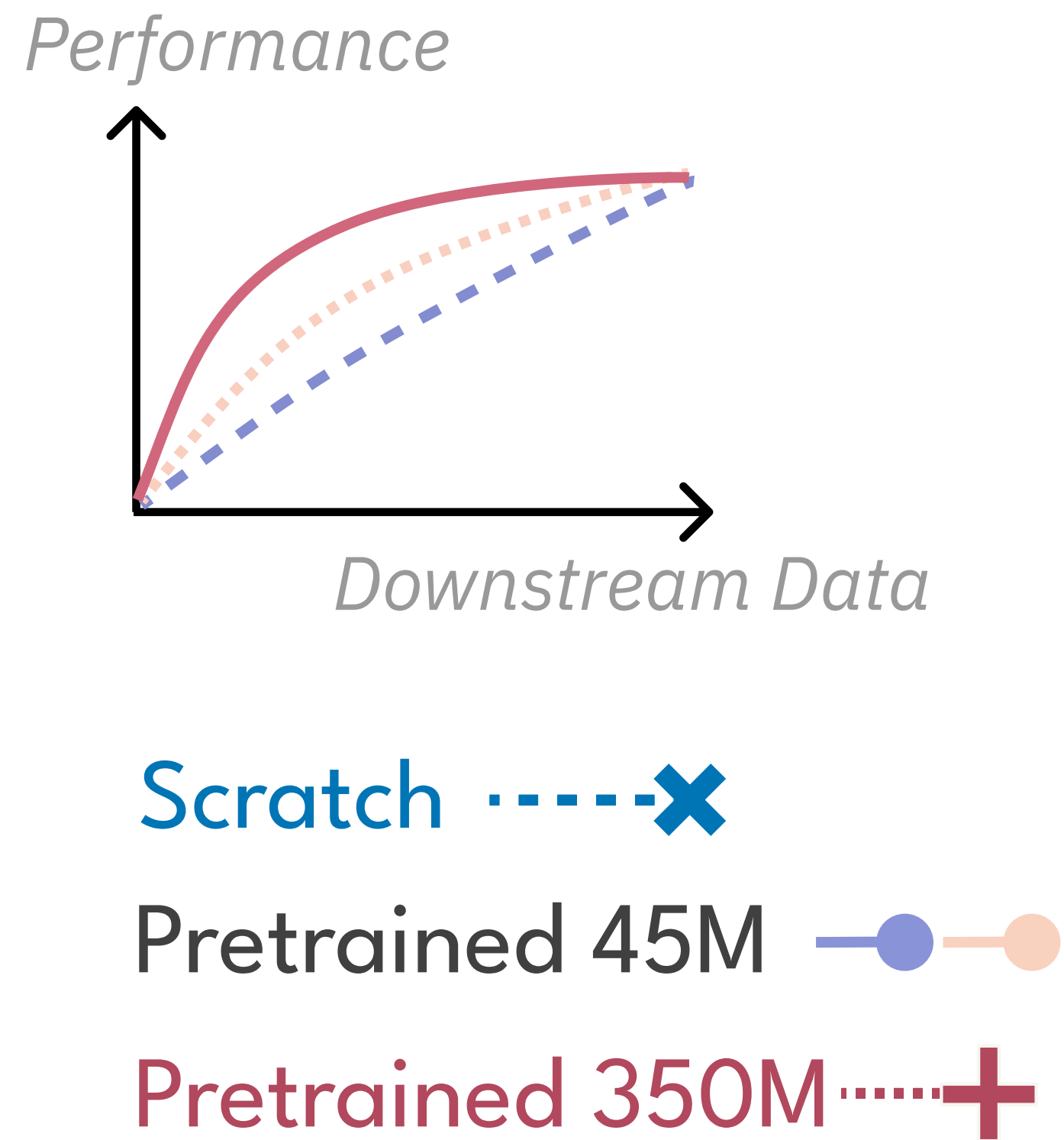
# Quantifying downstream scaling gains



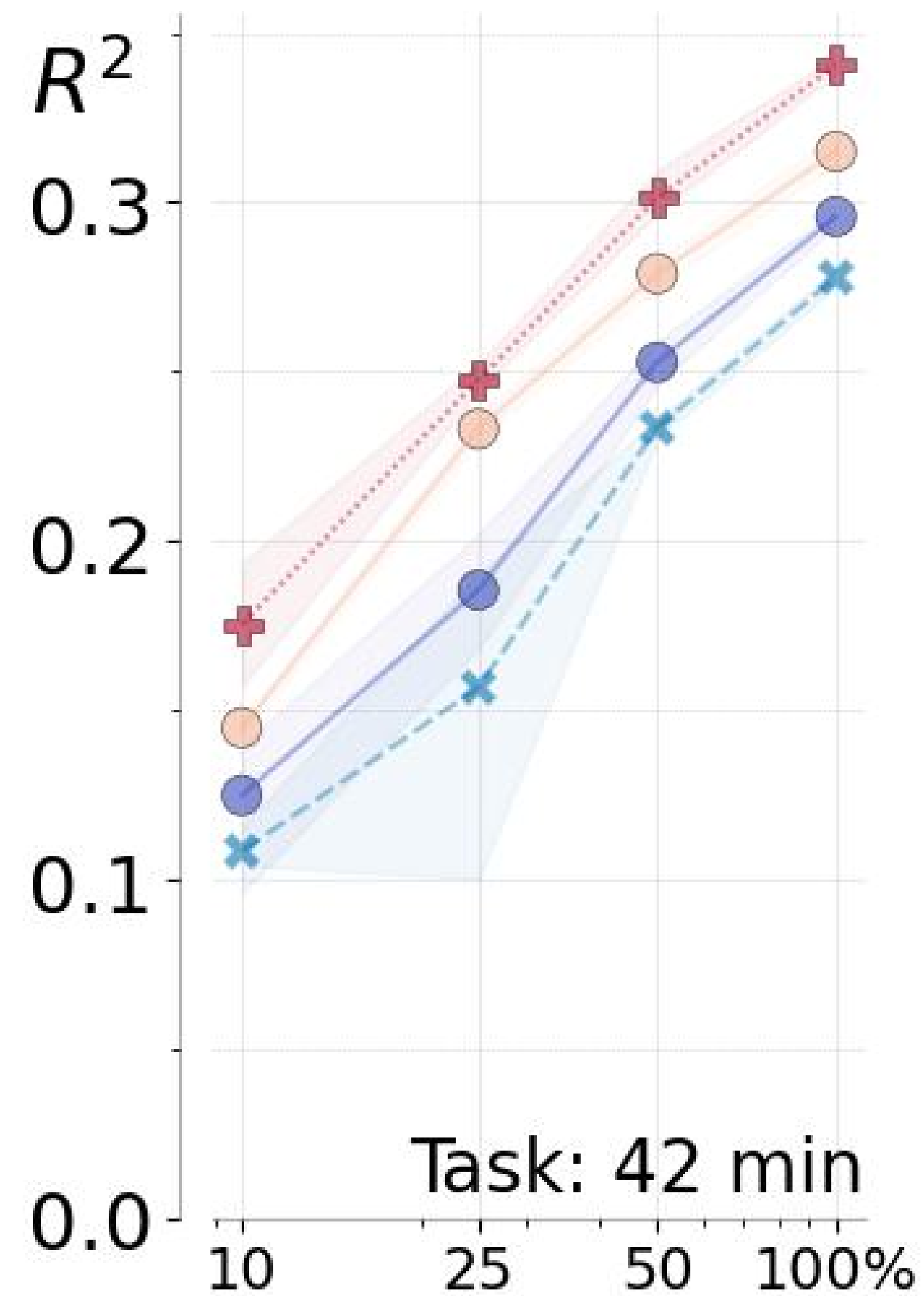
## Bimanual Cursor



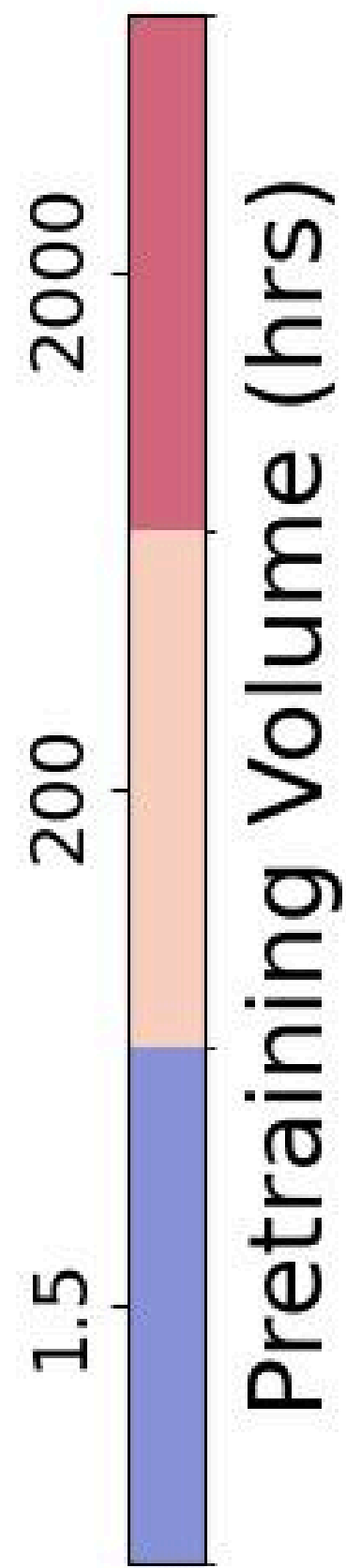
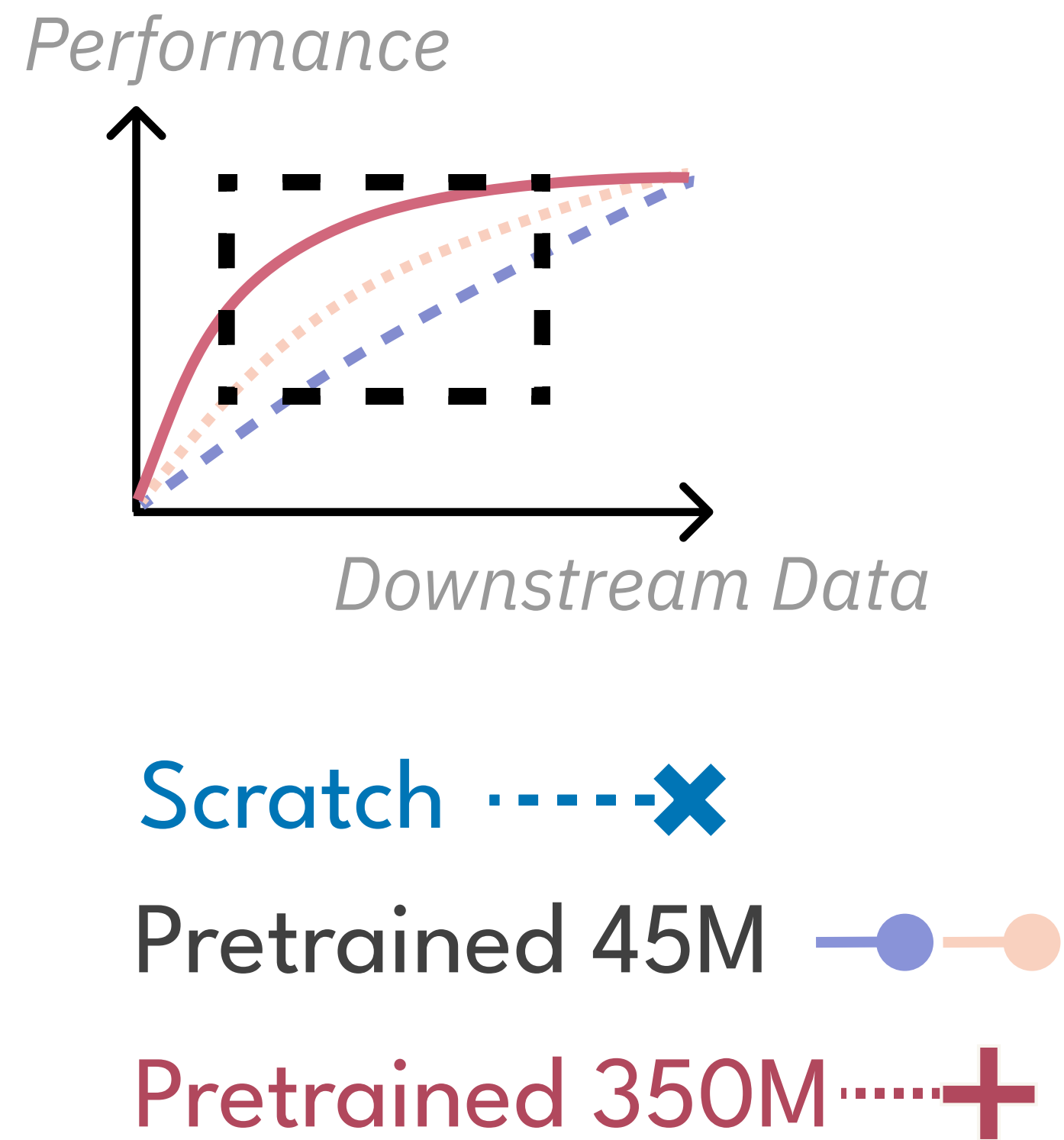
# Quantifying downstream scaling gains



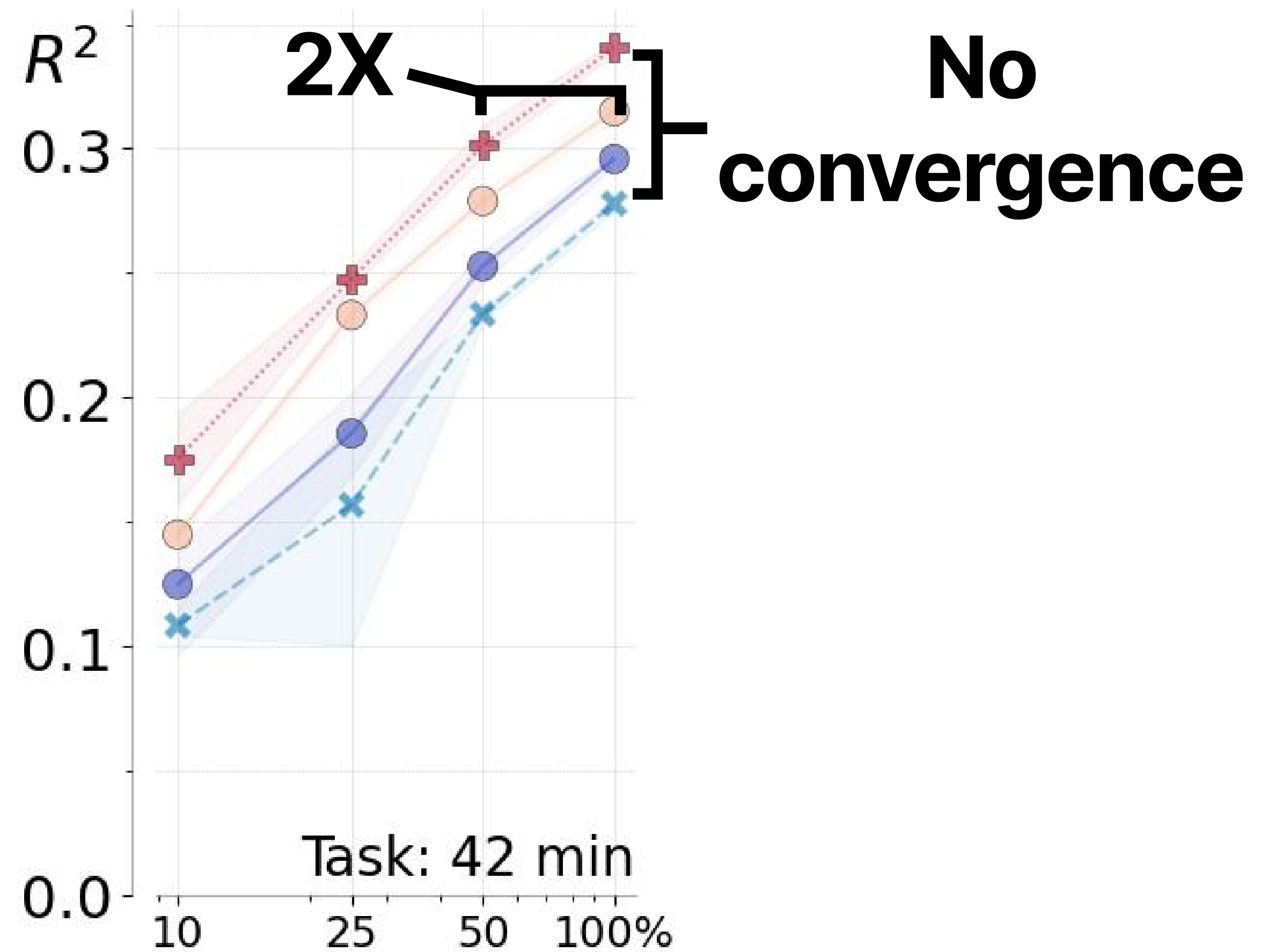
## Bimanual Cursor



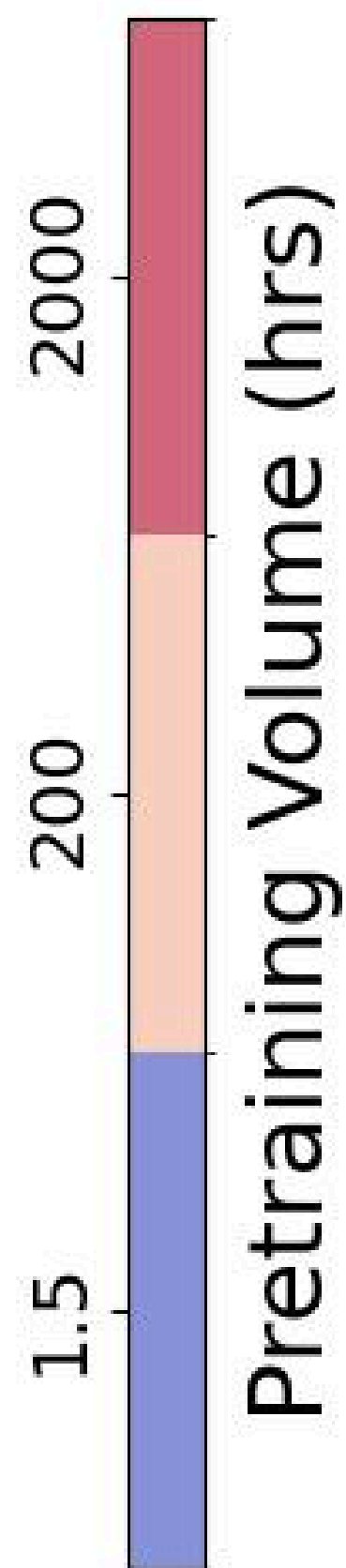
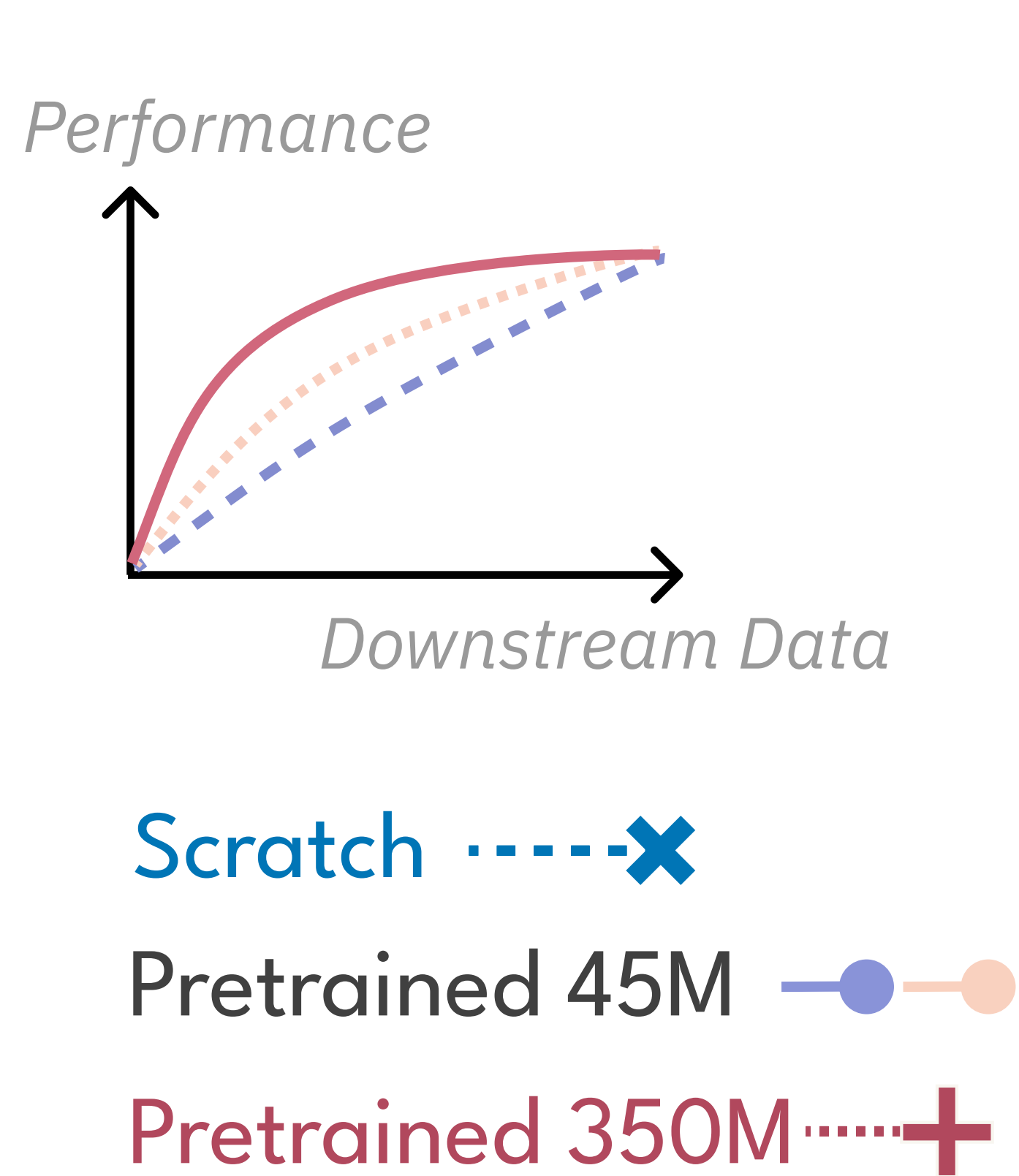
# Quantifying downstream scaling gains



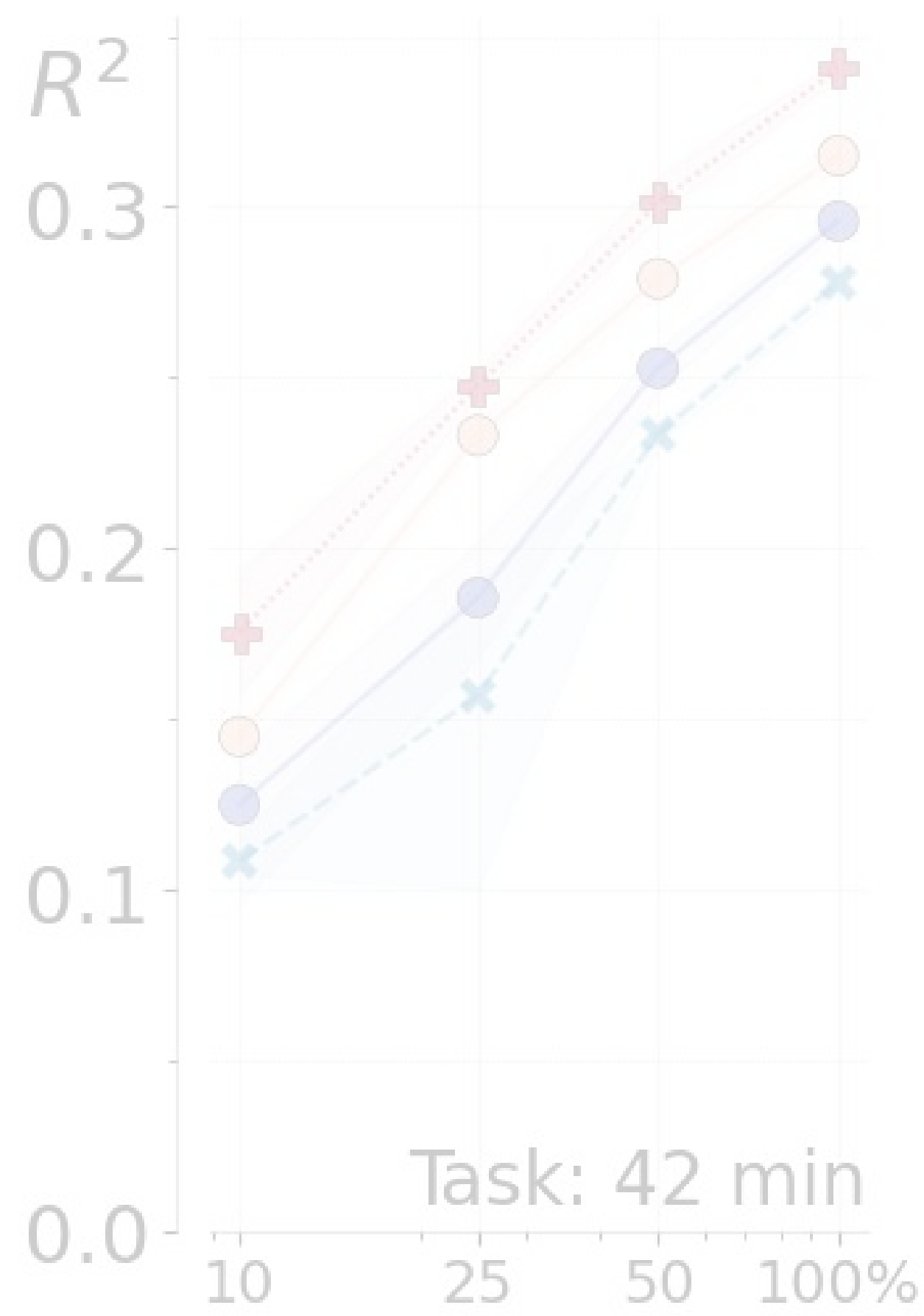
## Bimanual Cursor



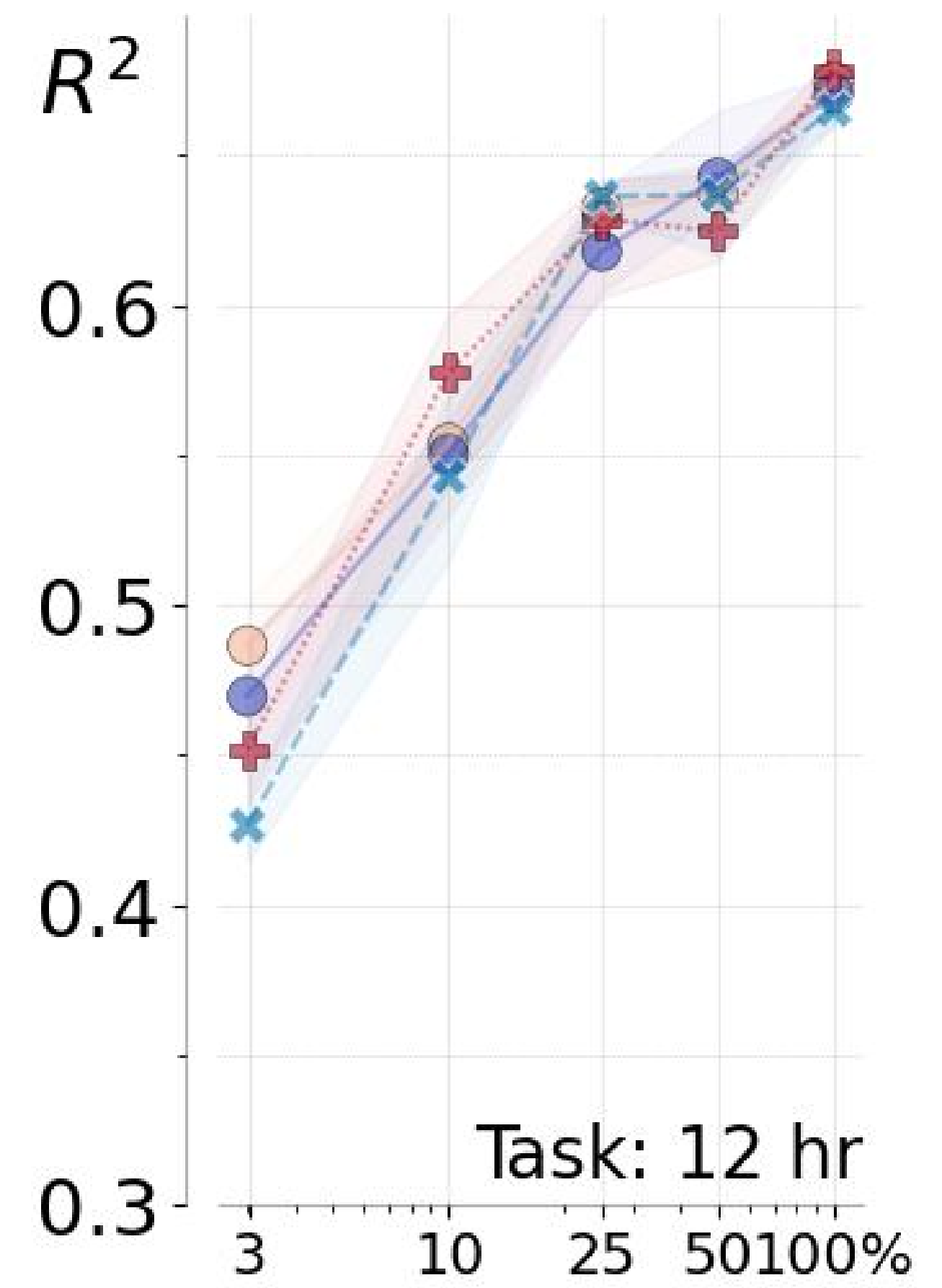
# Quantifying downstream scaling gains **across tasks**



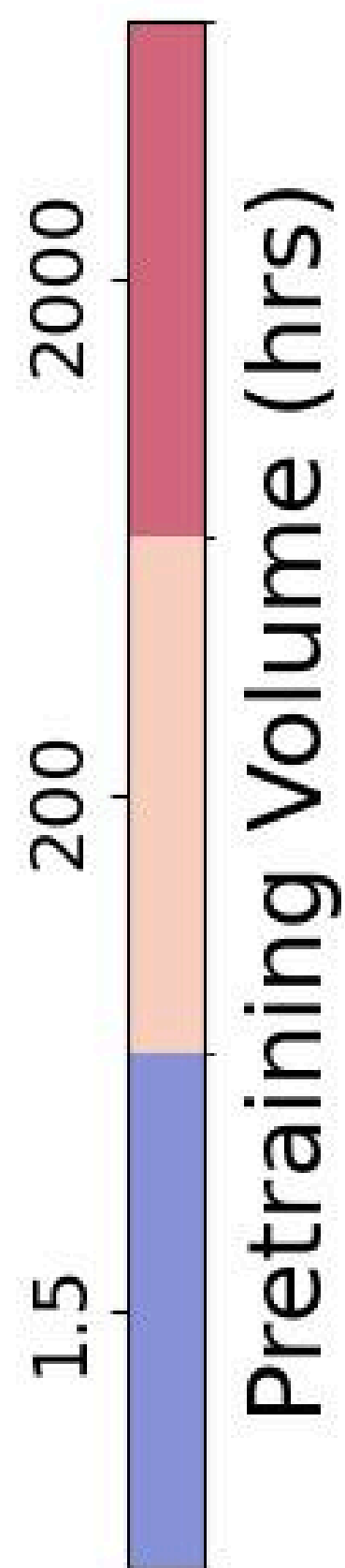
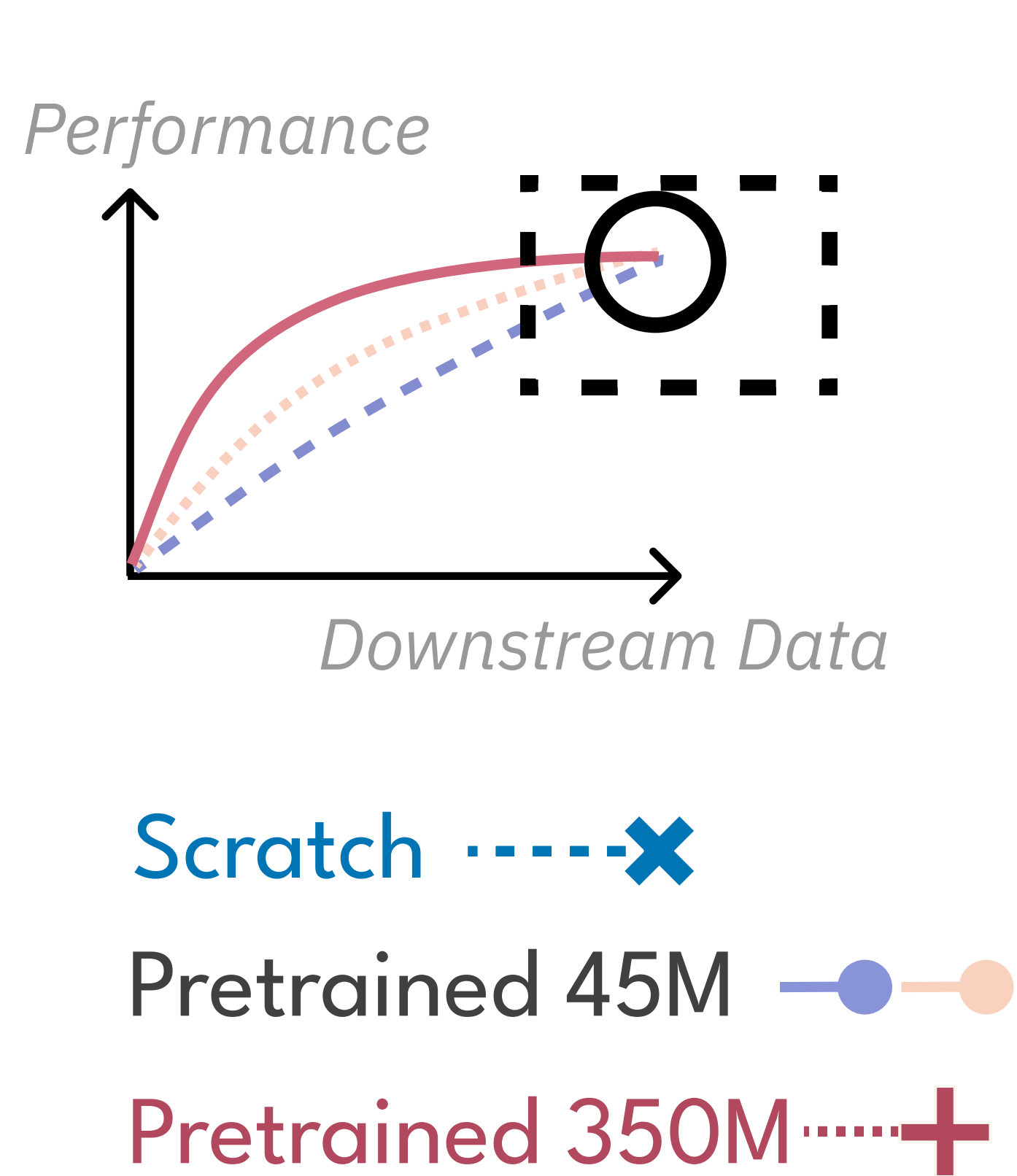
## Bimanual Cursor



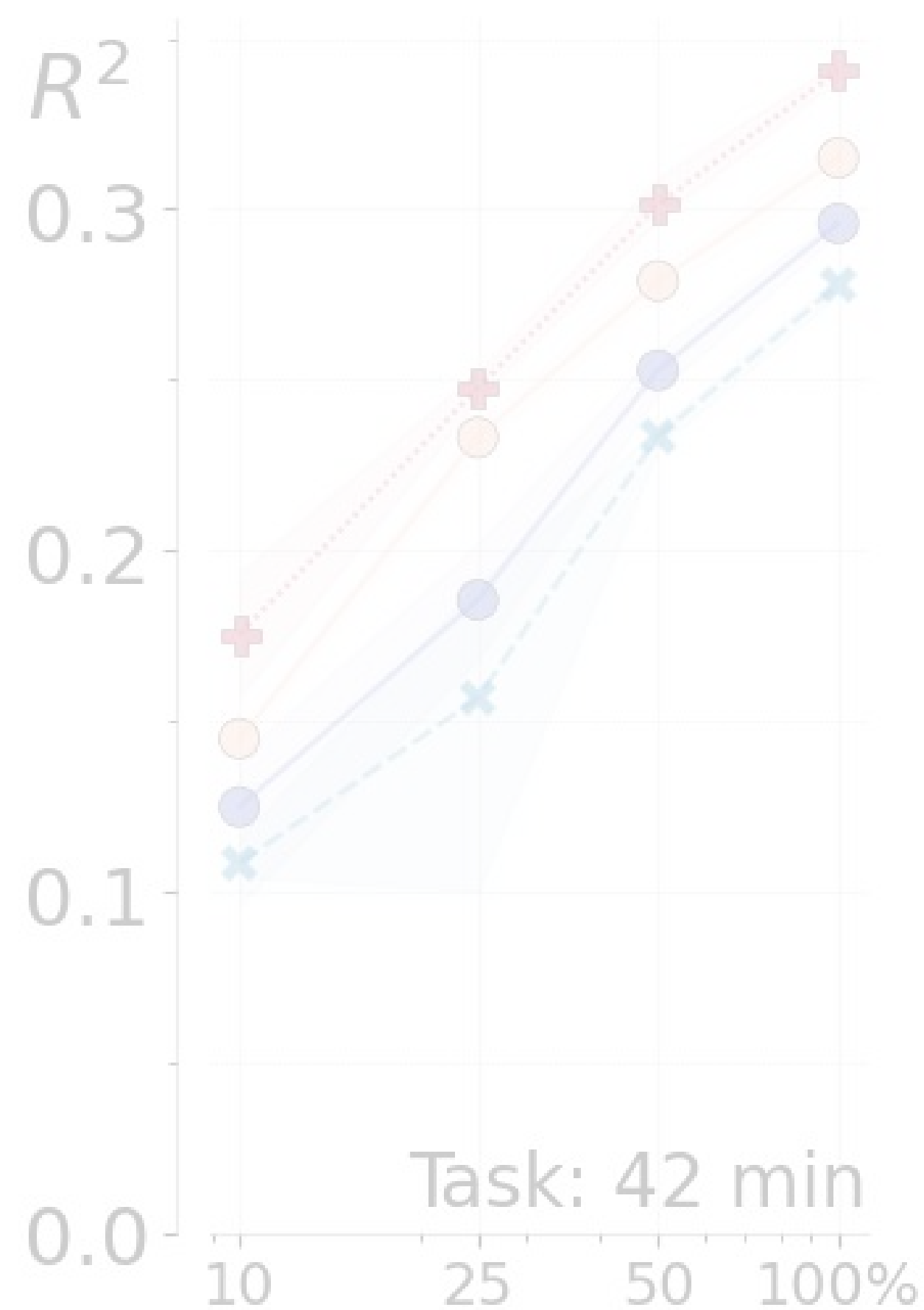
## Self-paced Reach



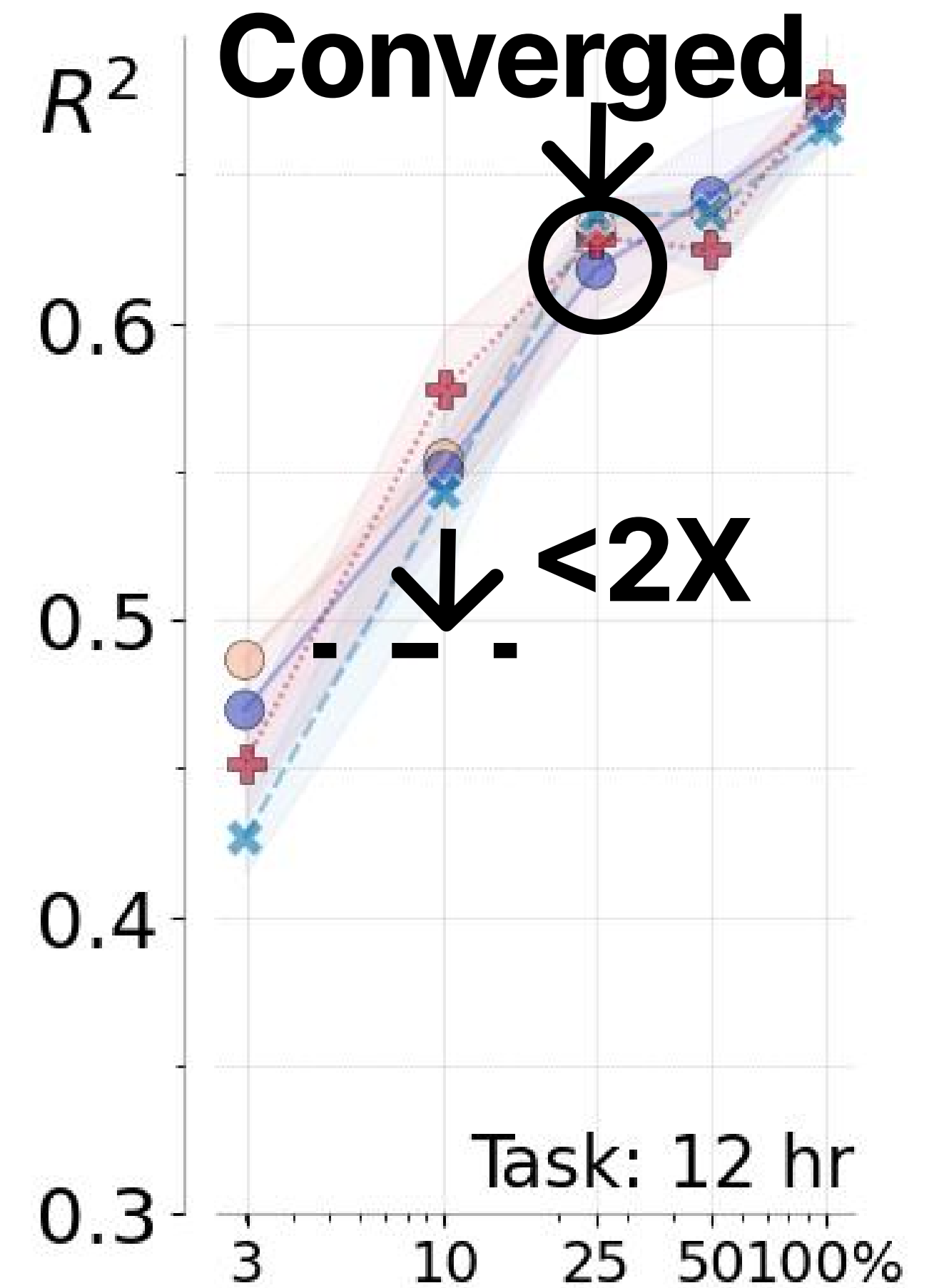
# Quantifying downstream scaling gains **across tasks**



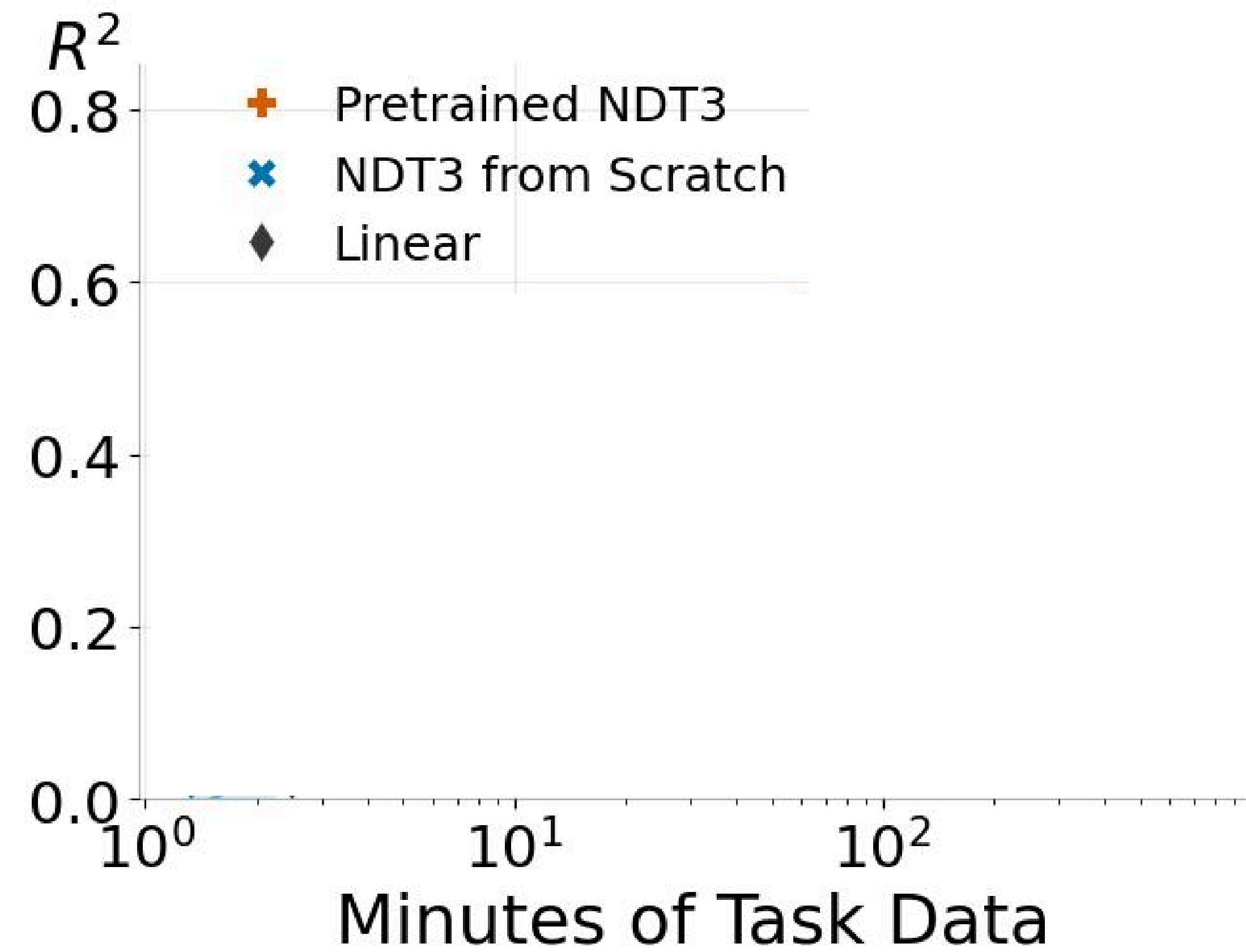
## Bimanual Cursor



## Self-paced Reach

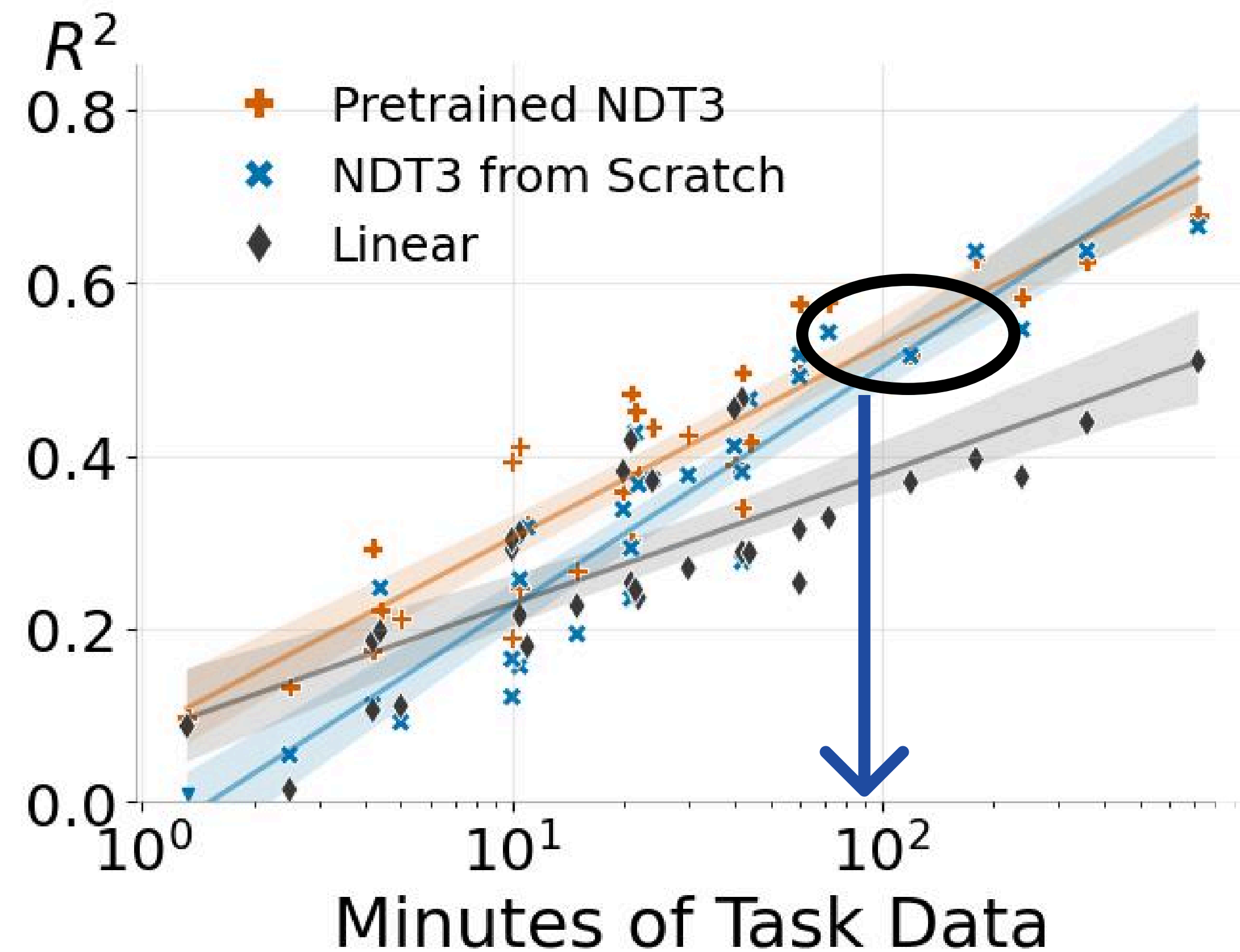


## Quantifying downstream scaling gains on 8 datasets



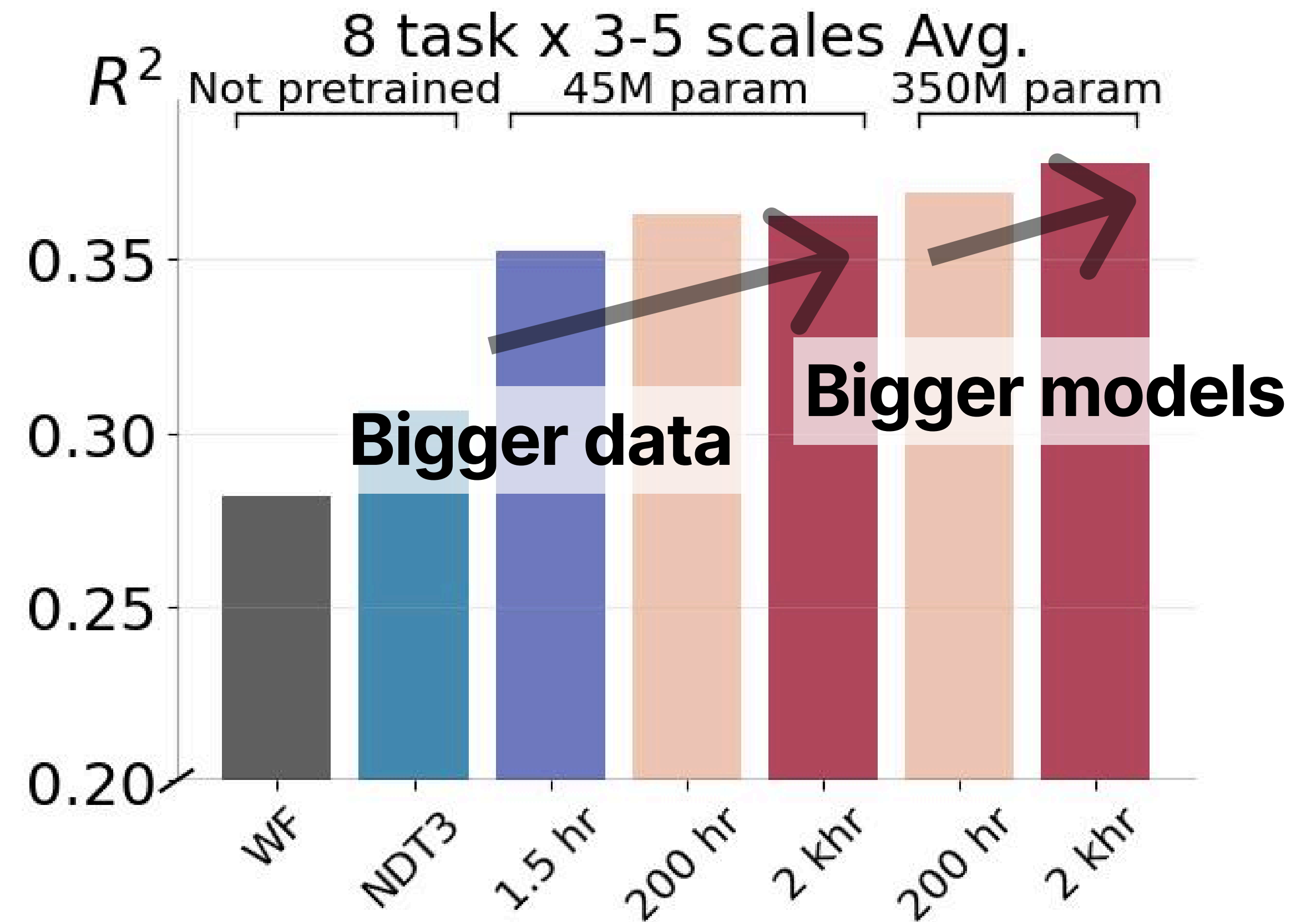
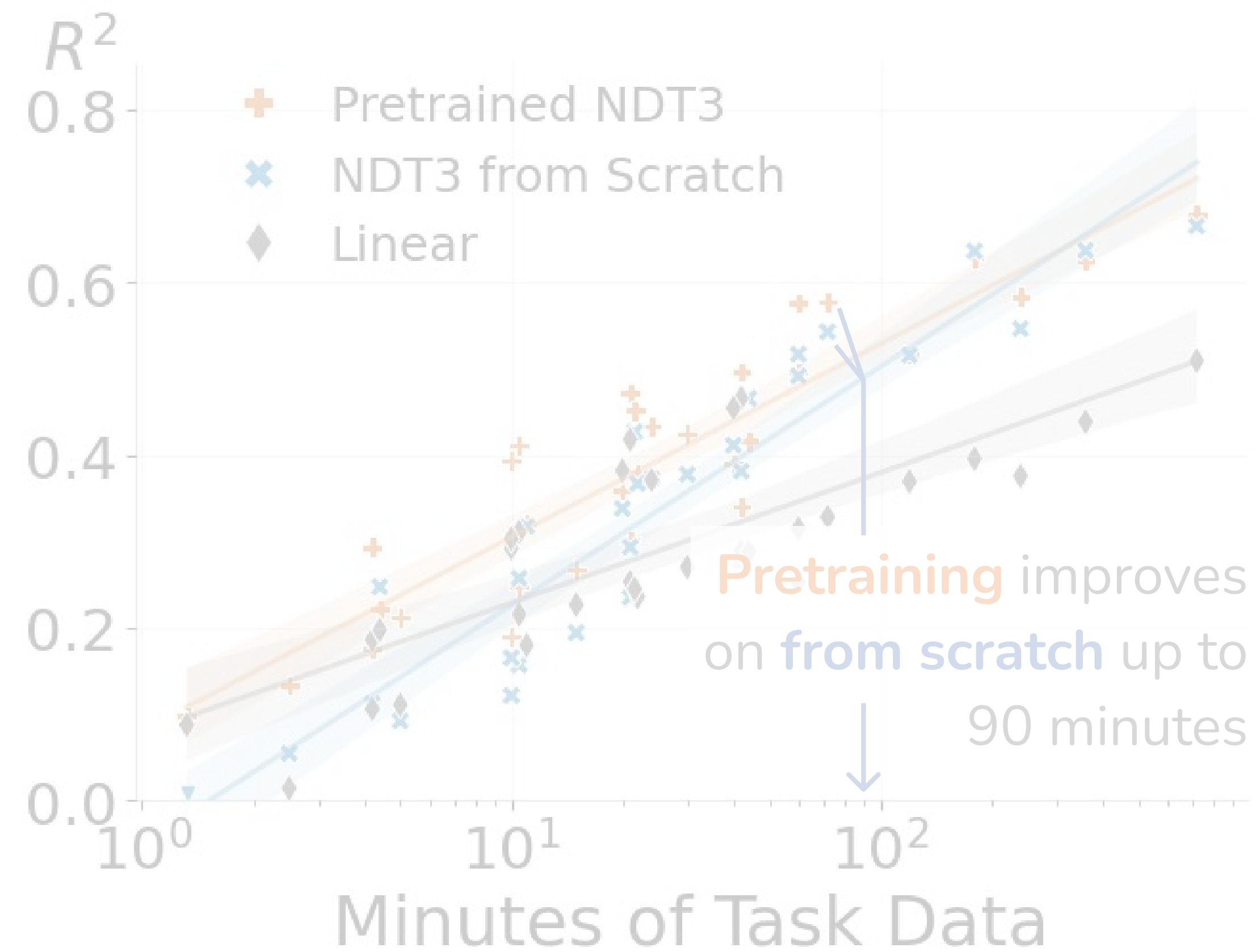


## Quantifying downstream scaling gains on 8 datasets

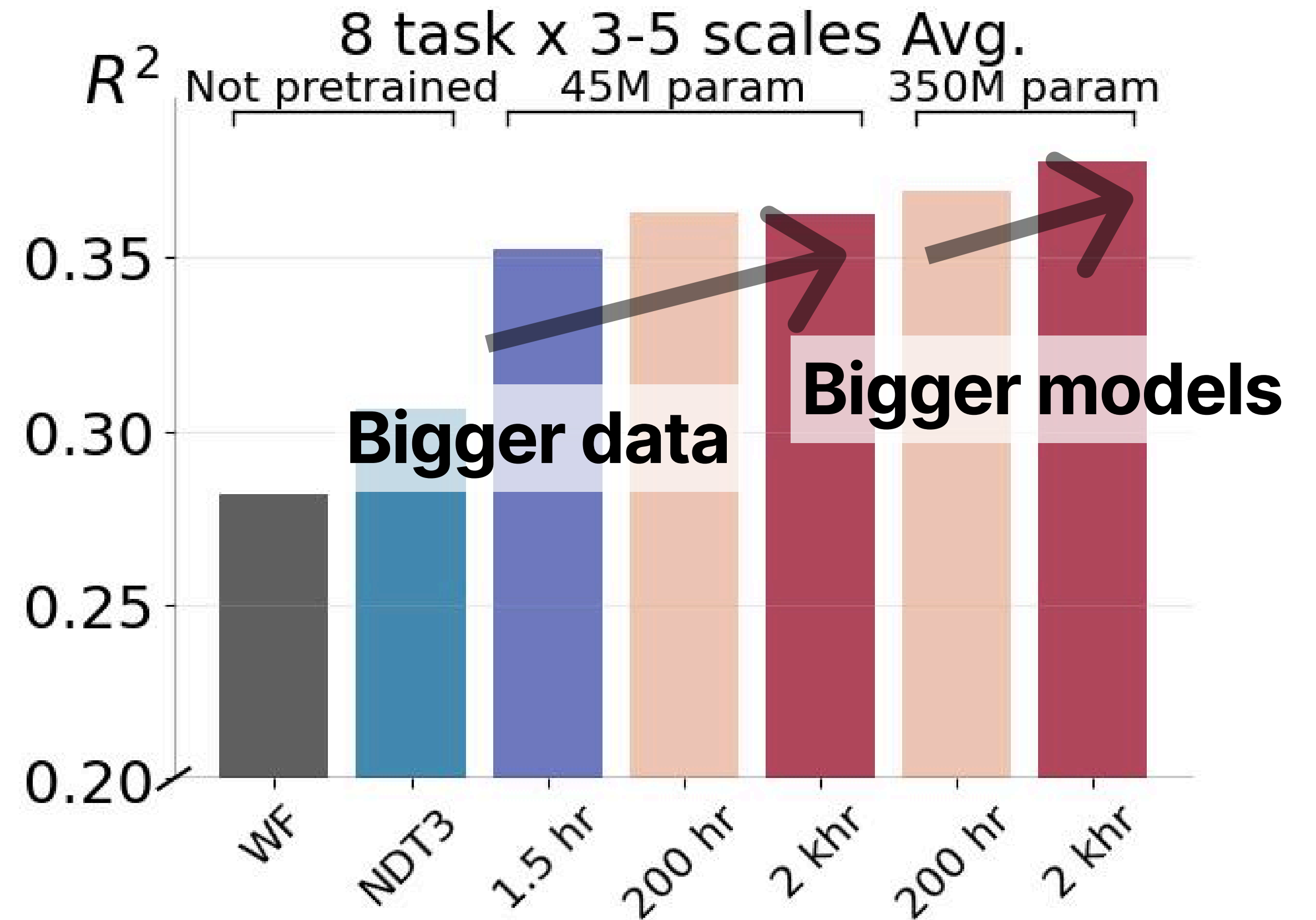
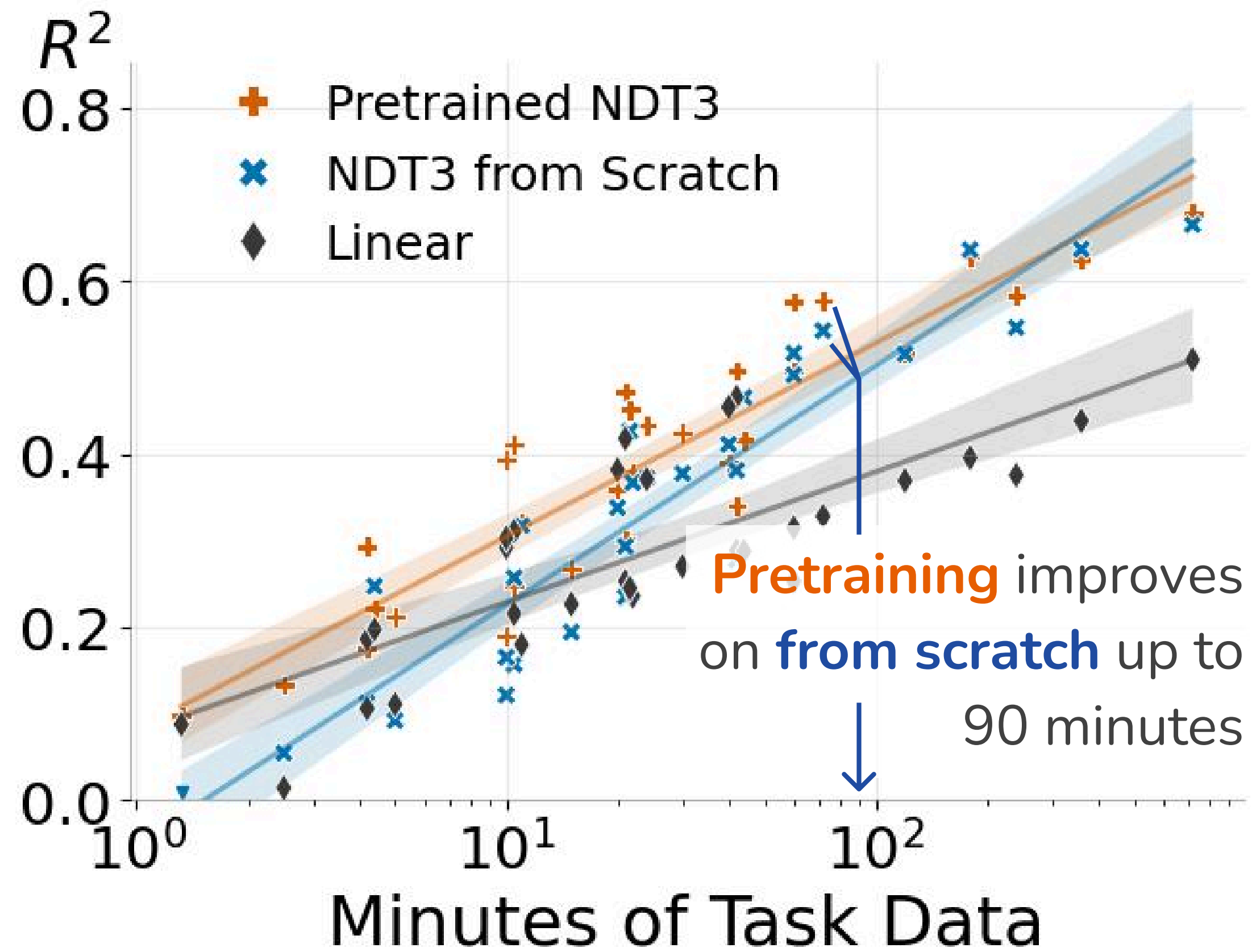


**Pretraining** improves  
on **from scratch** up to  
90 minutes

# Quantifying downstream scaling gains on 8 datasets



# NDT has modest practical value for BCI, and scaling likely won't change this.



**1. Evaluating\* for pragmatics (is hard)**

**2. Evaluating for generalization**

**Neural foundation models need evaluations to progress.**

1. Evaluating for pragmatics

2. Evaluating for generalization

**Pretrain** → **Tune A** → **Evaluate B**

- Ecological covariate shifts
- Angular attractors
- Cursor control

**Neural foundation models need evaluations to progress.**

Pretrain → Tune A → Evaluate B

**Ecological covariate shifts**

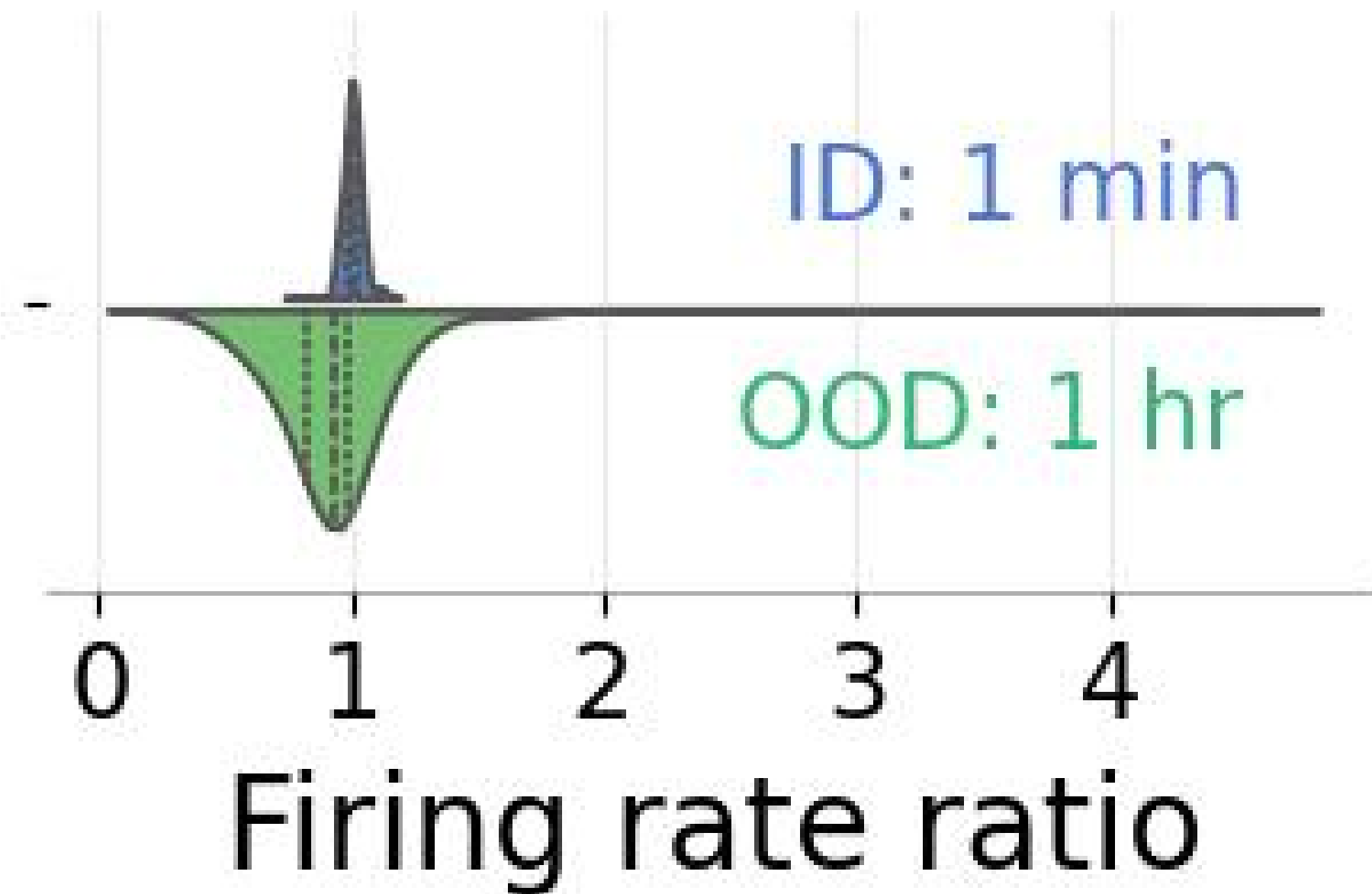
Shift: **Time**



Pretrain → Tune A → Evaluate B

## Ecological covariate shifts

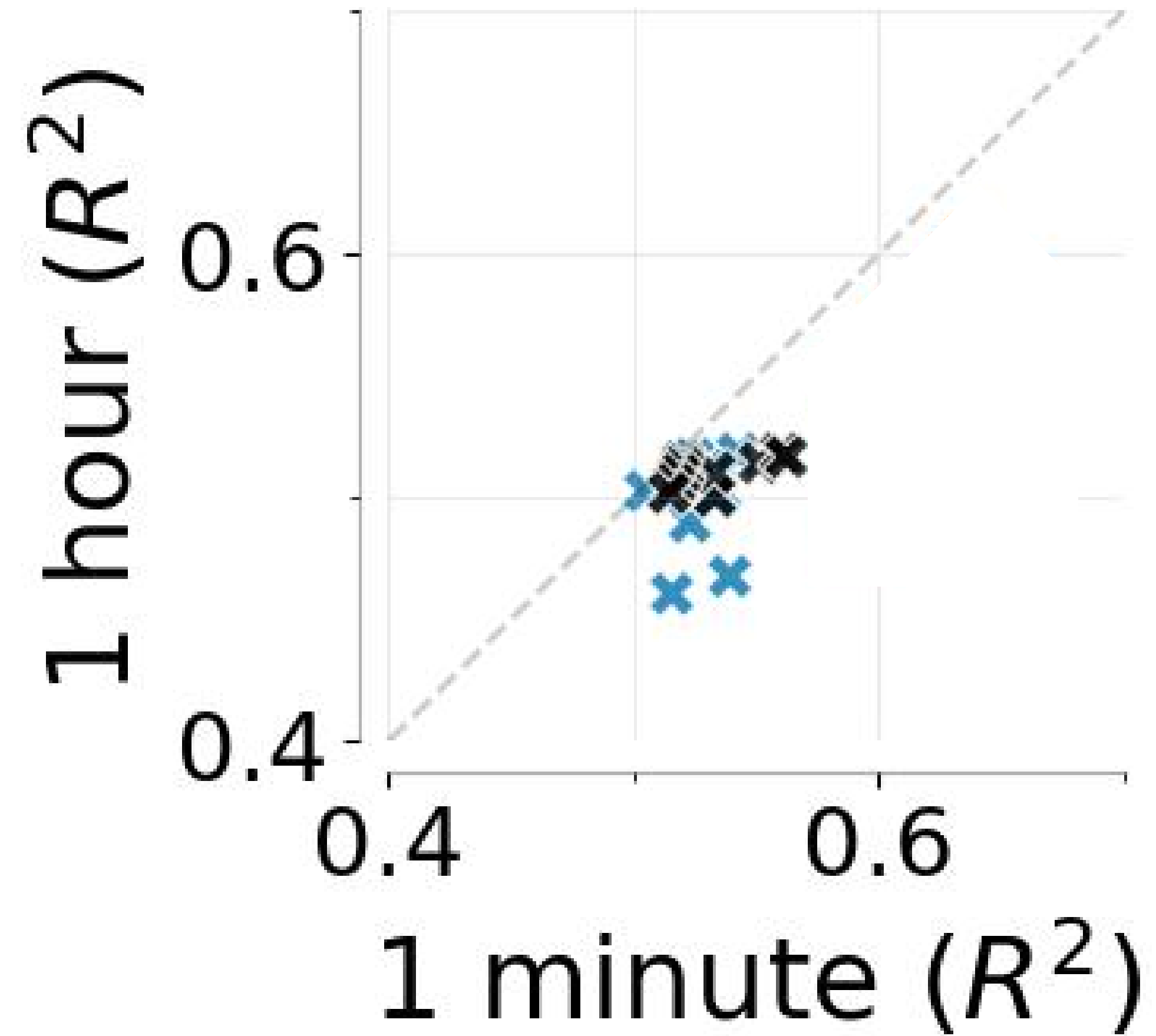
Shift: **Time**



1 minute      1 hour  
Tune ●—————|—————>

Pretrain → Tune A → Evaluate B

## Ecological covariate shifts

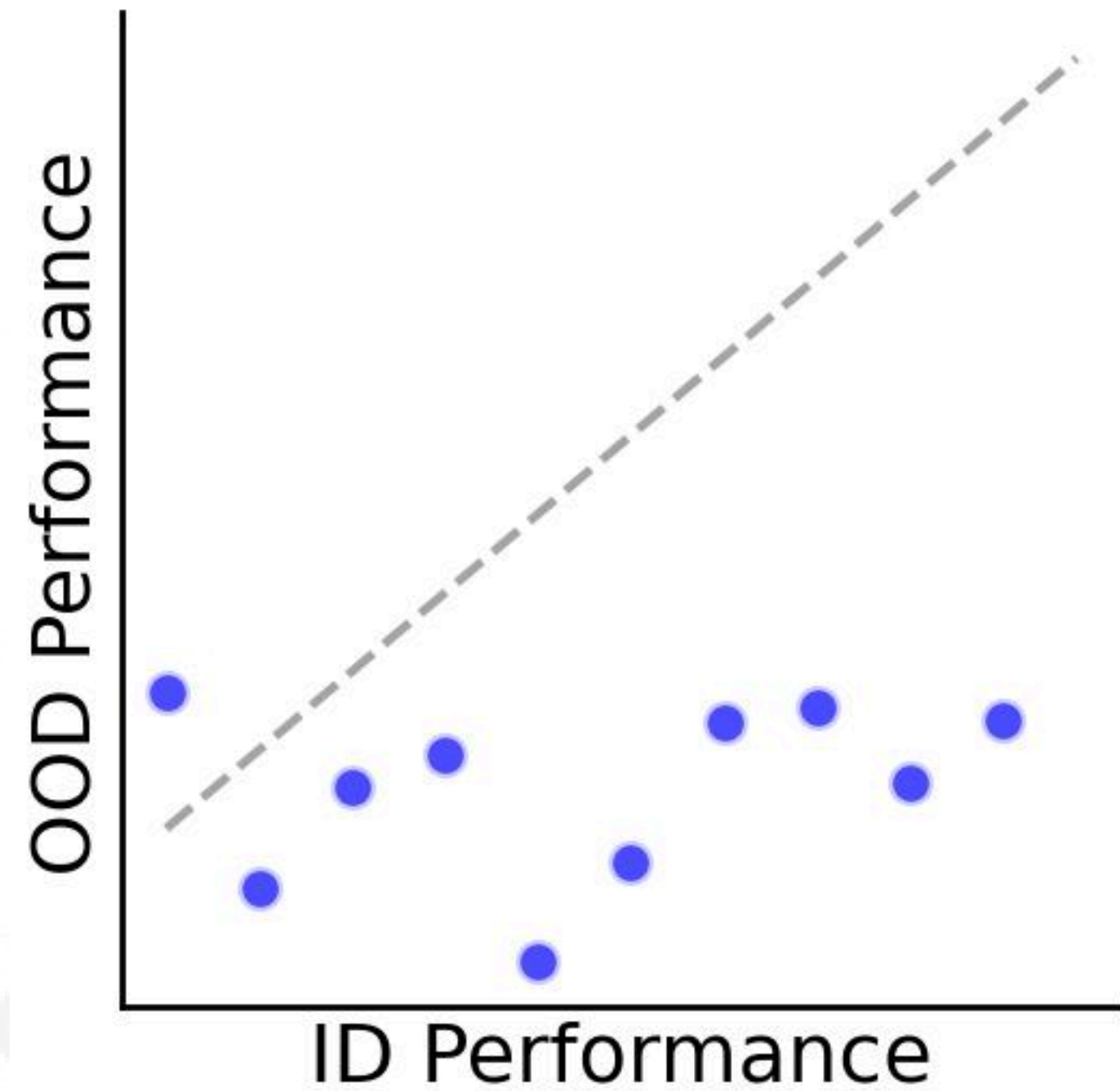


✘ Wiener Filter ✘ Scratch ● 200hr 45M + 2khr 350M

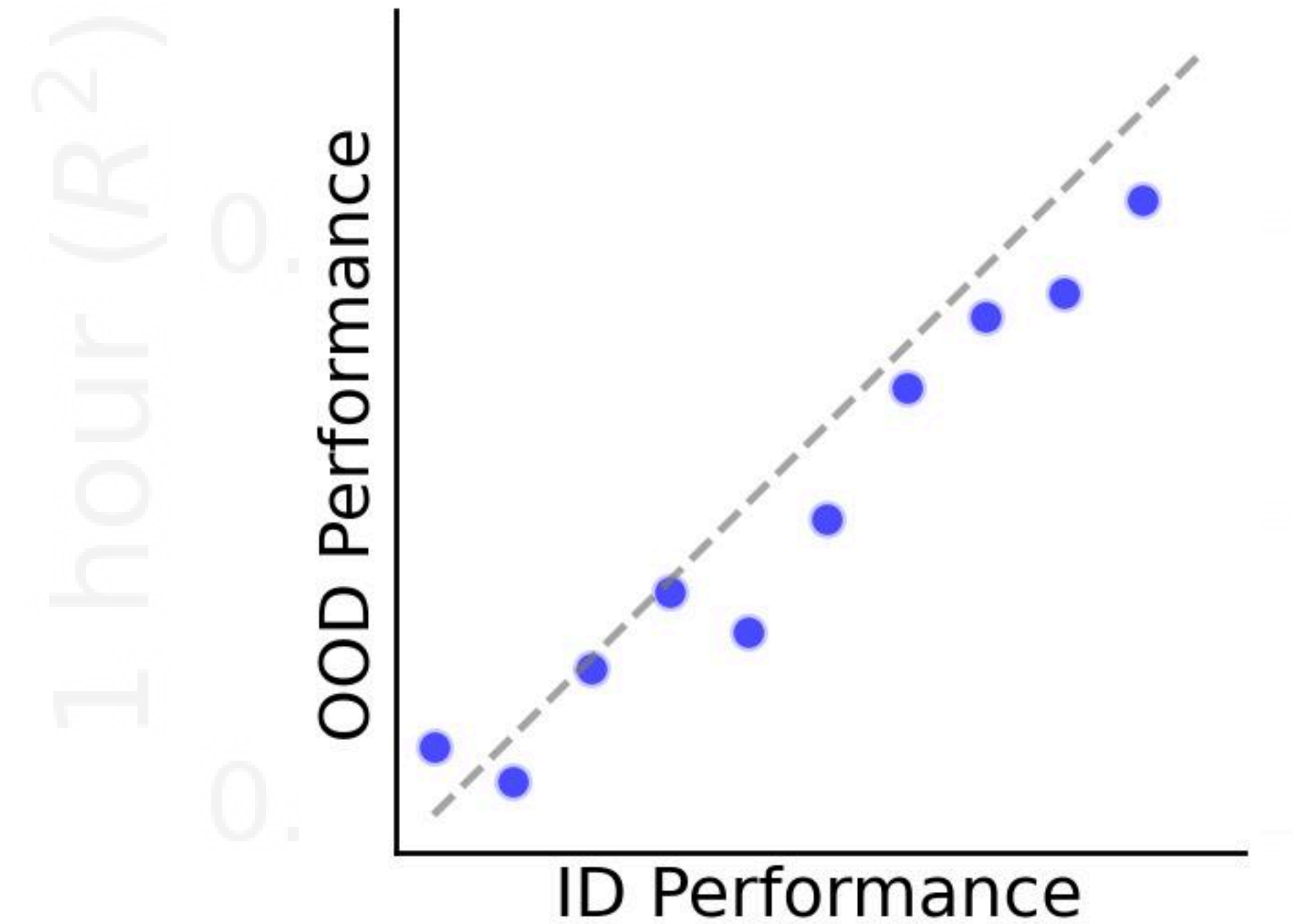


Pretrain → Tune A → Evaluate B

## Ecological covariate shifts



**Hypothesis 1: Fragile features**

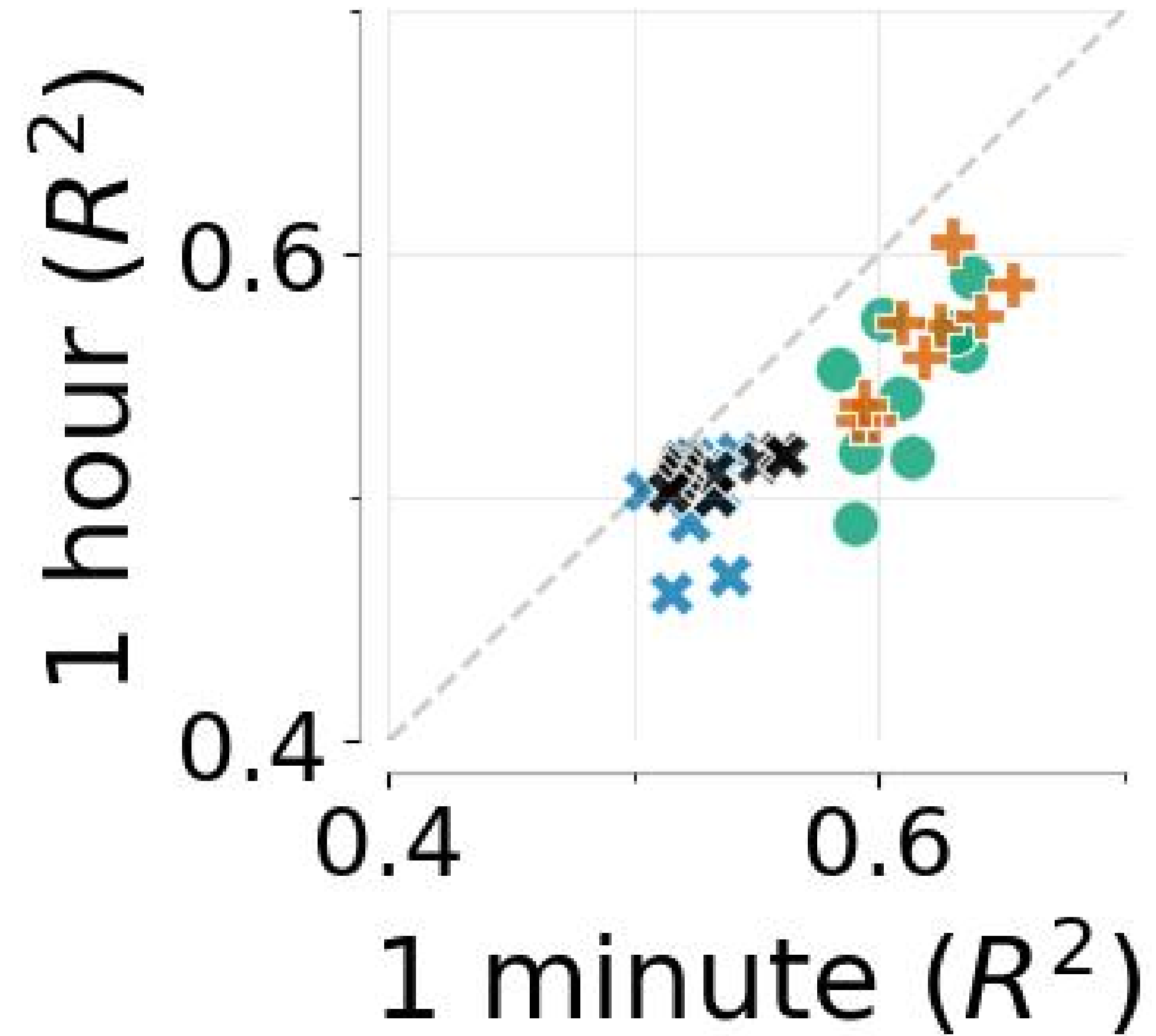
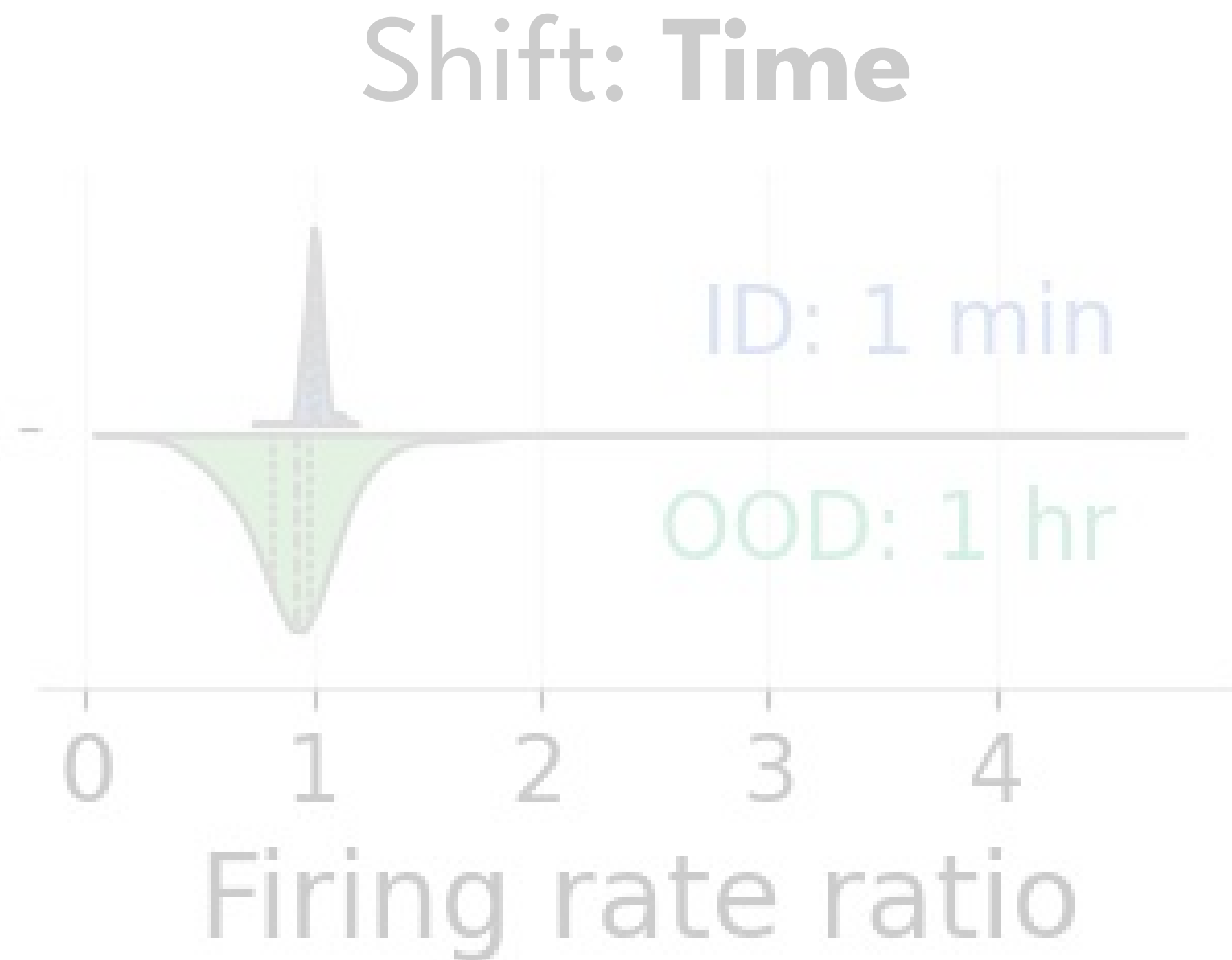


**Hypothesis 2: Robust gains**

✕ Wiener Filter ✕ Scratch ● 200hr 45M + 2khr 350M

Pretrain → Tune A → Evaluate B

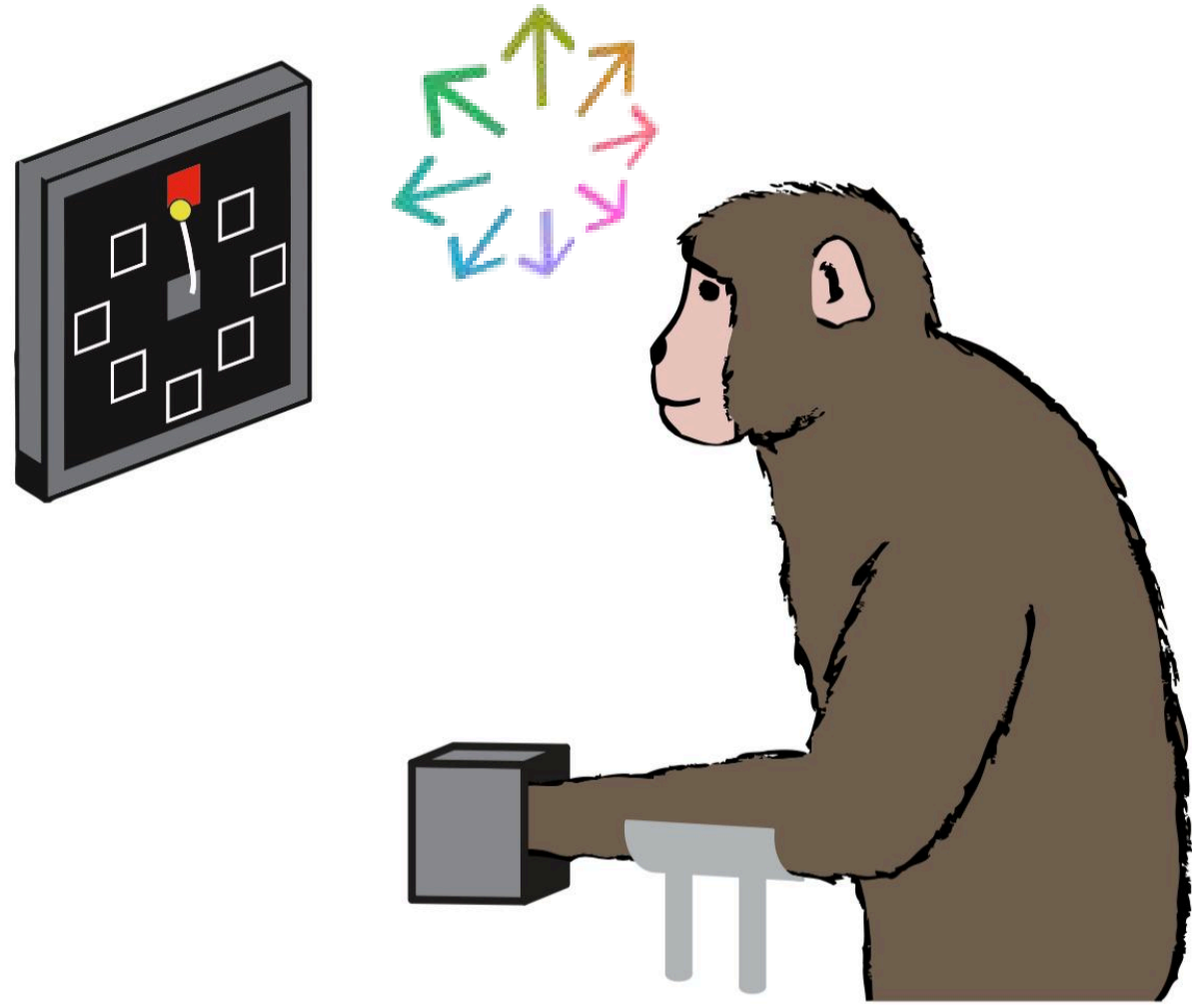
## Ecological covariate shifts



✘ Wiener Filter ✘ Scratch ● 200hr 45M + 2khr 350M

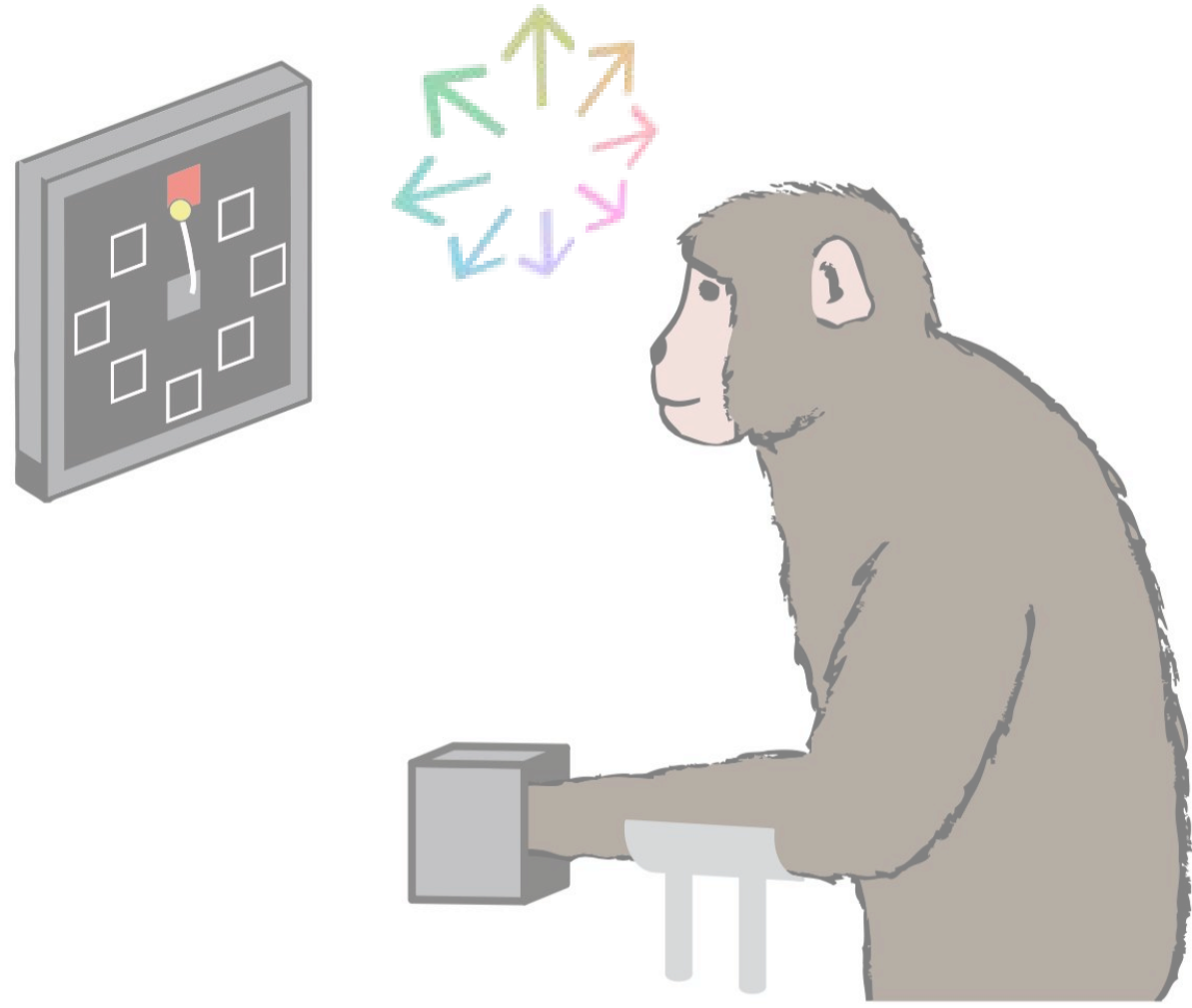
Pretrain → Tune A → Evaluate B

## Angular attractors: Probing for “qualitative priors”

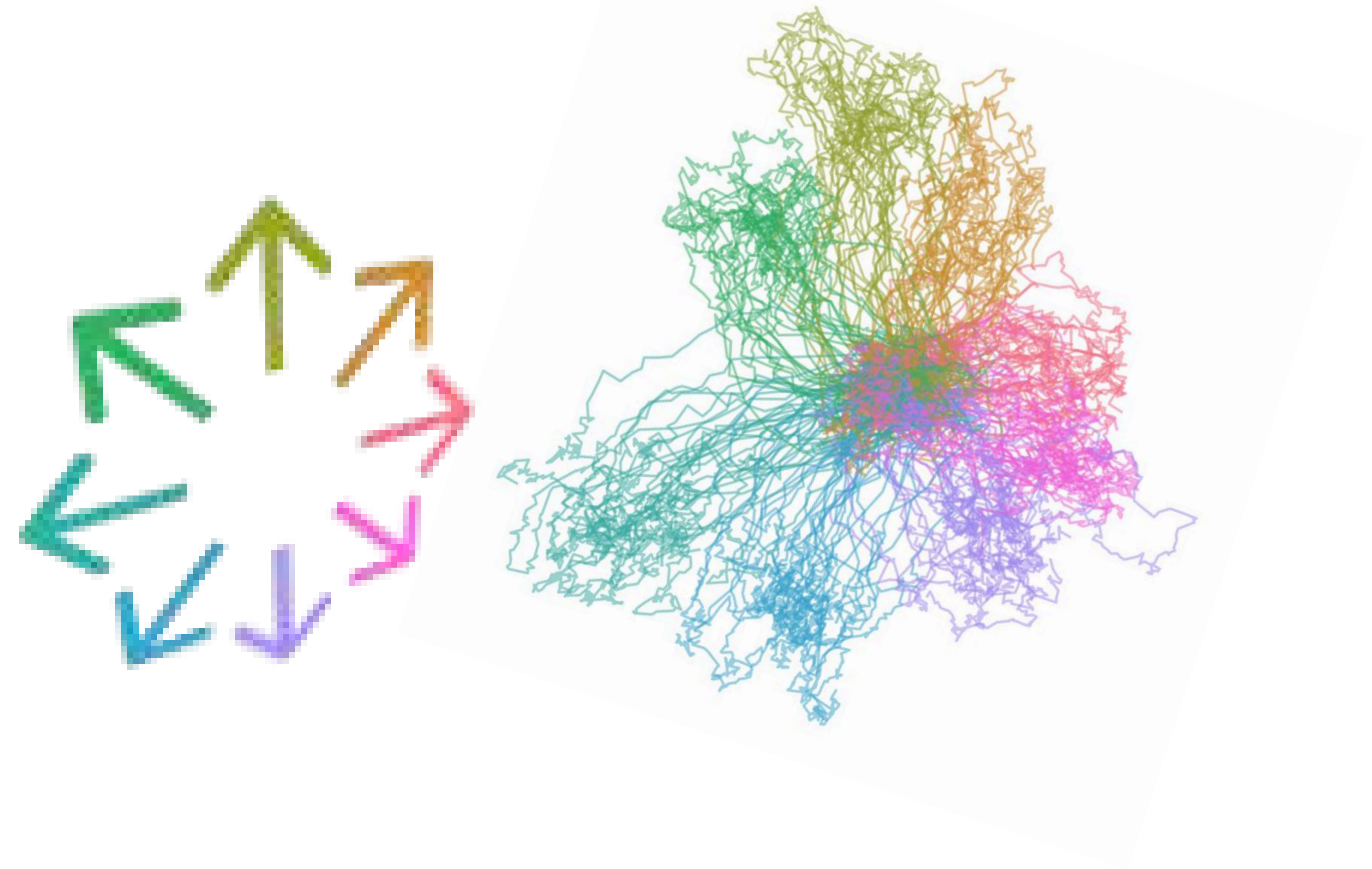


Pretrain → Tune A → Evaluate B

## Angular attractors



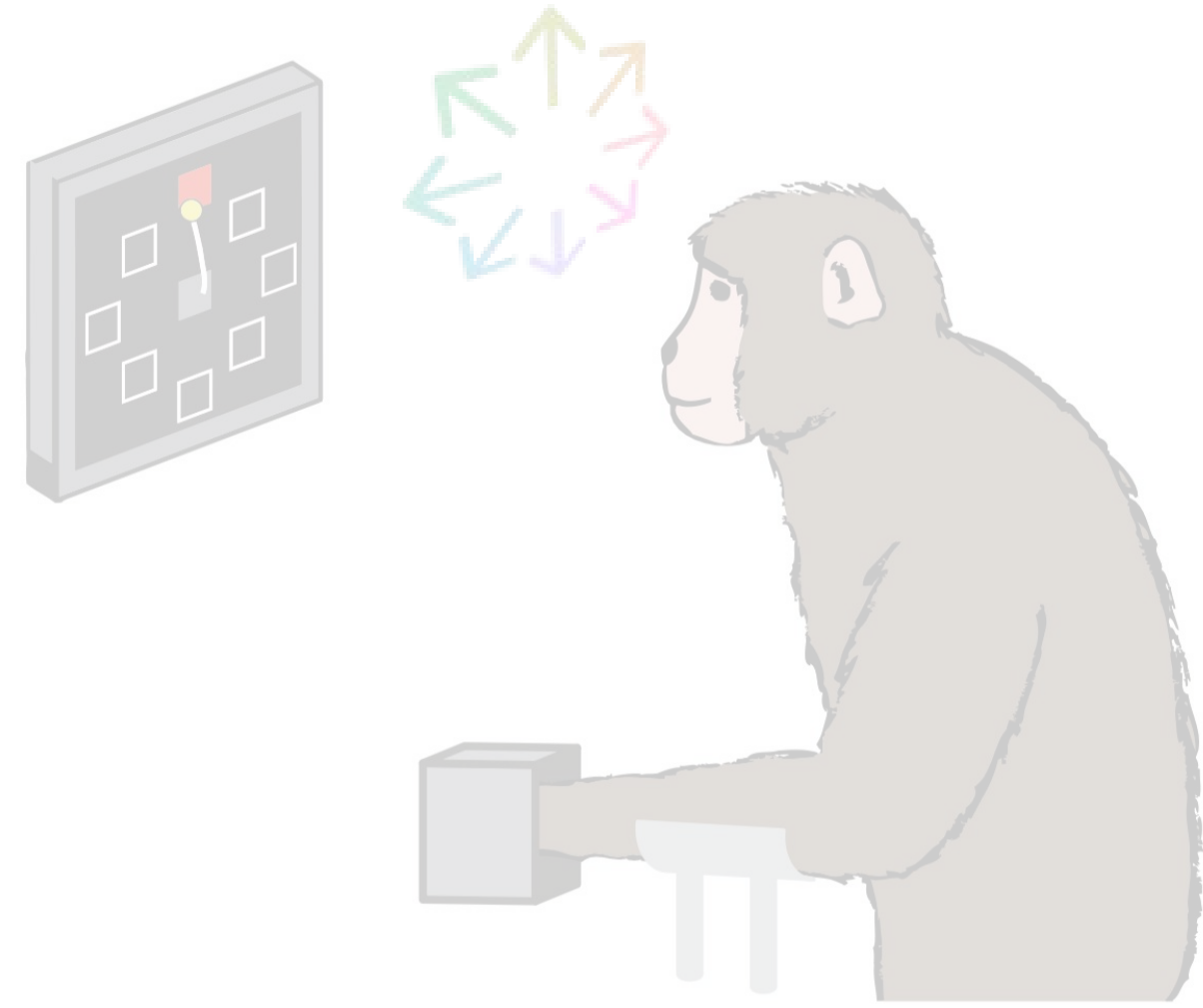
## PCA + LDA Trajectories





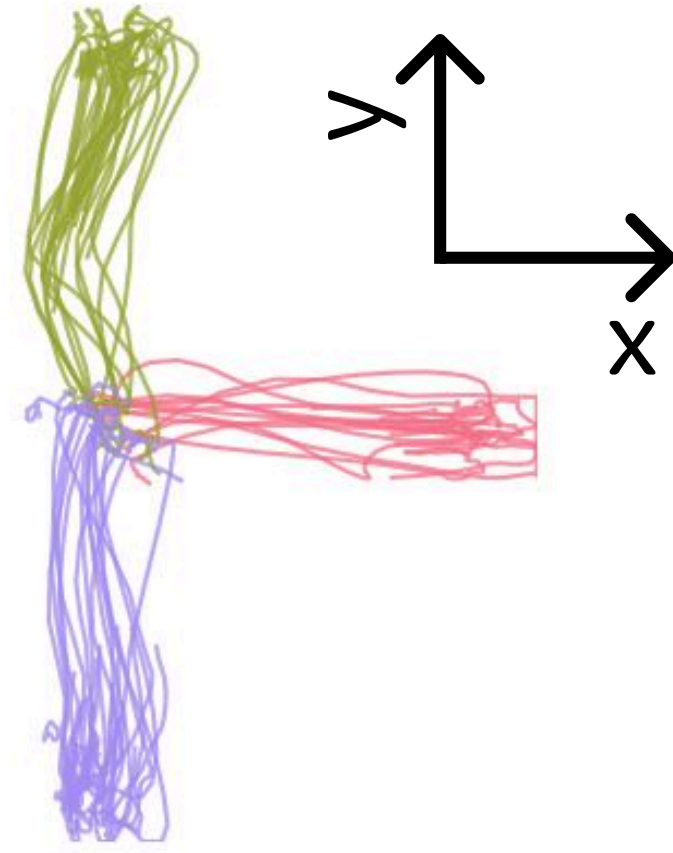
Pretrain → Tune A → Evaluate B

# Angular attractors

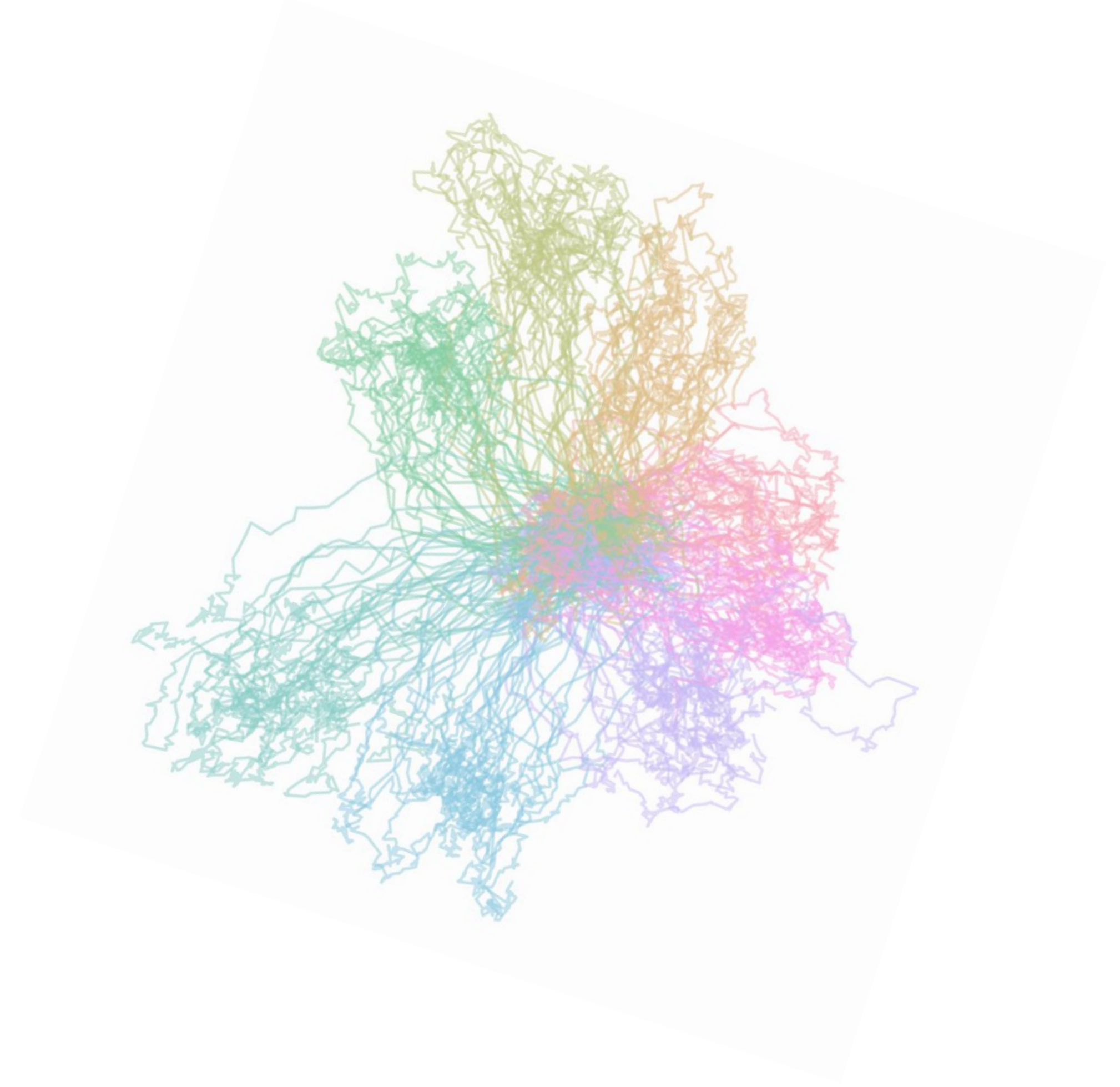


Behavior

Train angles



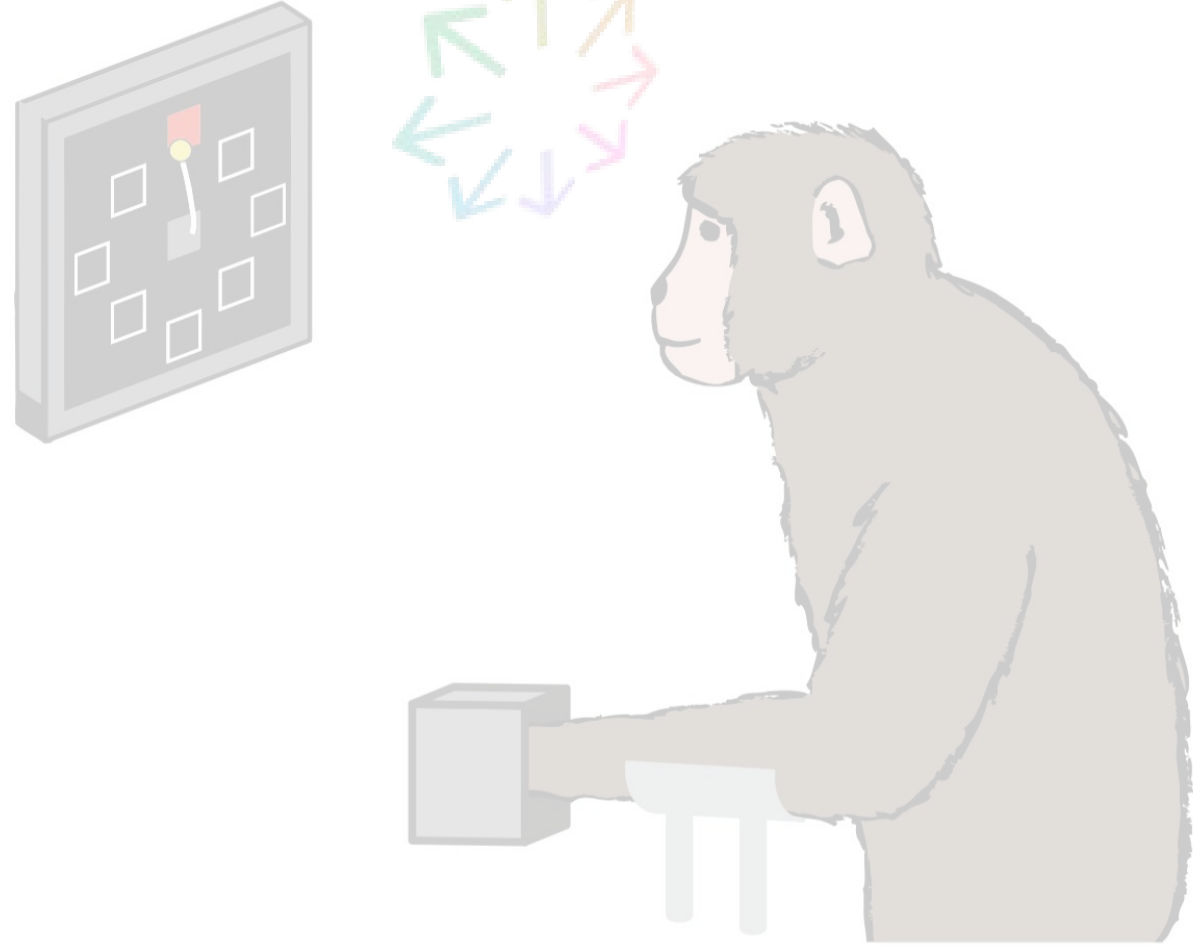
Test angles





Pretrain → Tune A → Evaluate B

# Angular attractors

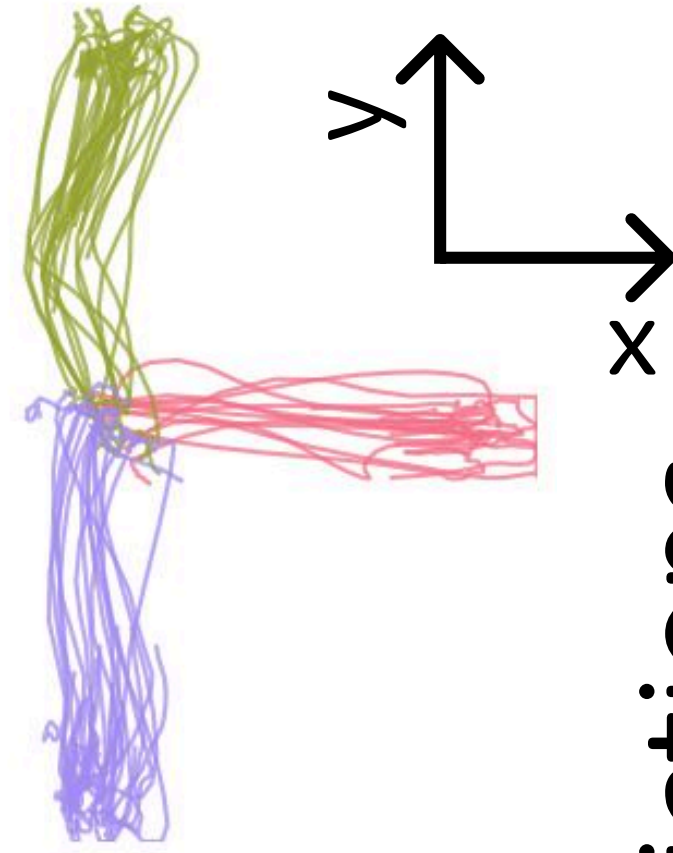


Train angles

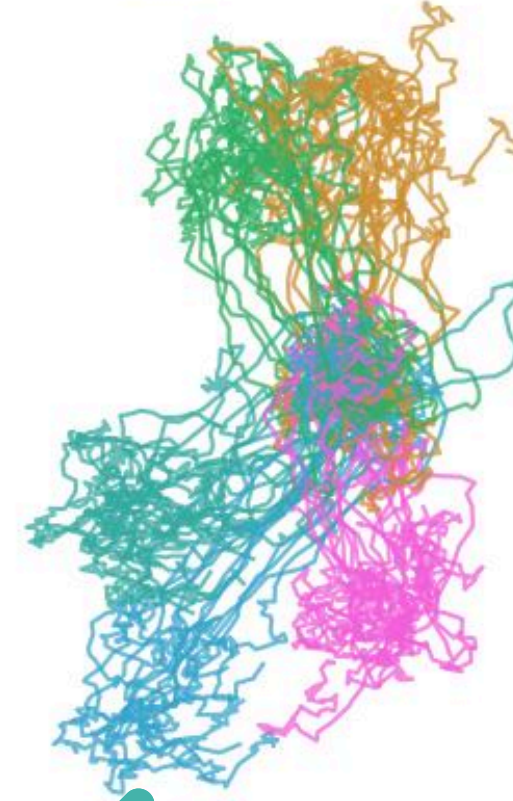
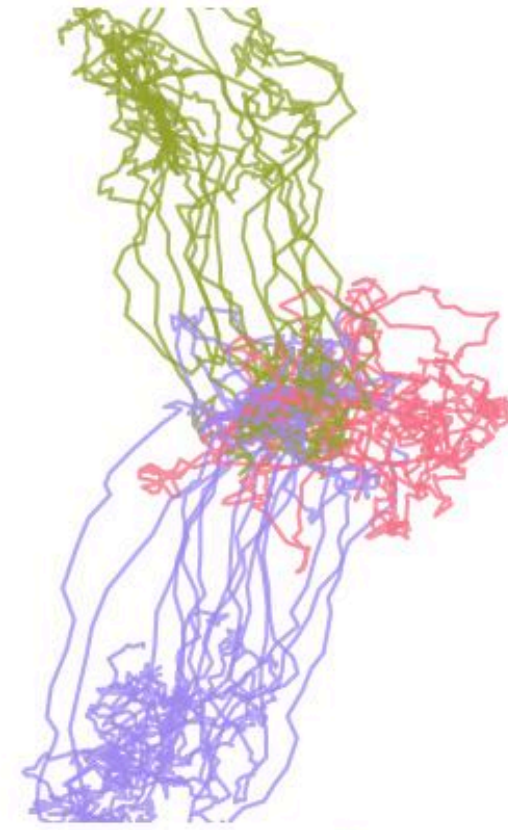
Test angles

Behavior

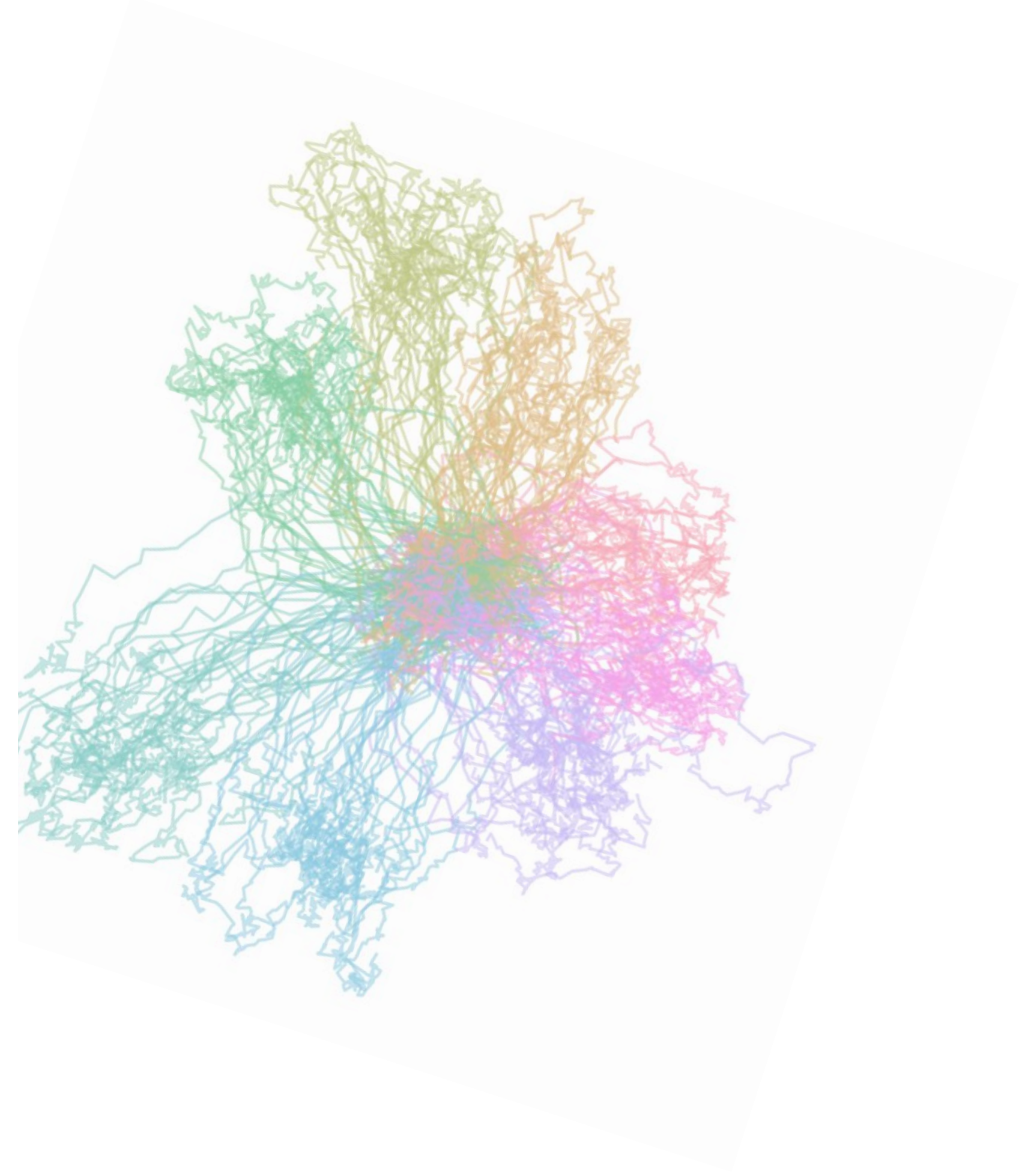
Linear  
(PCA-LDA)



Predictions



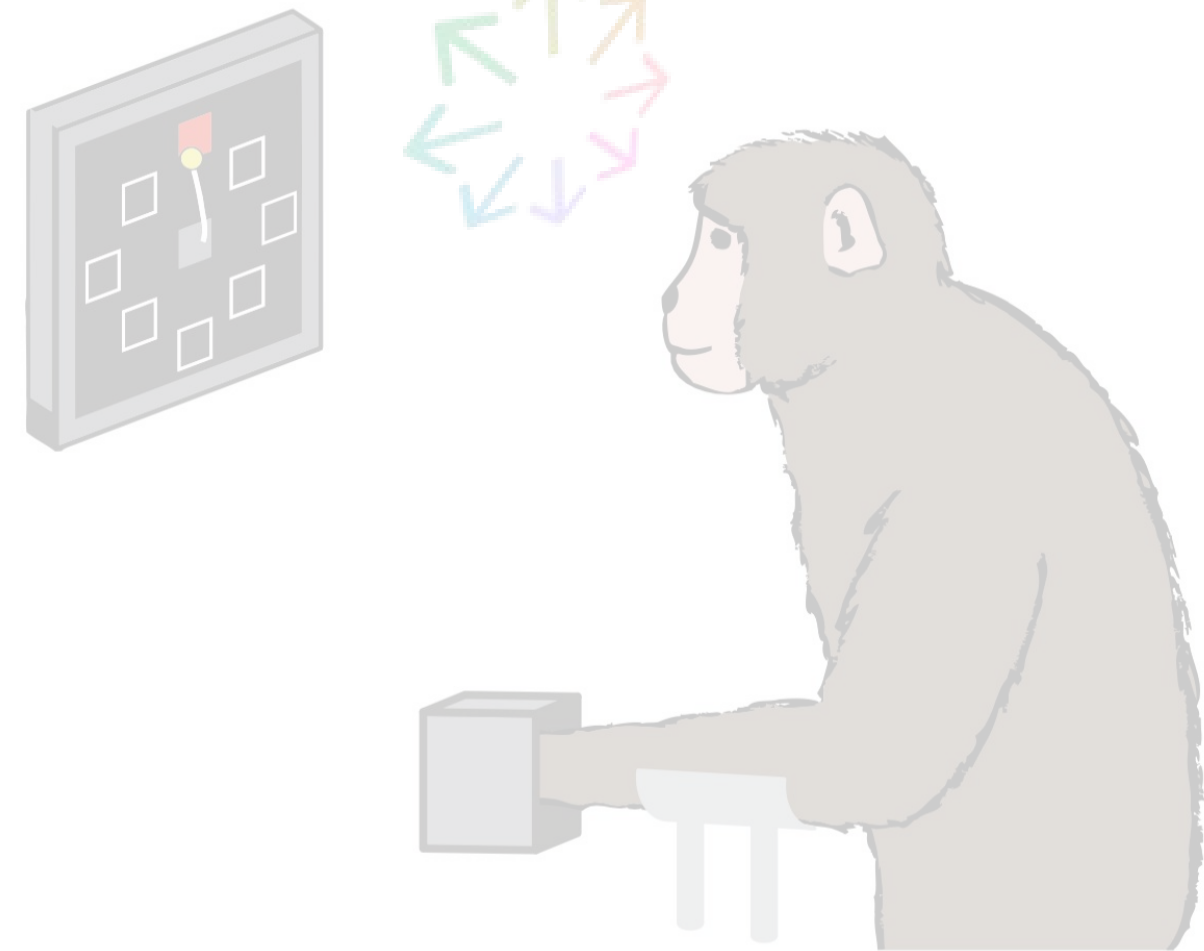
Generalization





Pretrain → Tune A → Evaluate B

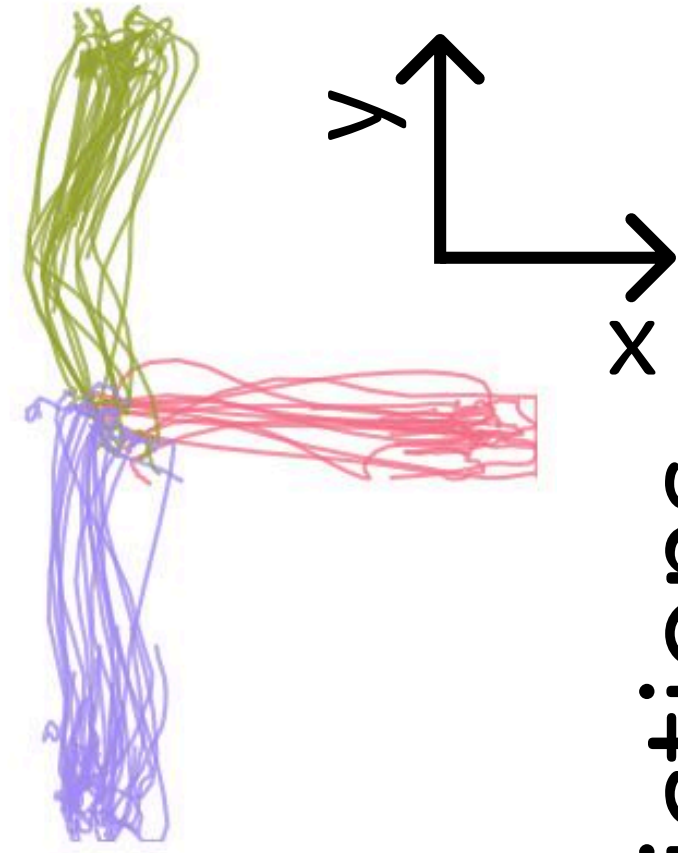
# Angular attractors



Train angles

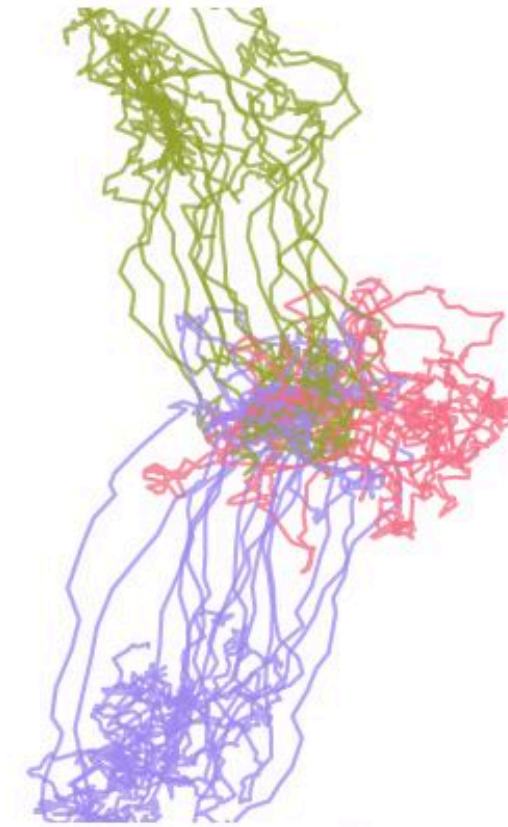
Test angles

Behavior

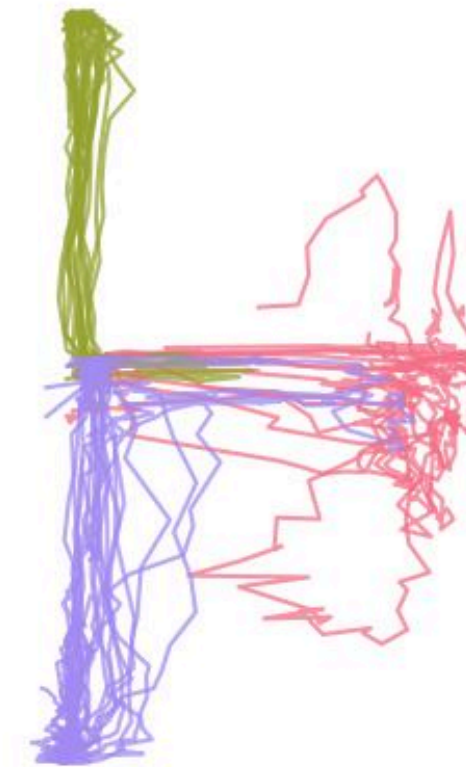


Predictions

Linear (PCA-LDA)



NDT3 Scratch



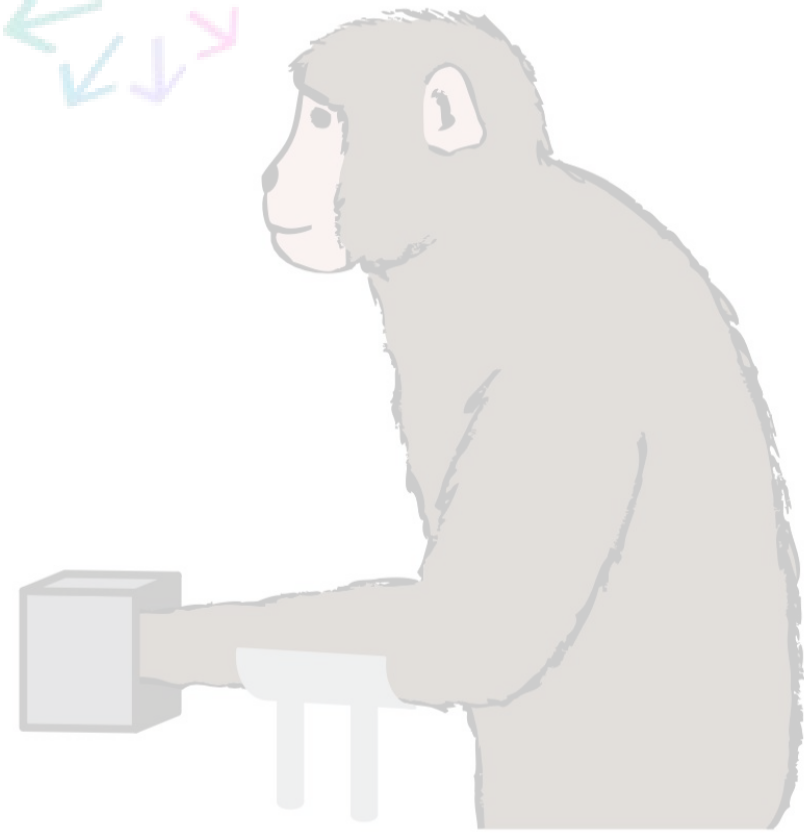
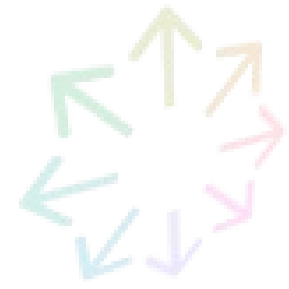
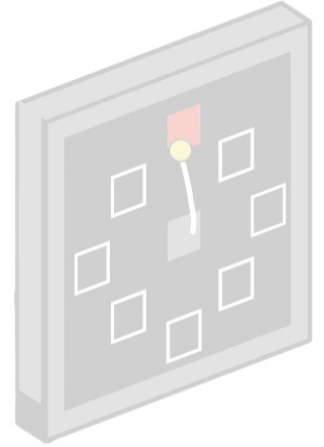
Generalization





Pretrain → Tune A → Evaluate B

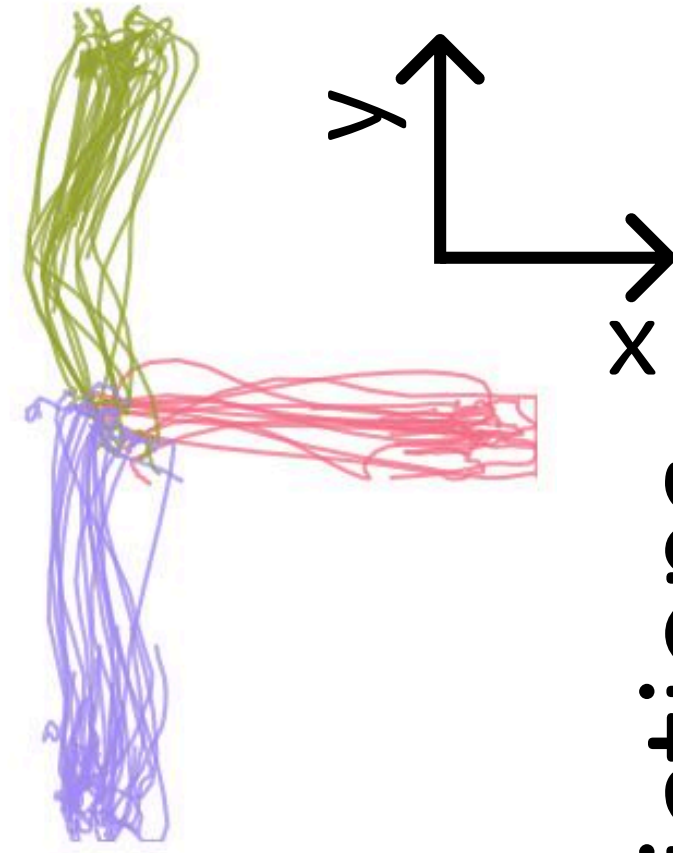
# Angular attractors



Train angles

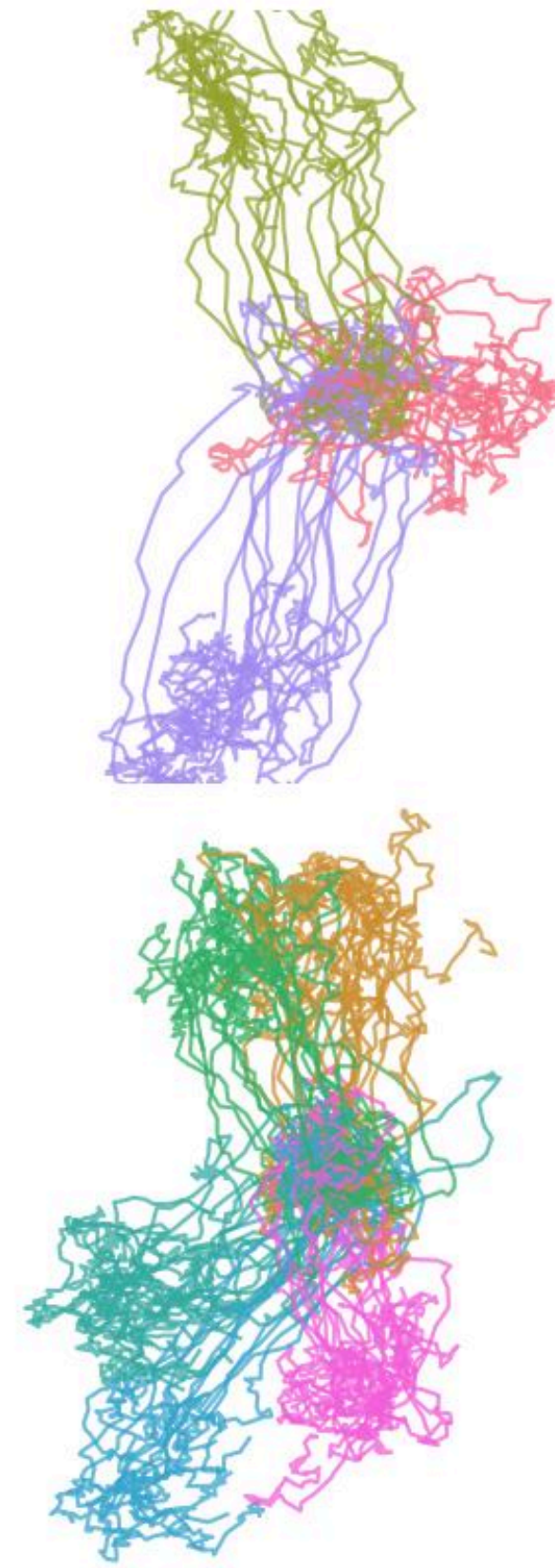
Test angles

Behavior

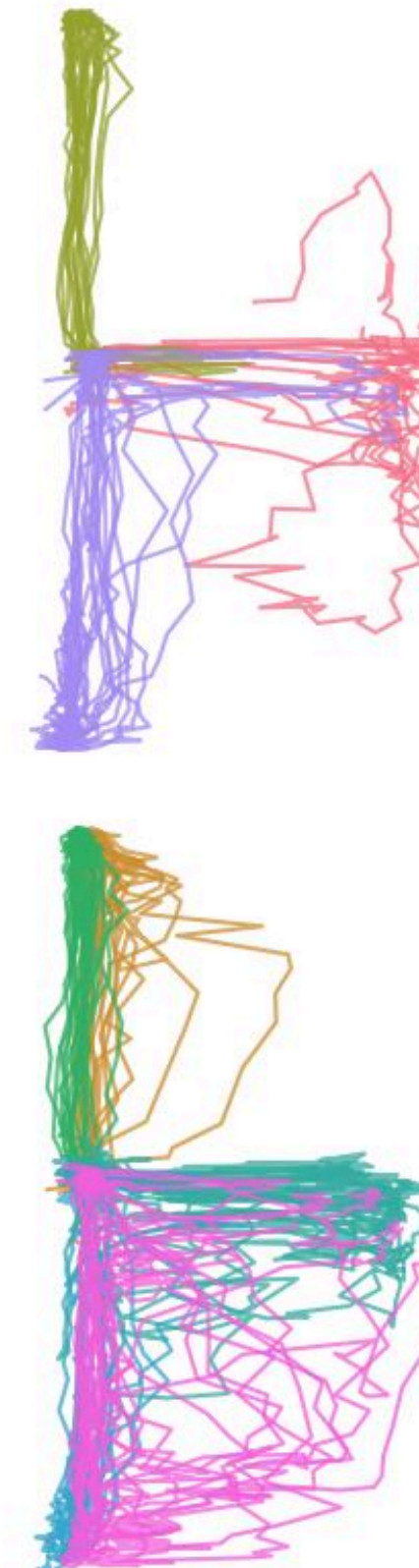


Predictions

Linear  
(PCA-LDA)



NDT3  
Scratch



NDT3  
350M 2 khr





Pretrain → Tune A → Evaluate B

## Angular attractors

- Either:
  - Model has failed to learn prior
  - Fine-tuning alone **fails to surface** priors (Post-training?)



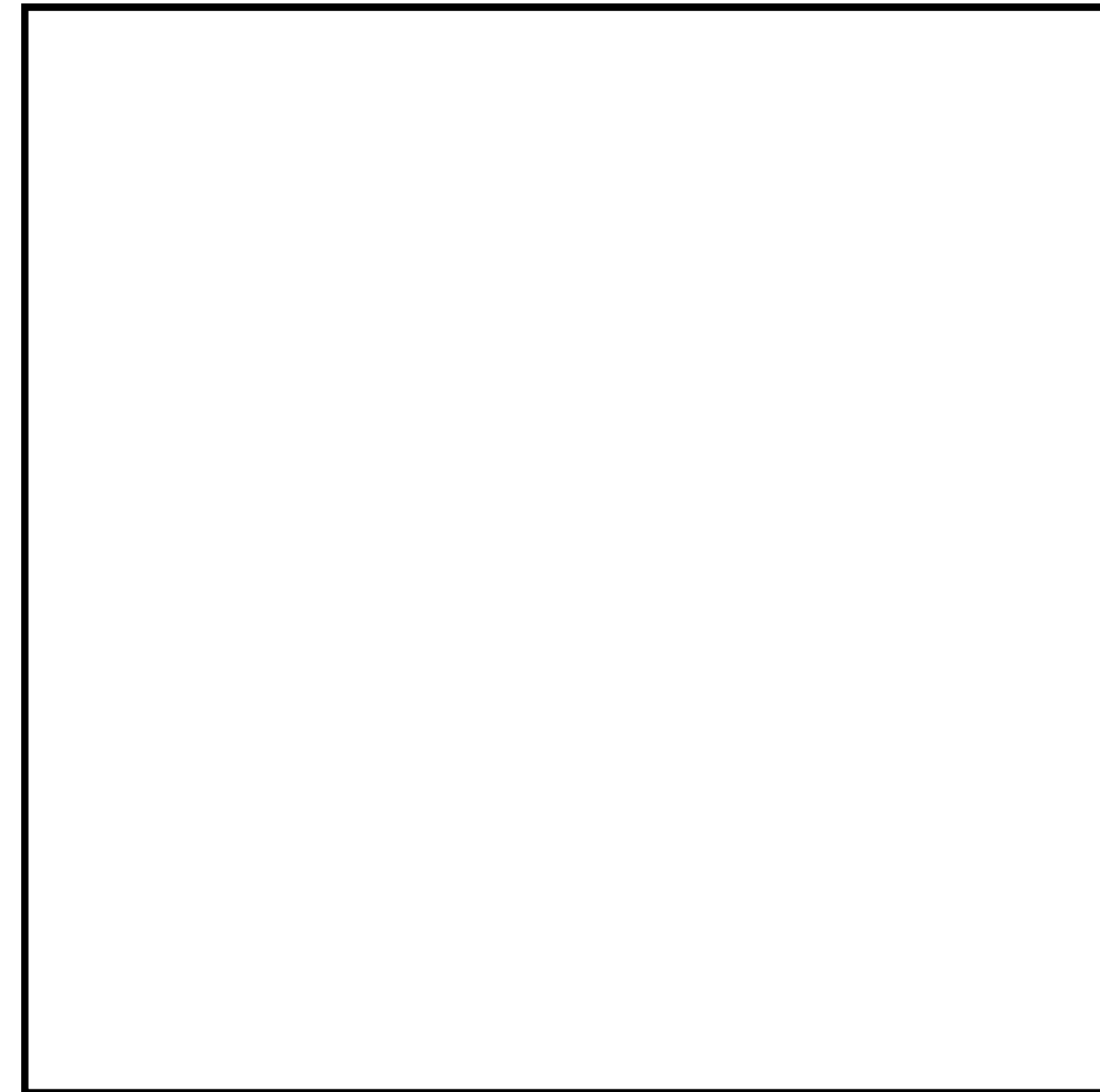
**Pretrain** → **Tune A** → **Evaluate B**

**Cursor control**

**Tune A**

**Evaluate B (Control)**

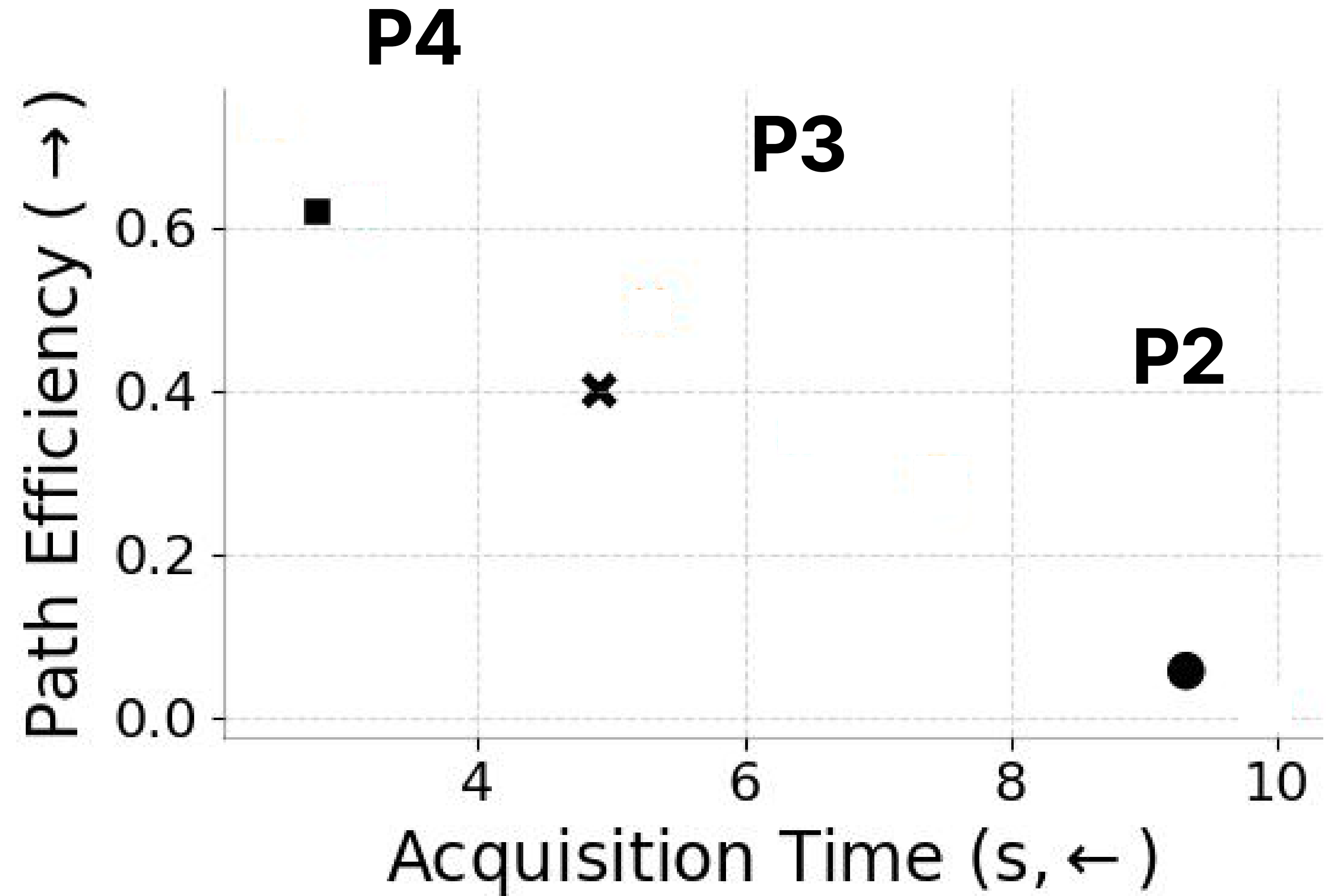
**Open loop calibration  
(~1 minute)**



Pretrain → Tune A → Evaluate B

Cursor control

Linear (iOLE)



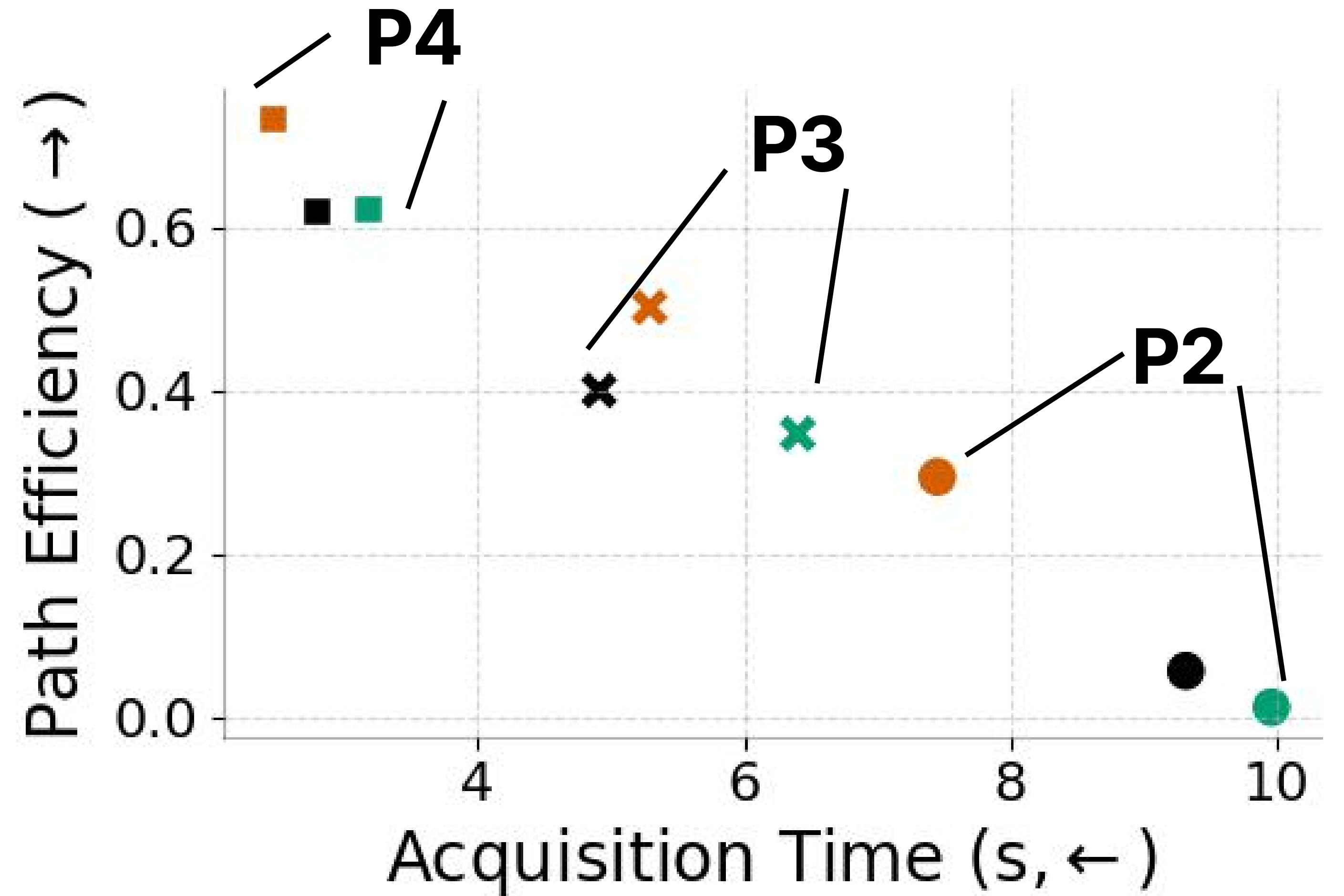
Pretrain → Tune A → Evaluate B

## Cursor control

Linear (iOLE)

NDT Base (200hr 45M)

NDT Big (2khr 350M)



**Evaluation will drive progress in neural foundation models.**

**Pragmatics**

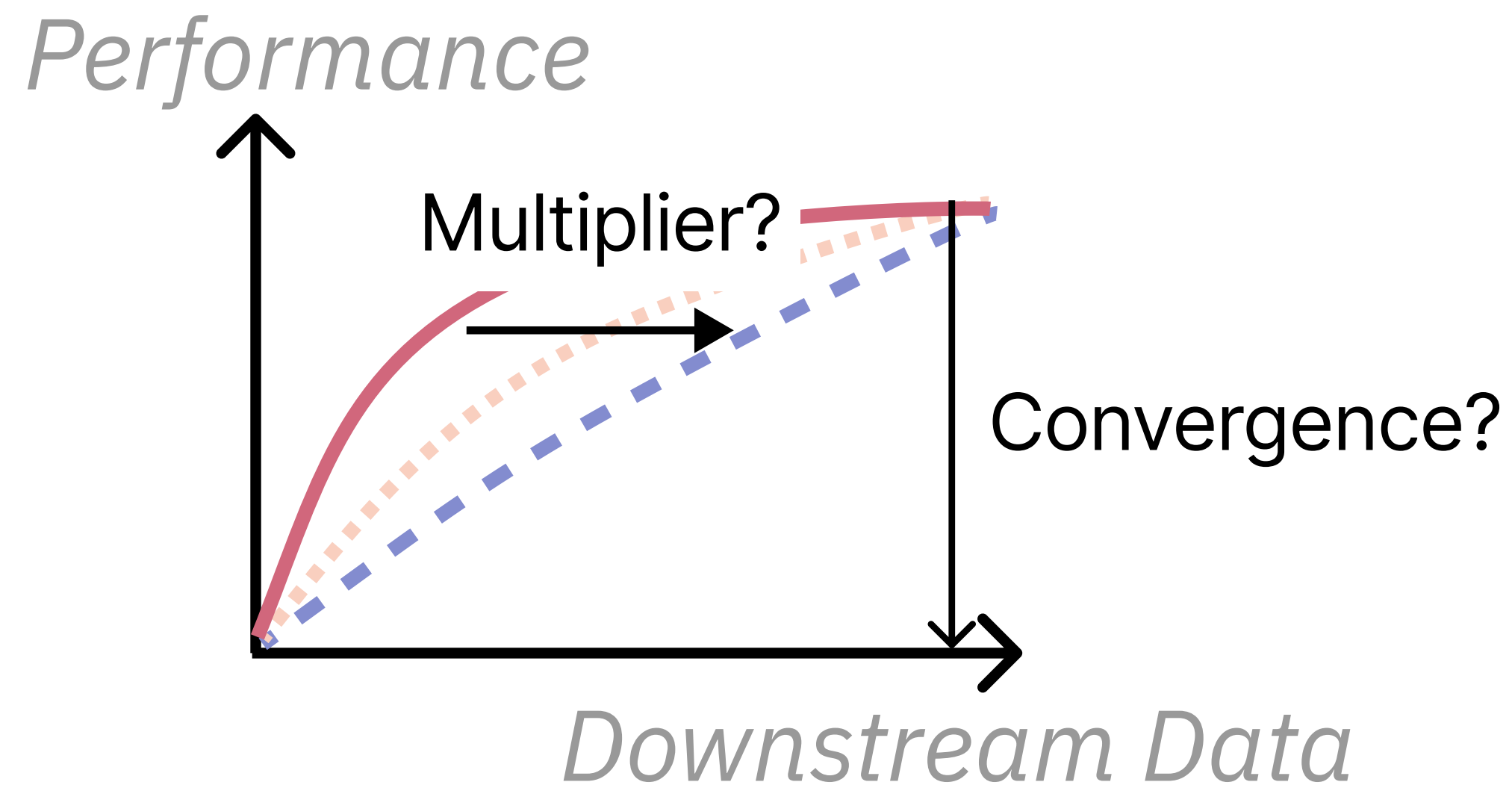
**Generalization**

**Evaluation will drive progress in neural foundation models.**

## **Pragmatics**

- Pretraining gain should be measured over realistic ranges

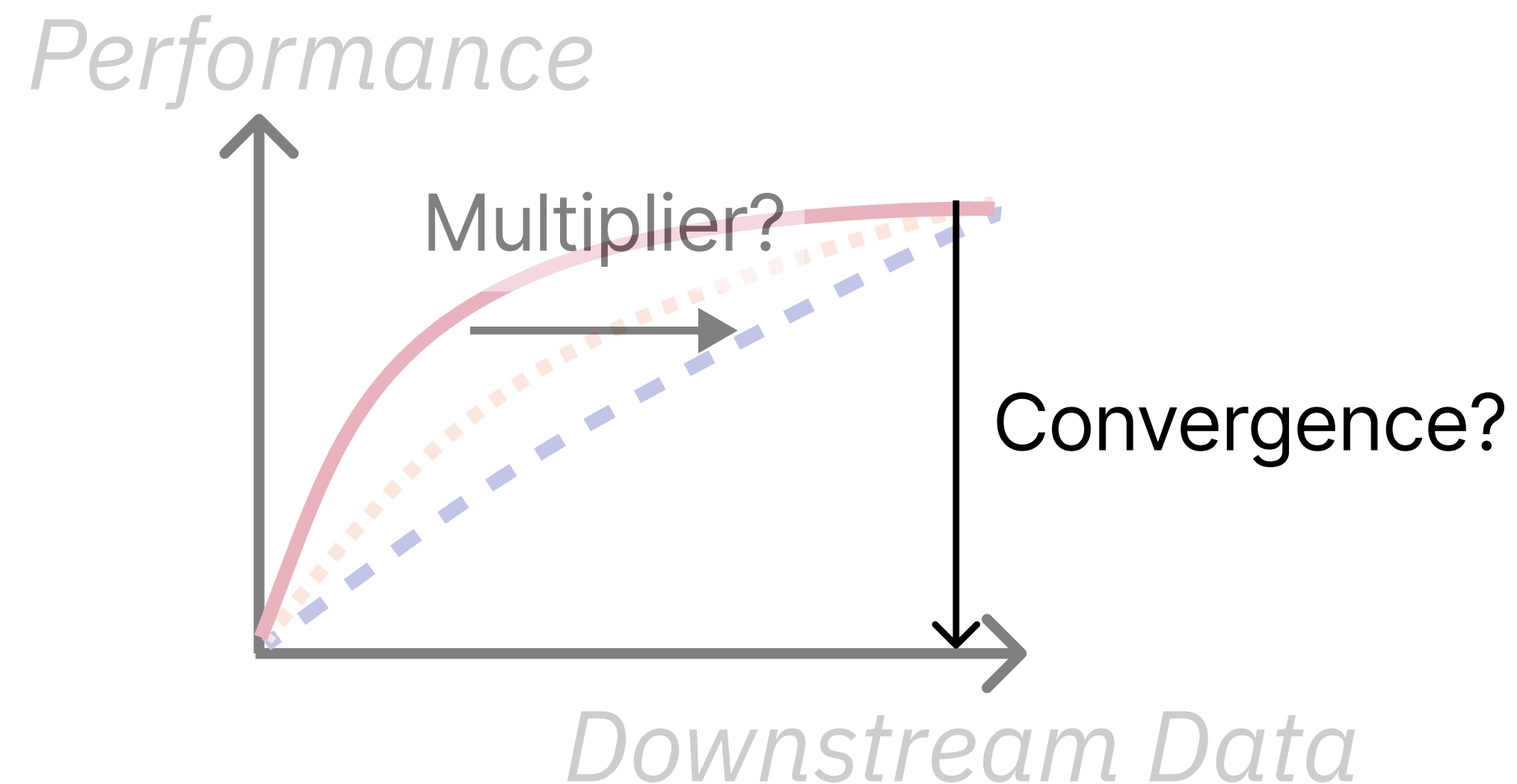
## **Generalization**



# Evaluation will drive progress in neural foundation models.

## Pragmatics

- Pretraining gain should be measured over realistic ranges



## Generalization

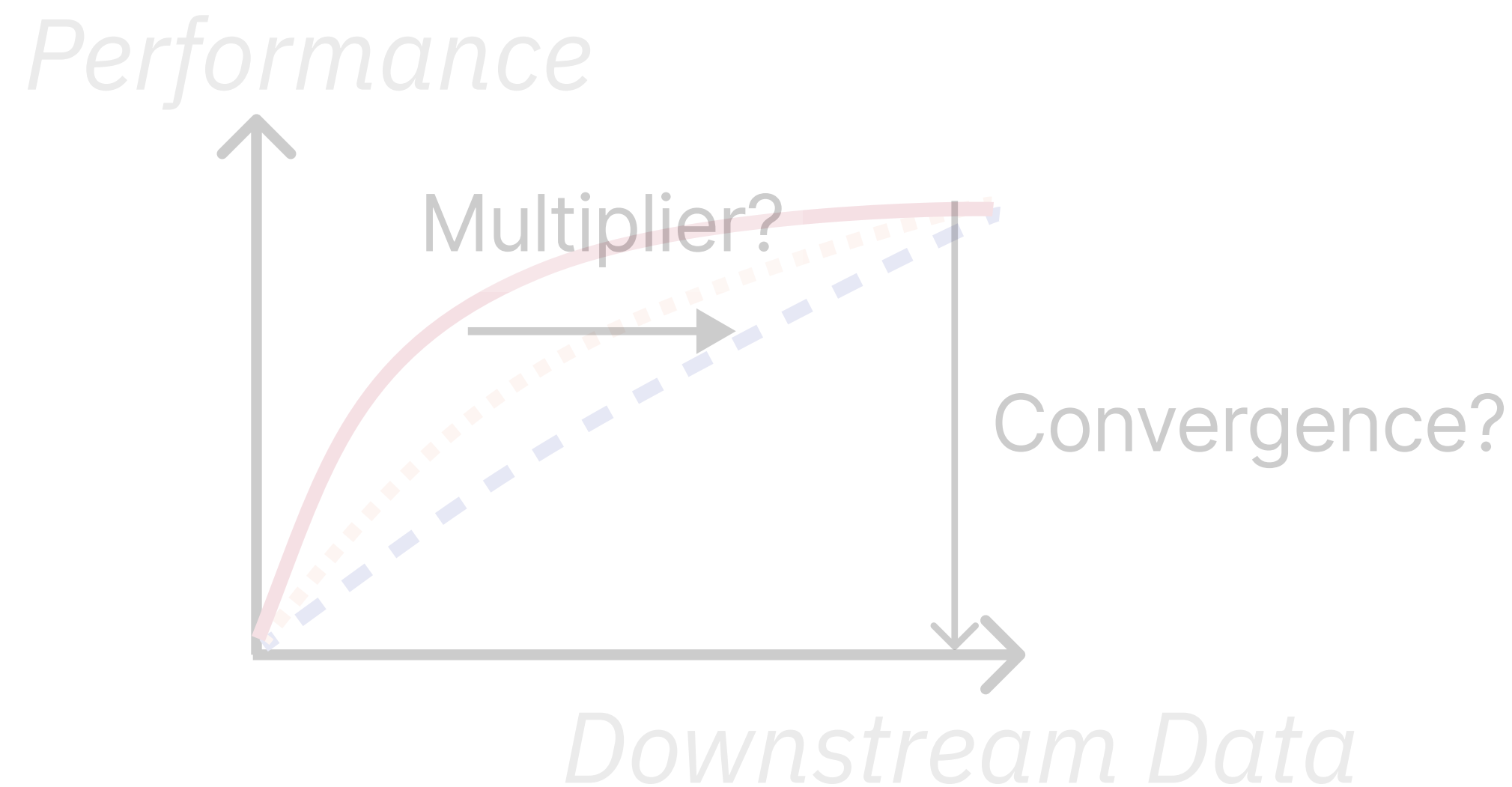
- Downstream often needs generalization
- Targeted probes can surface challenges that scaling will not resolve.

**Pretrain** → **Tune A** → **Evaluate B**

Pragmatics

Generalization

**Evaluations define progress in neural foundation models.**



resolve.

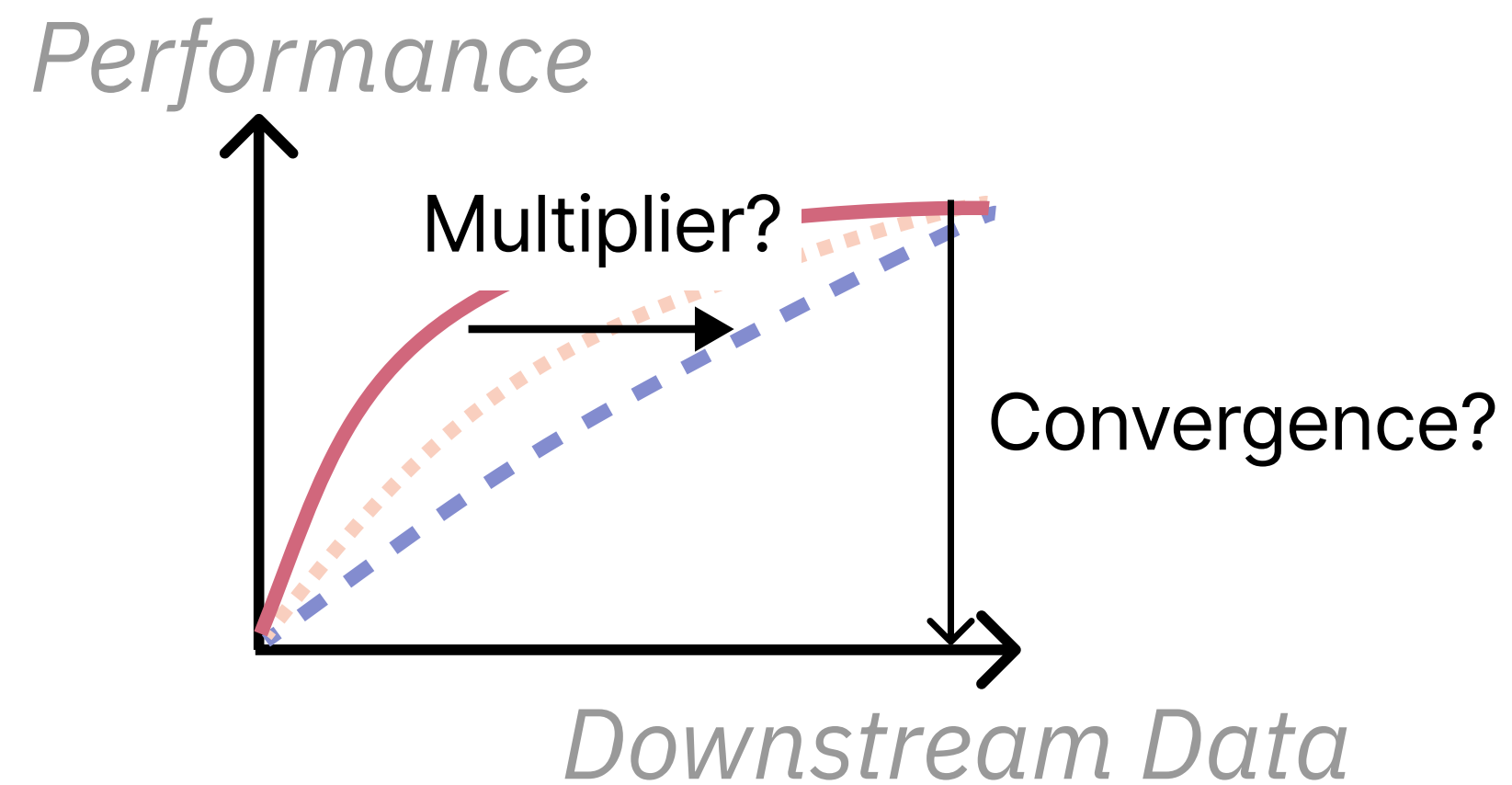
Pretrain → Tune A → Evaluate B



# Evaluation will drive progress in neural foundation models.

## Pragmatics

- Pretraining gain should be measured over realistic ranges



## Generalization

- Downstream will need generalization
- Targeted probes can surface challenges that scaling will not resolve.

**Pretrain** → **Tune A** → **Evaluate B**